

Rewriting History in Integrable Stochastic Particle Systems

Leonid Petrov (University of Virginia)

November 2, 2022

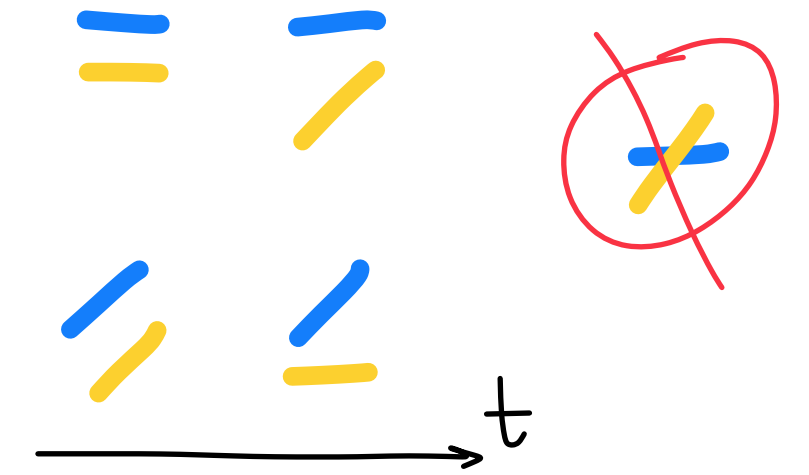
joint with Axel Saenz (Oregon State University), preprint upcoming

**A tale of two cars on a
one-lane road**

Two cars (discrete time TASEP with Bernoulli jumps)

Time $t \in \mathbb{Z}_{\geq 0}$, 2 cars with speeds $a_1 > a_2 > 0$, probabilities of jumps $a_i/(1 + a_i)$

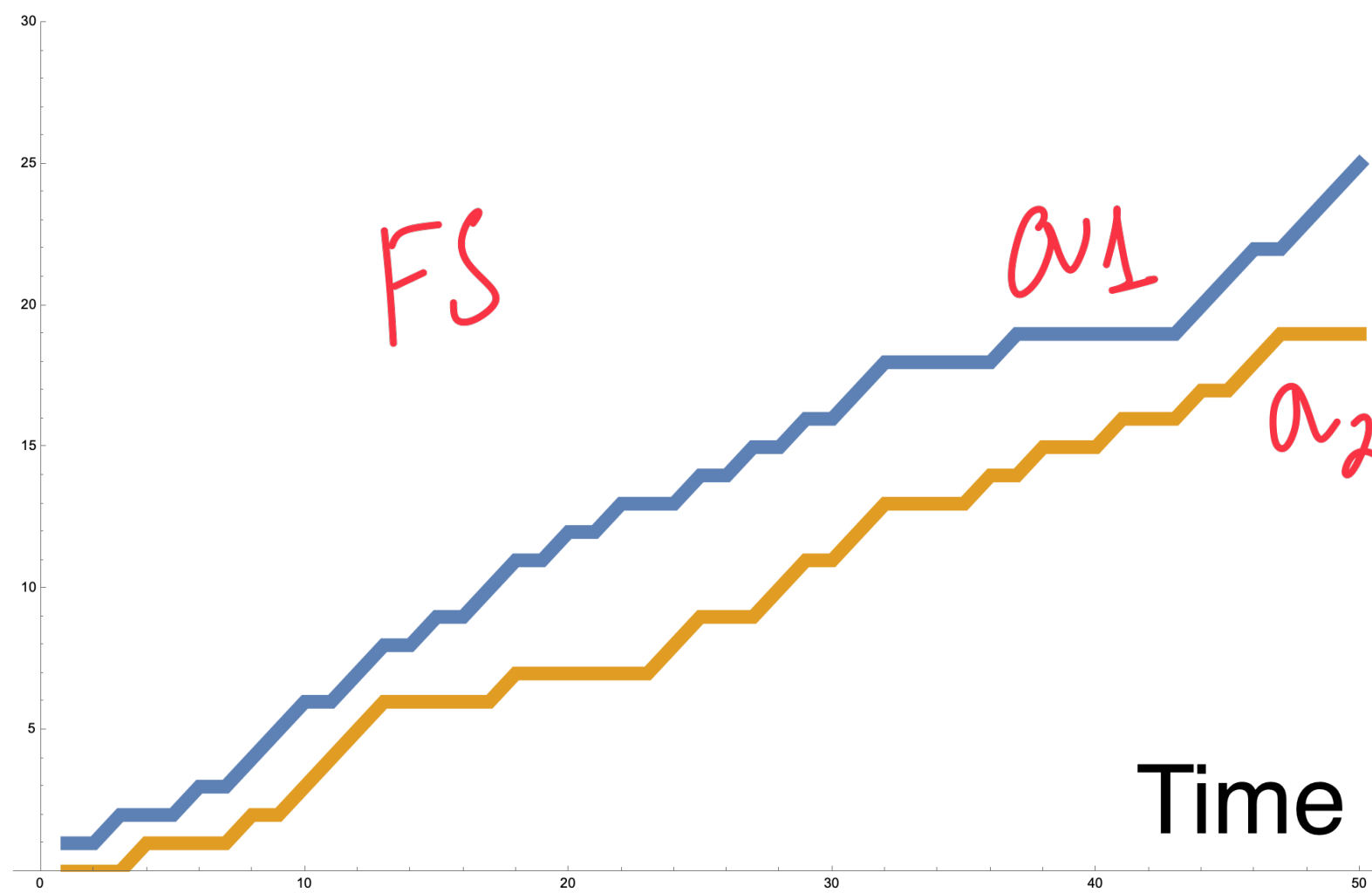
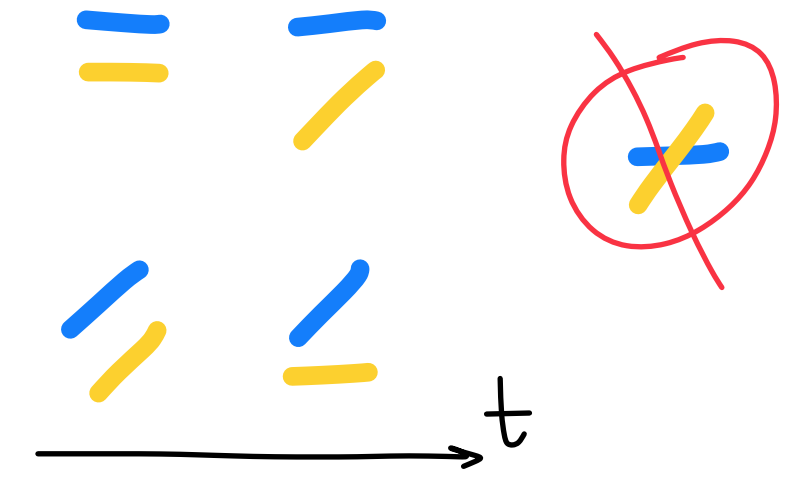
One-lane highway: no passing. Consider two systems: FS and SF



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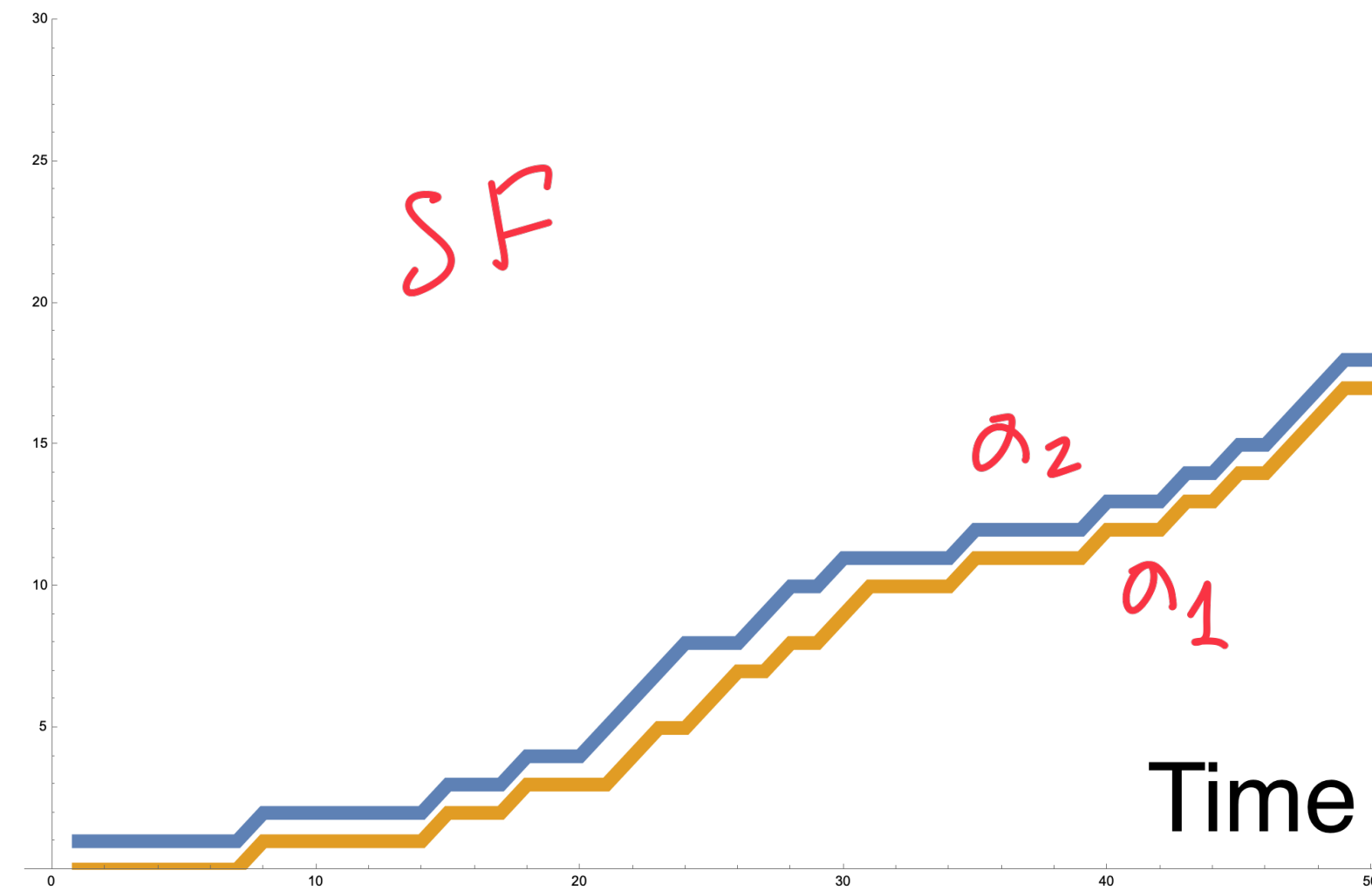
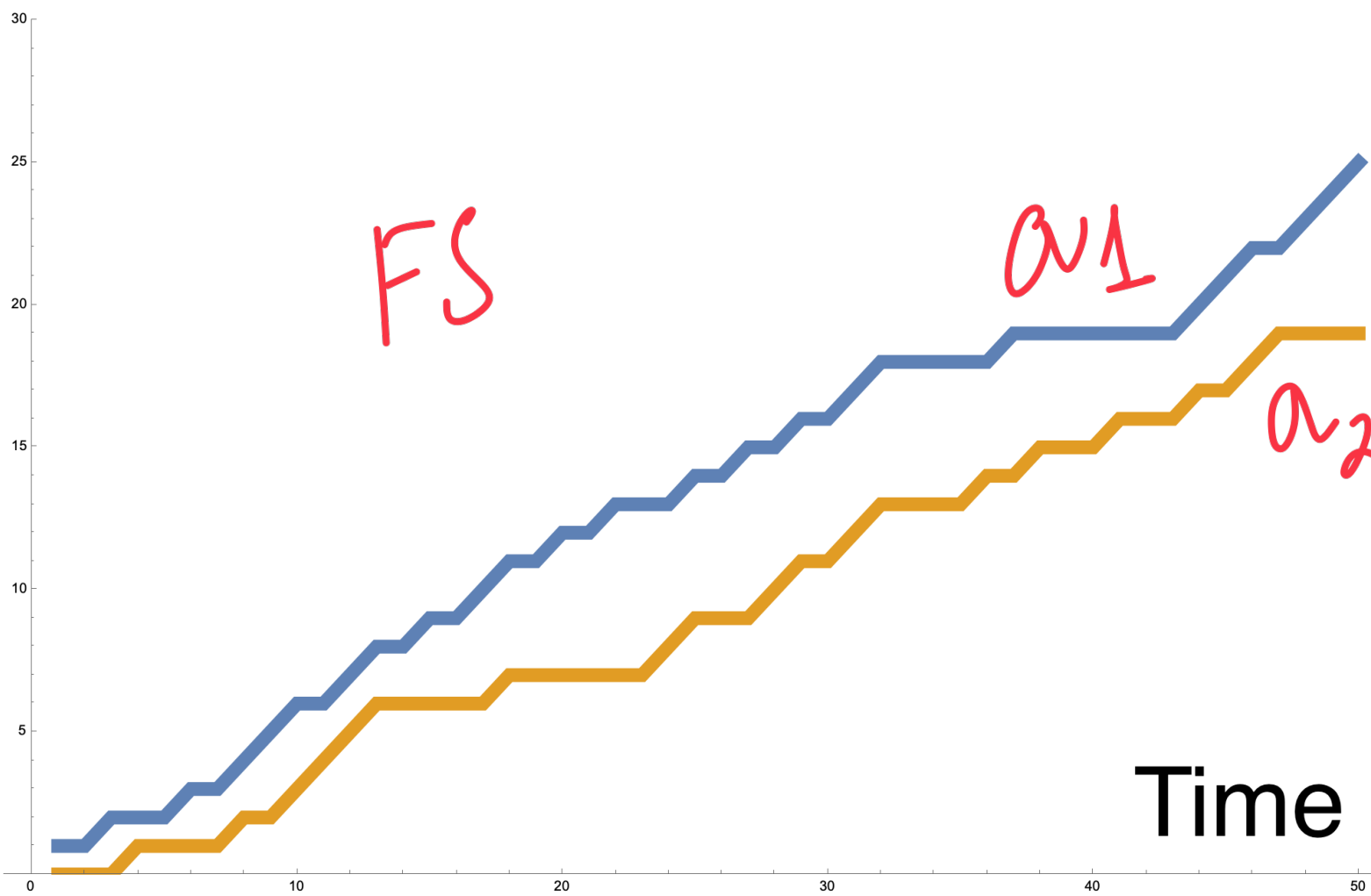
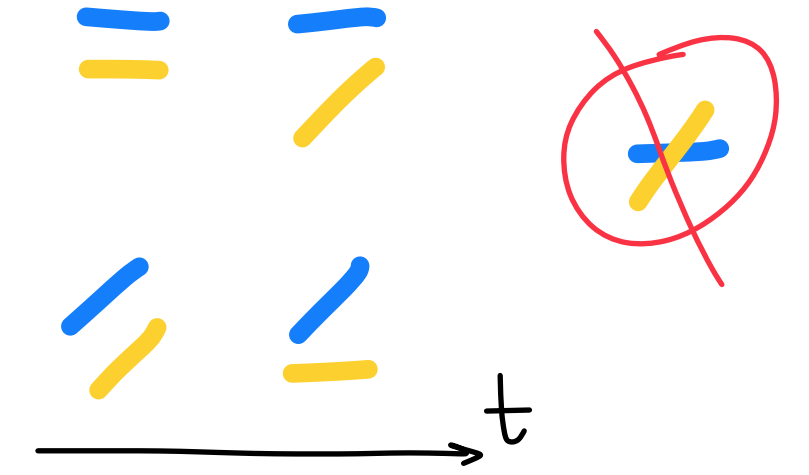
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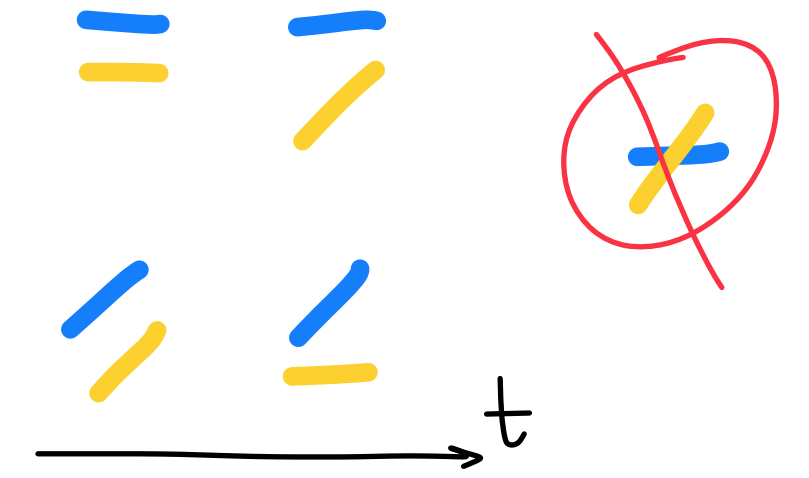
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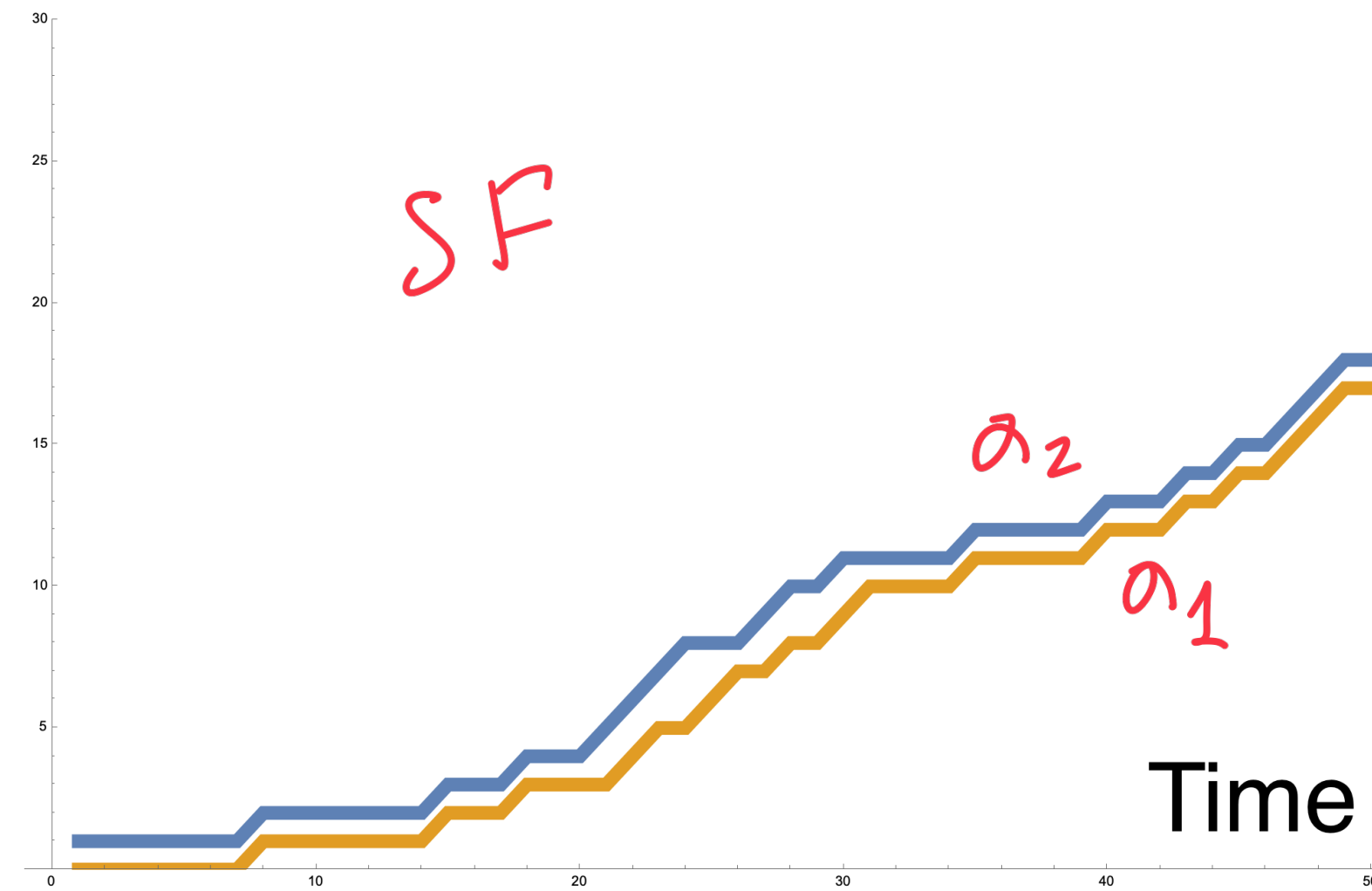
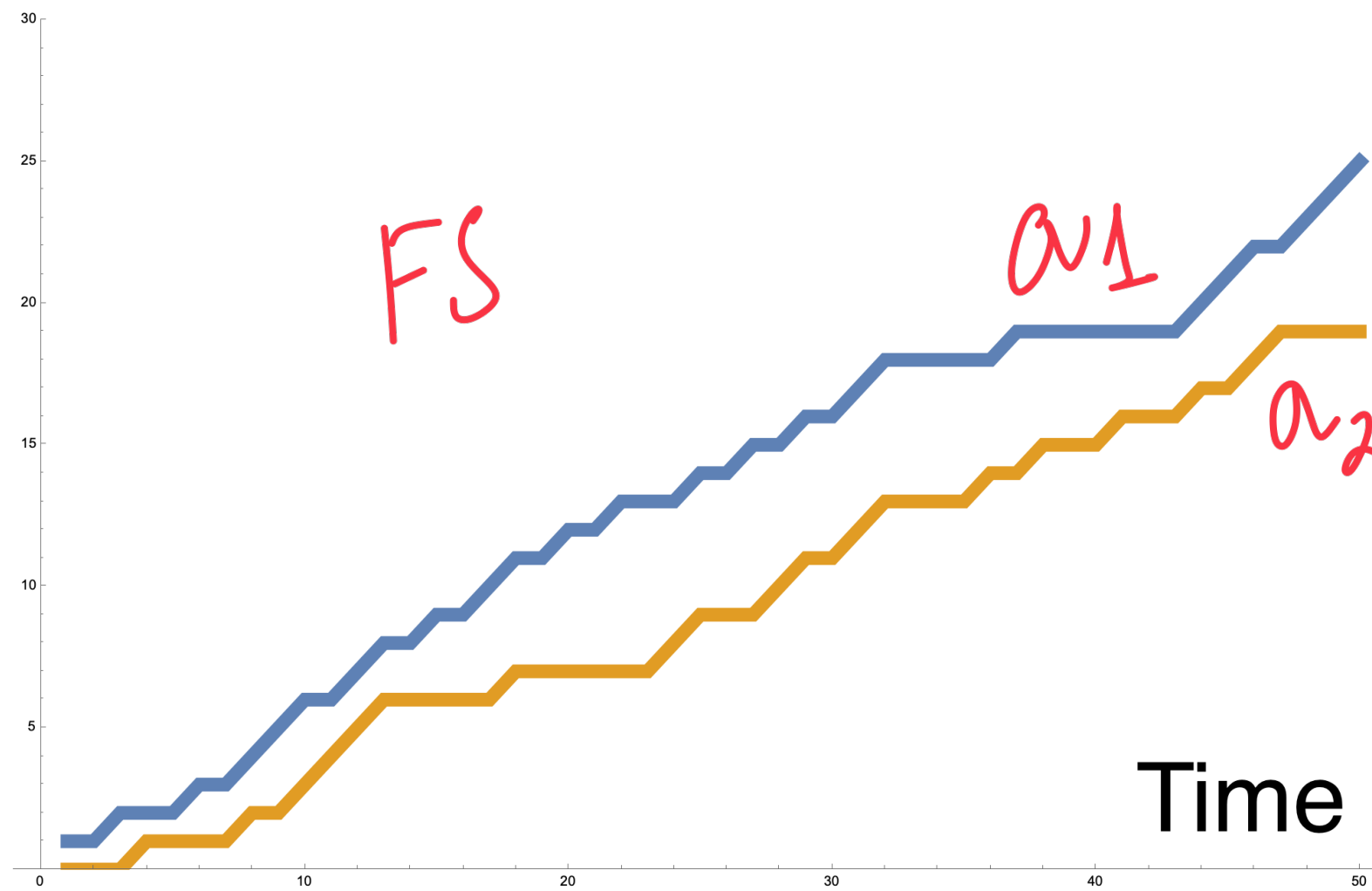
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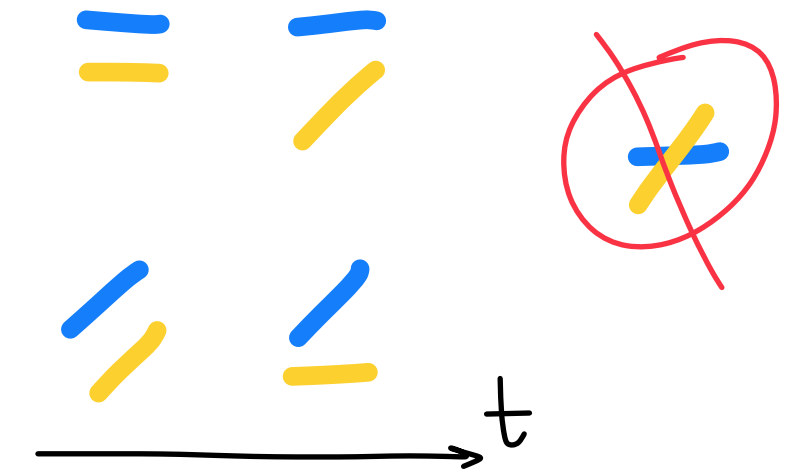
The long-time speed of the car ahead (blue) depends on which car is first; for the car behind (yellow) it **does not** depend on the order



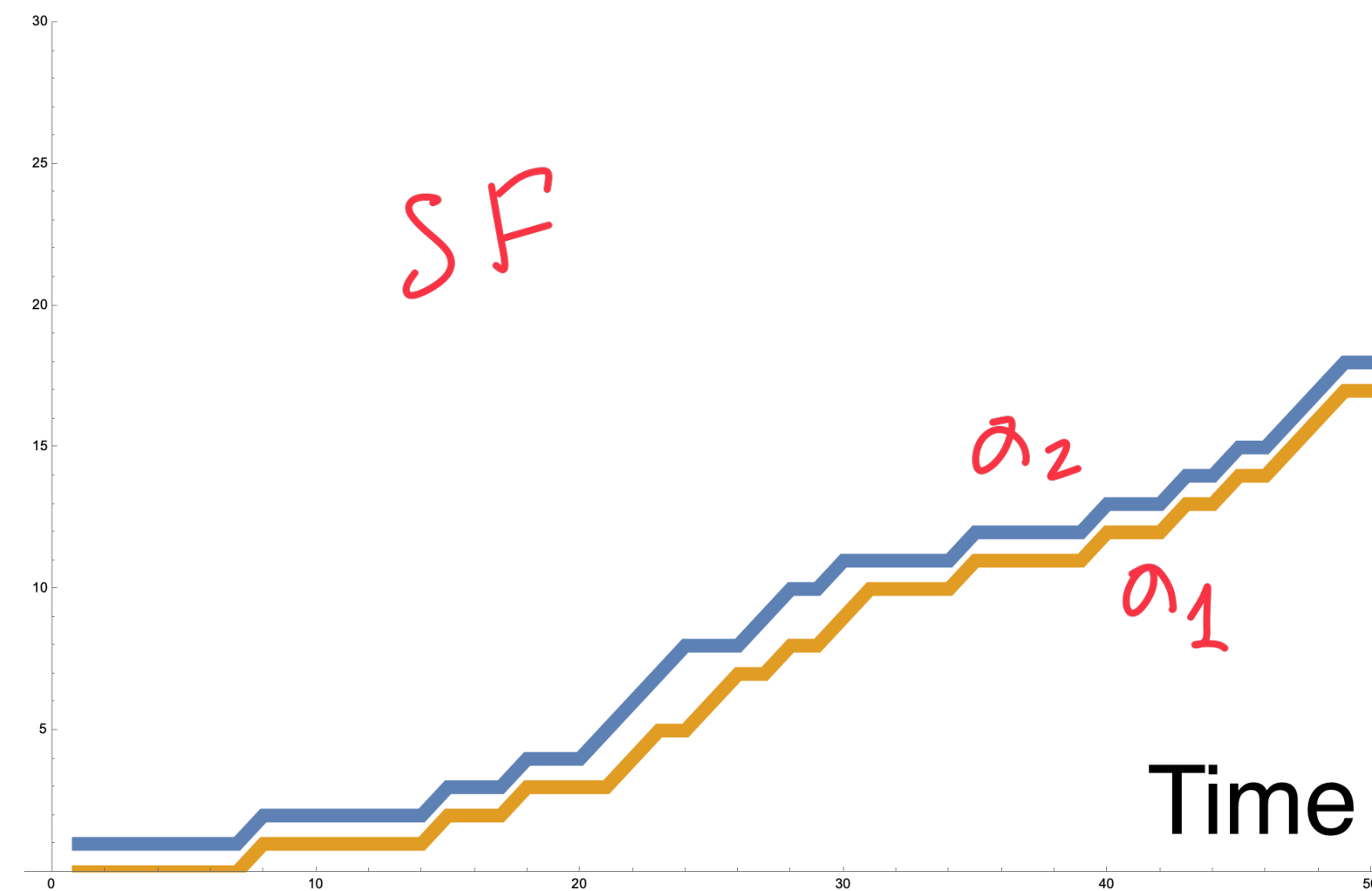
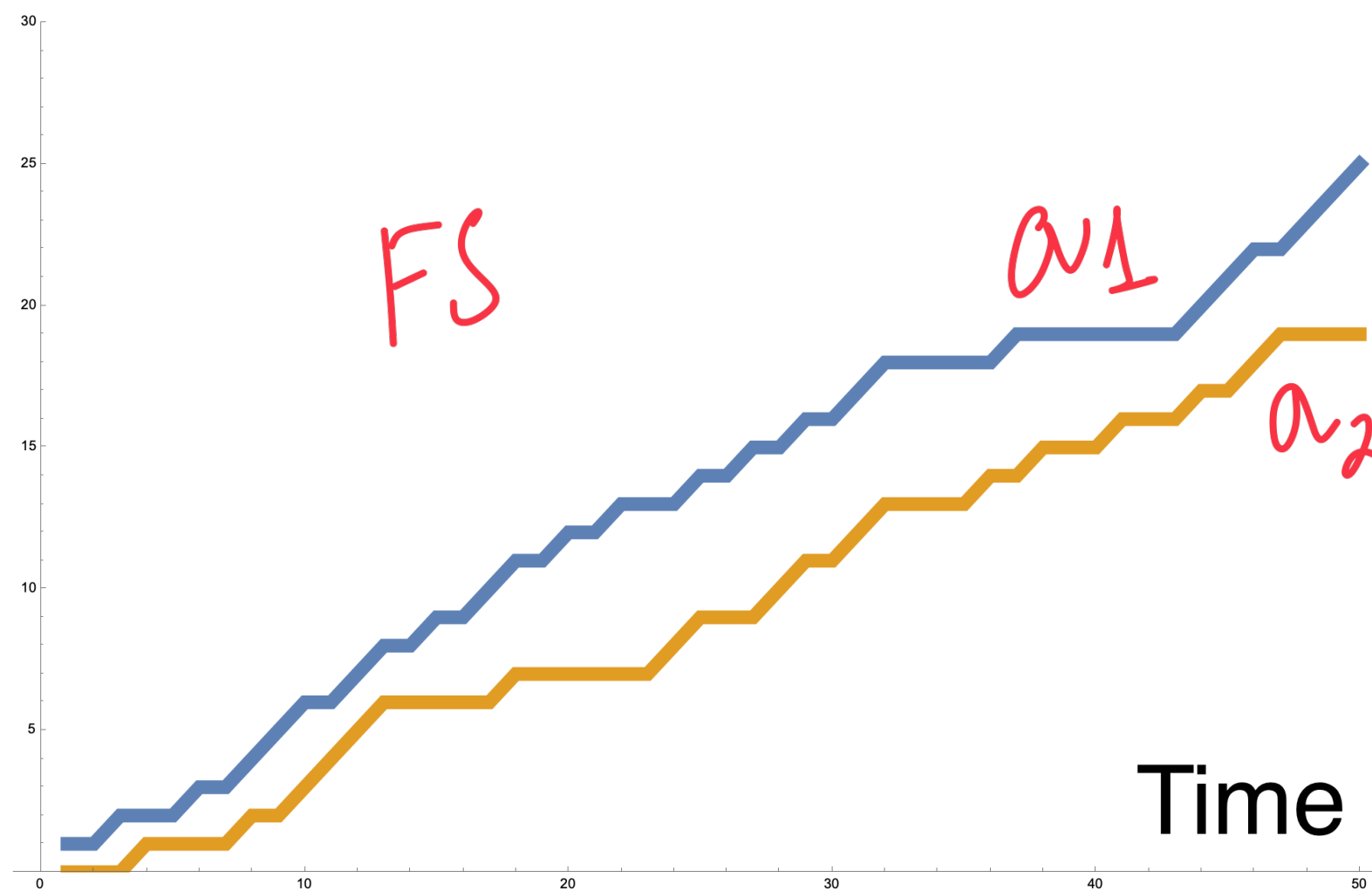
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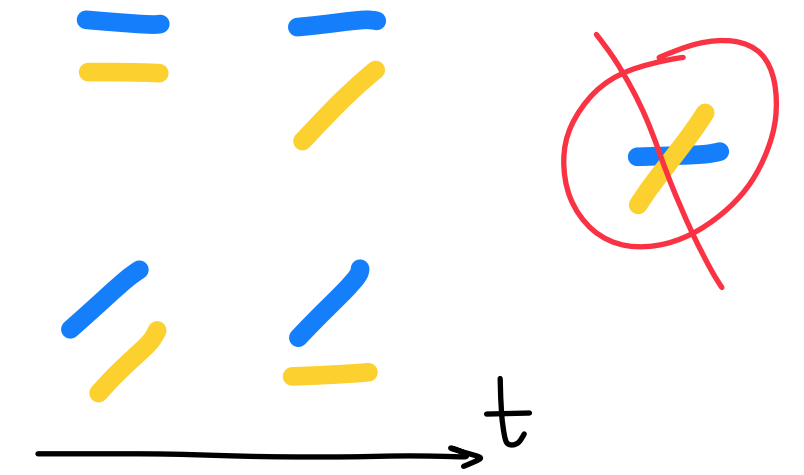
Theorem. (Vershik-Kerov ~1981; O'Connell 2003)

If the cars started at locations 0,1 (immediate neighbors; called *step initial configuration*), then the distribution of the trajectory of the car behind is **independent** of the order of the speeds

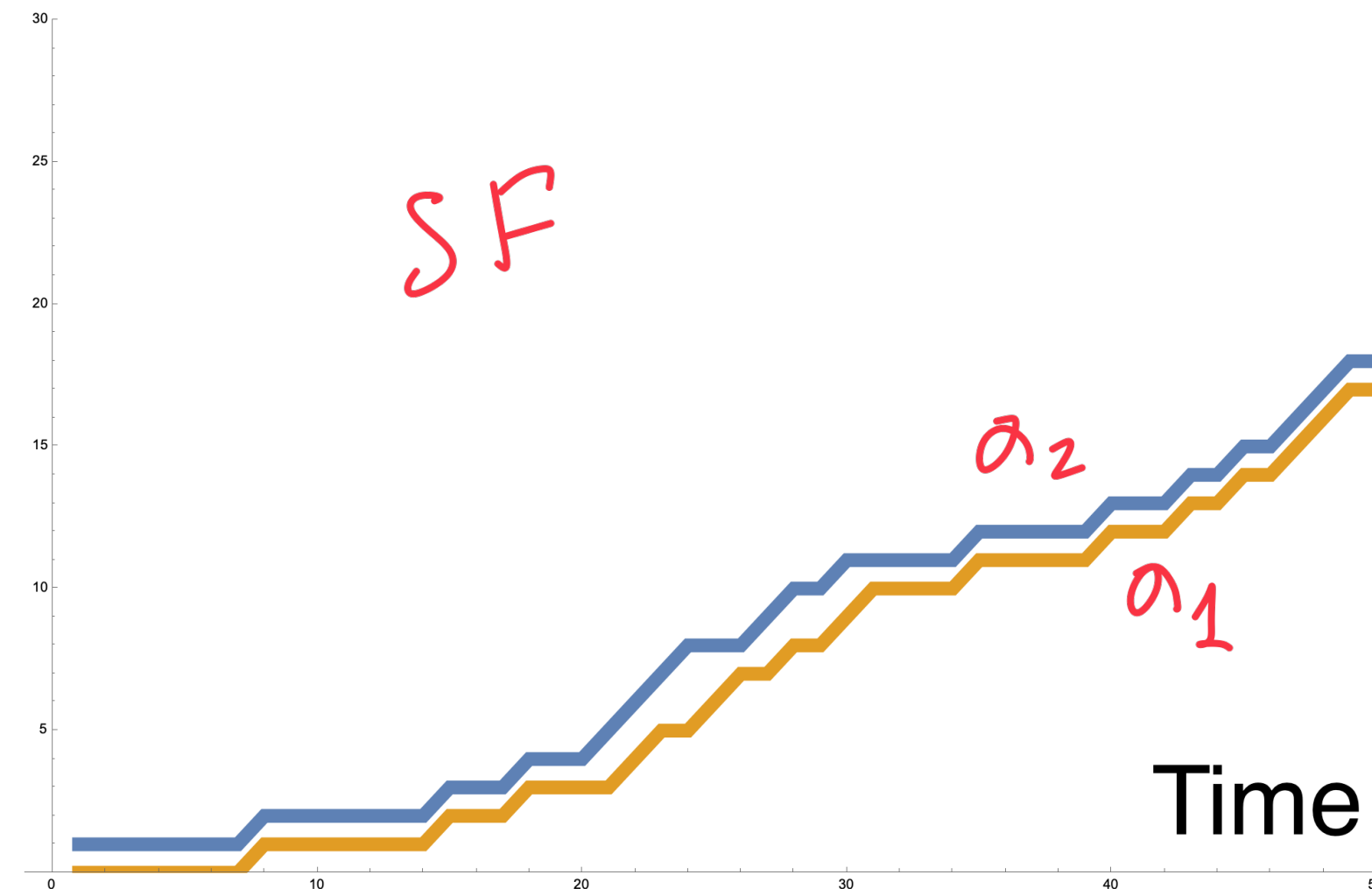
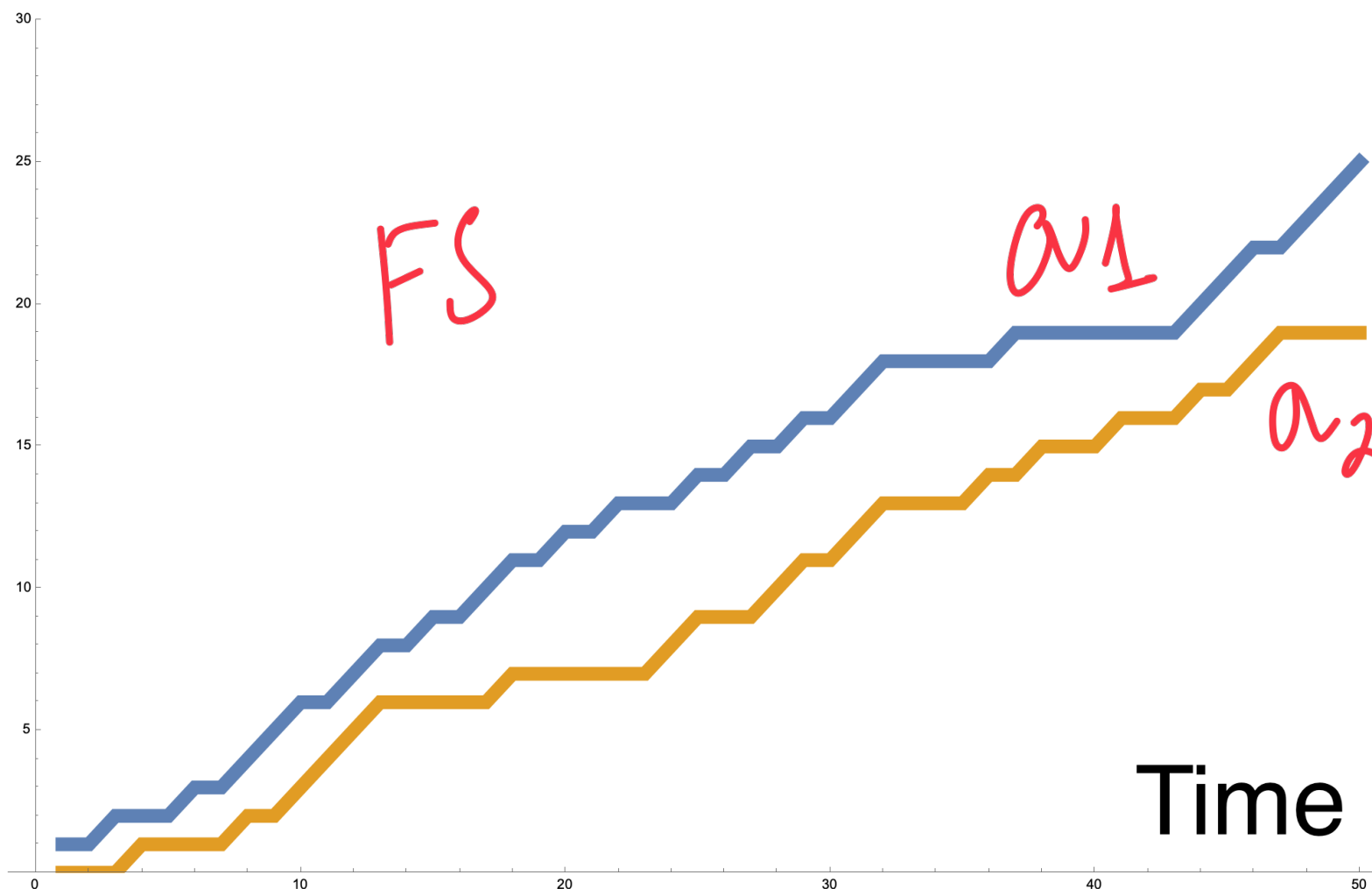
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← follows from Robinson-Schensted-Knuth correspondence which encodes unused jumps

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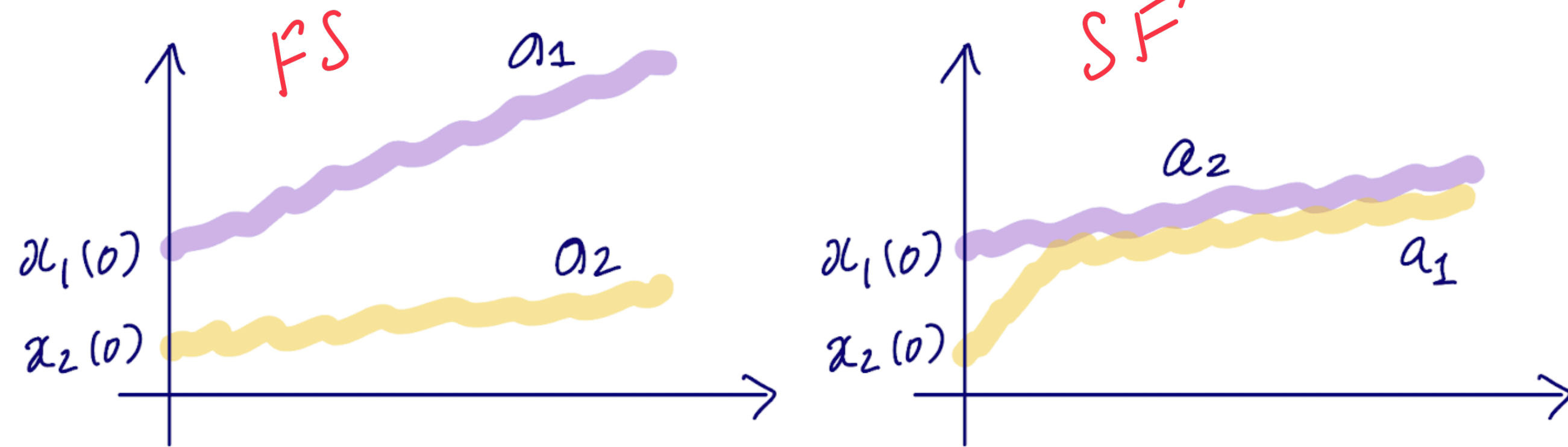
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Theorem **fails** when cars are not initially neighbors, $x_1(0) - x_2(0) - 1 > 0$

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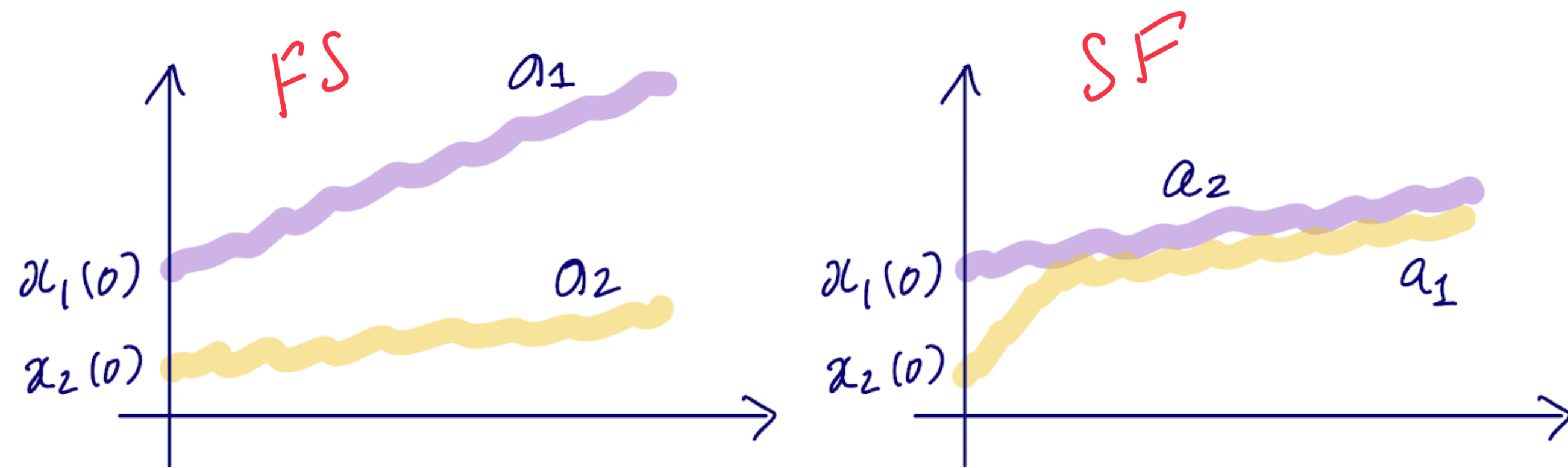
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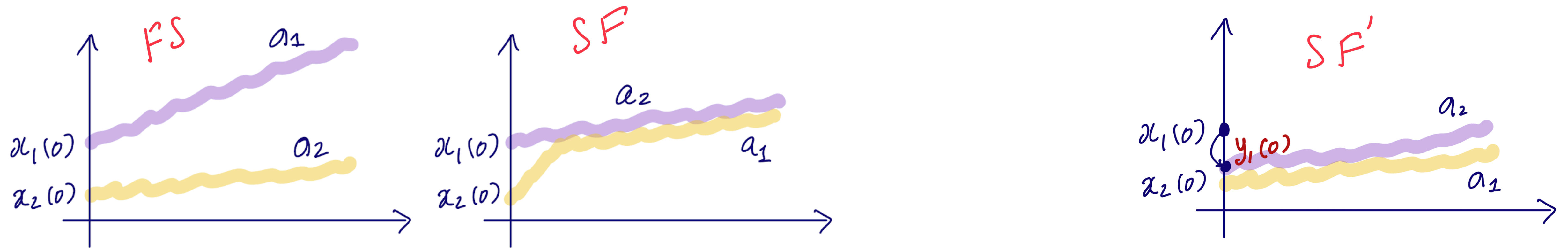
Theorem (P.-Saenz 2022). Define $y_1(0) = x_2(0) + 1 + \min(G, x_1(0) - x_2(0) - 1)$, where $G \in \mathbb{Z}_{\geq 0}$ is an independent geometric random variable with $P(G = k) = (a_2/a_1)^k(1 - a_2/a_1)$. Let SF' be the system started from $(y_1(0), x_2(0))$.

Then the distributions of the trajectories of the second particle in FS and SF' are **the same**.

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When applied to $x_1(0) = 1, x_2(0) = 0$, the operator B_{a_2/a_1} acts as identity, so

$$\delta_{step} T_{a_1, a_2} B_{a_2/a_1} = \delta_{step} B_{a_2/a_1} T_{a_2, a_1} = \delta_{step} T_{a_2, a_1}$$

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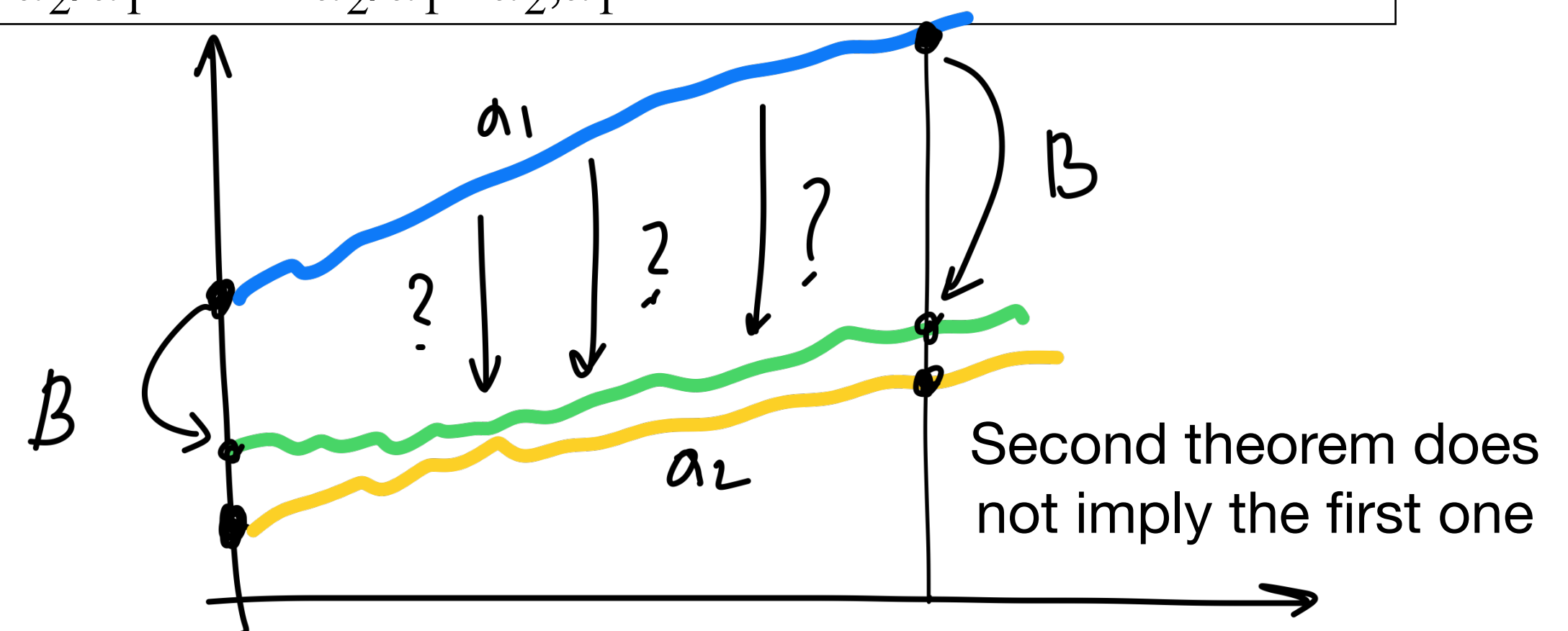
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For questions and remarks

Proof via Yang-Baxter equation

Jumps and Yang-Baxter equation

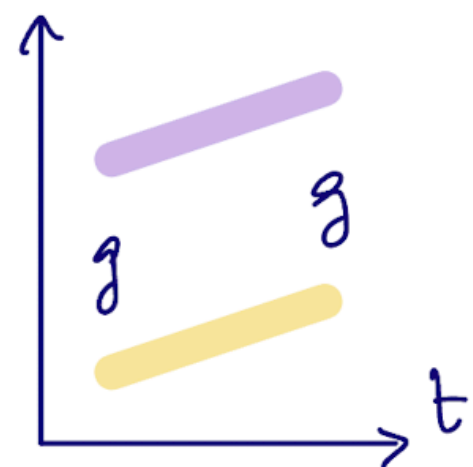
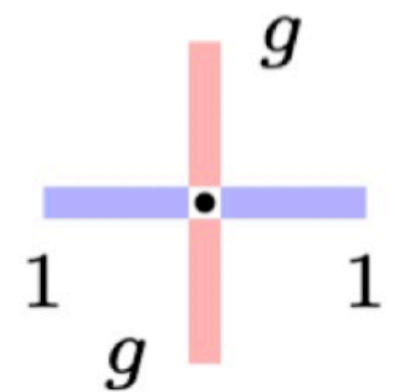
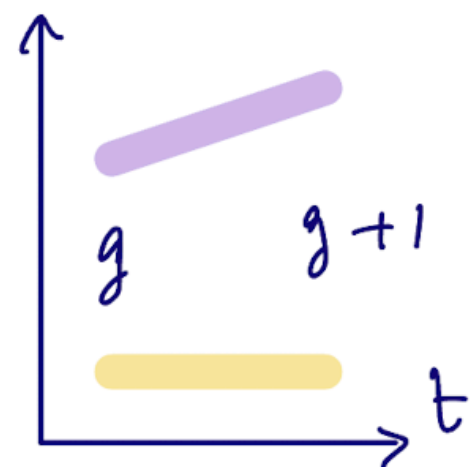
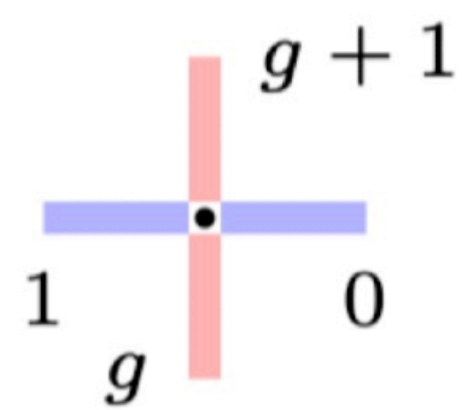
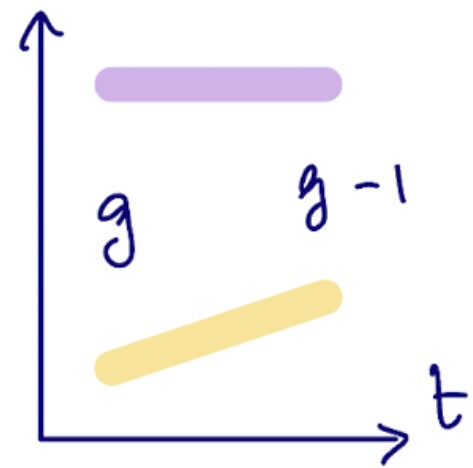
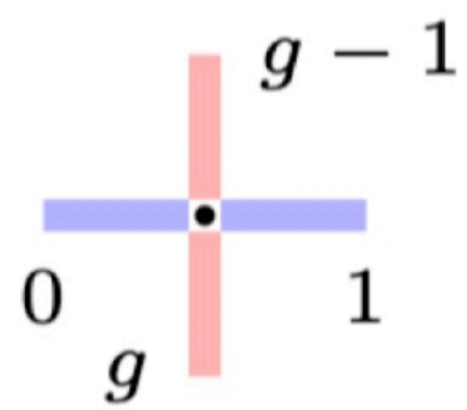
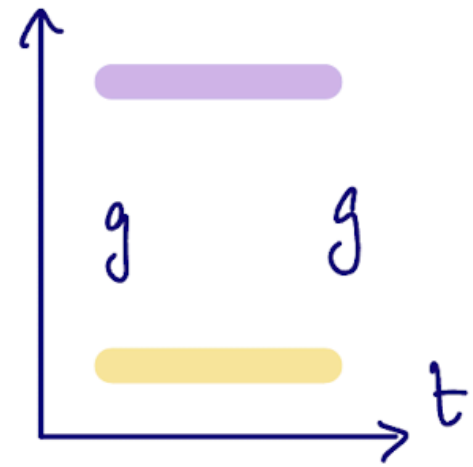
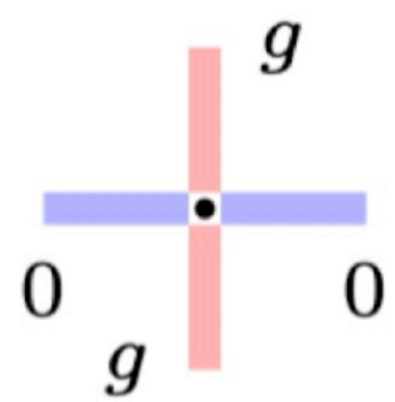
Translate into the “vertex model”
language. In vertex models, time runs **up**.

$g = x_1 - x_2 - 1$ is the **gap**

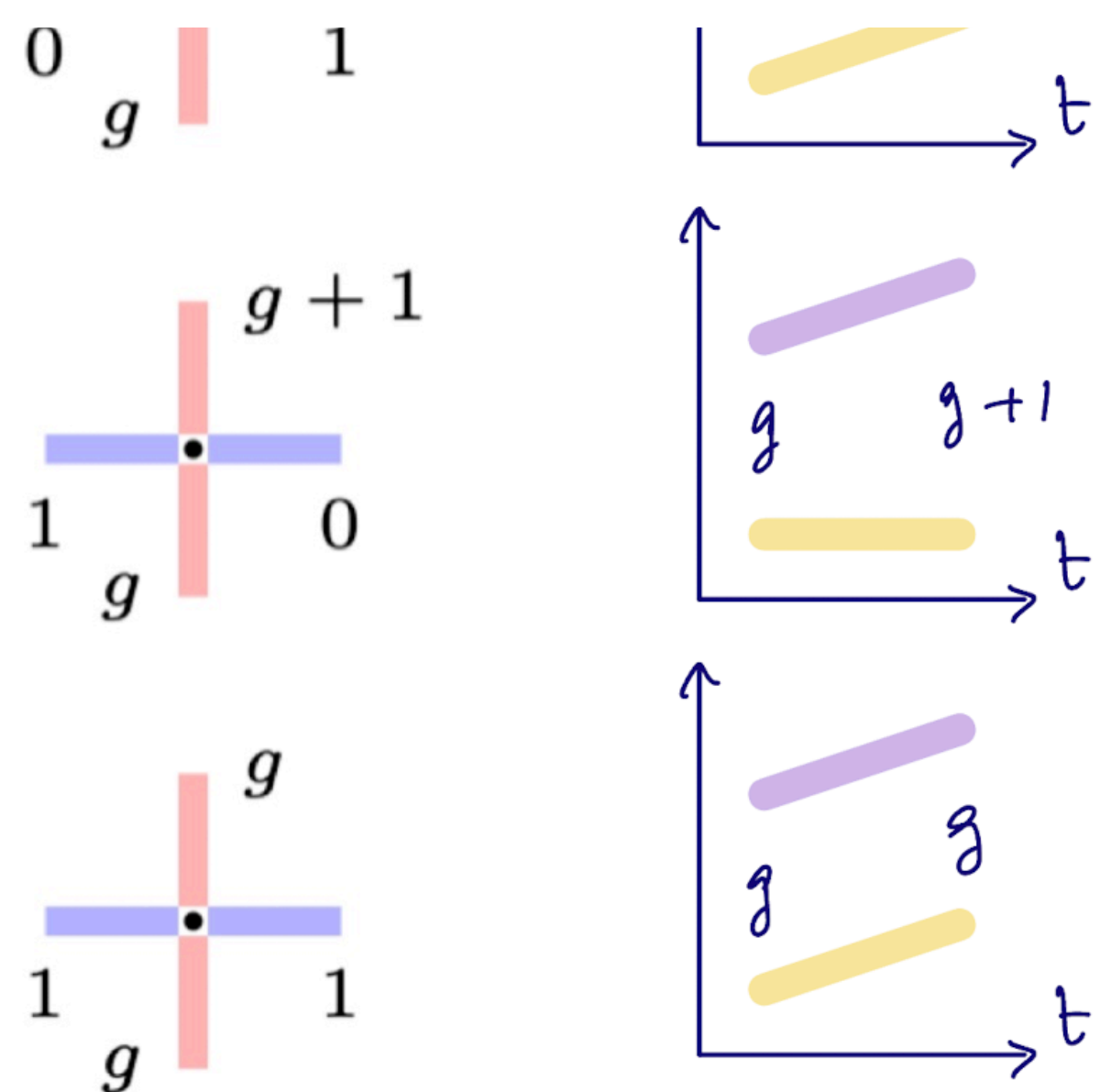
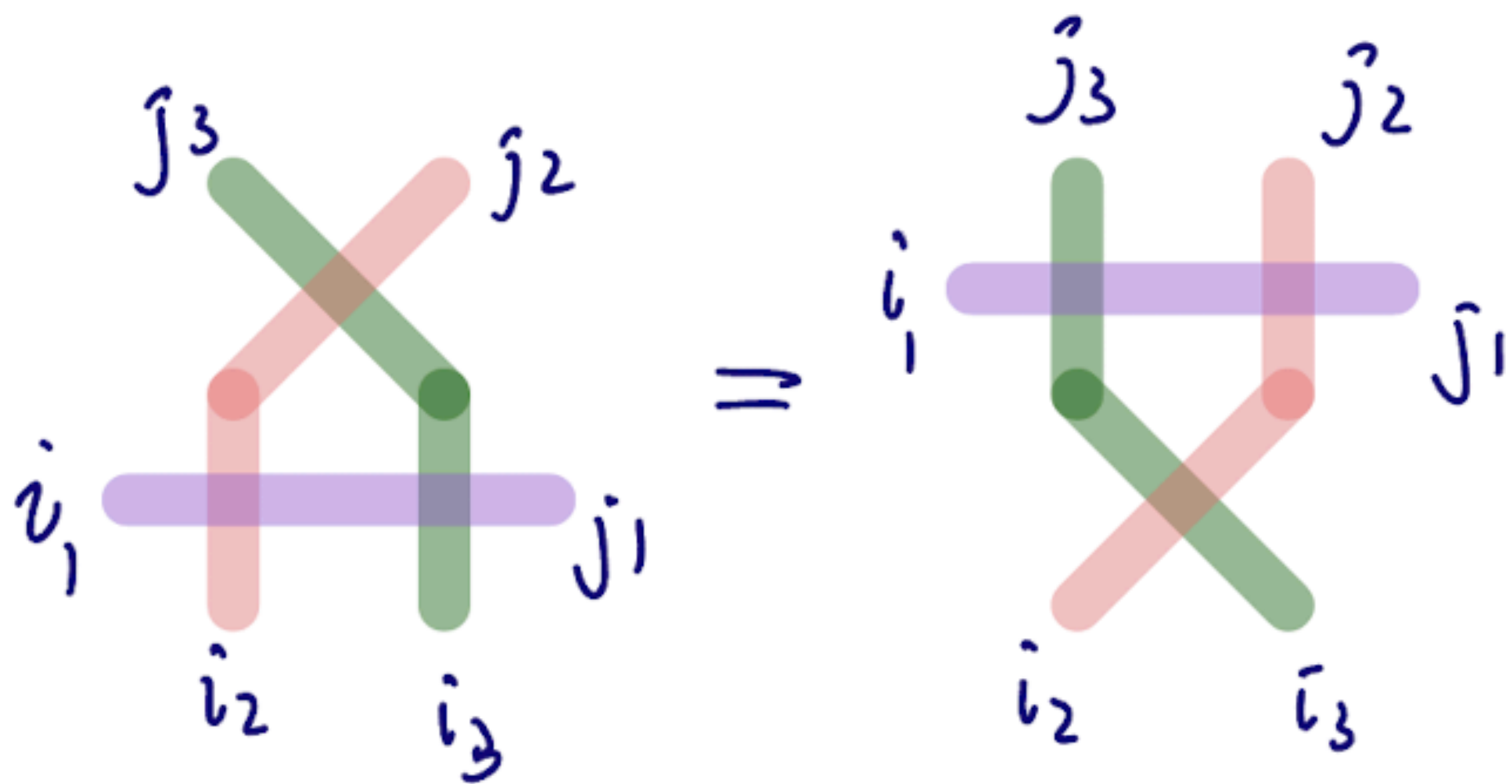
Jumps and Yang-Baxter equation

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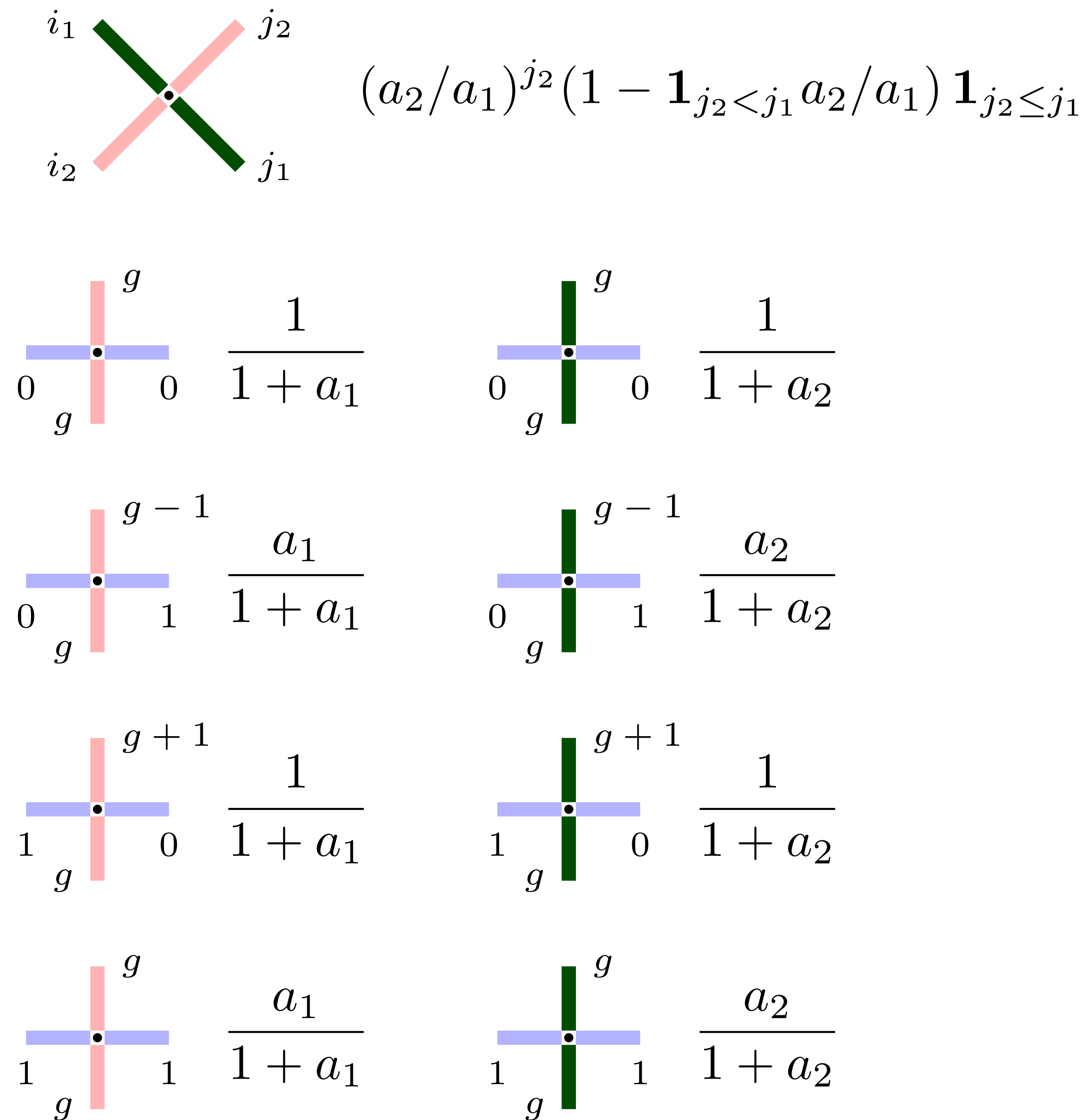
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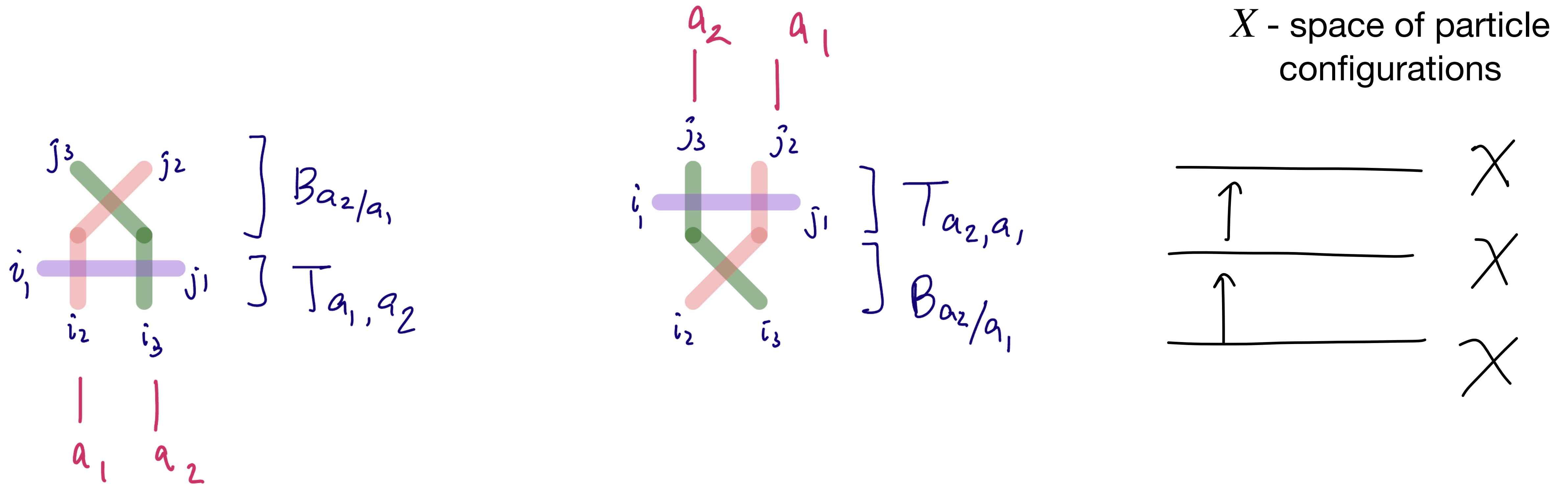
Jumps and Yang-Baxter equation



Theorem. Vertex weights satisfy the Yang-Baxter equation



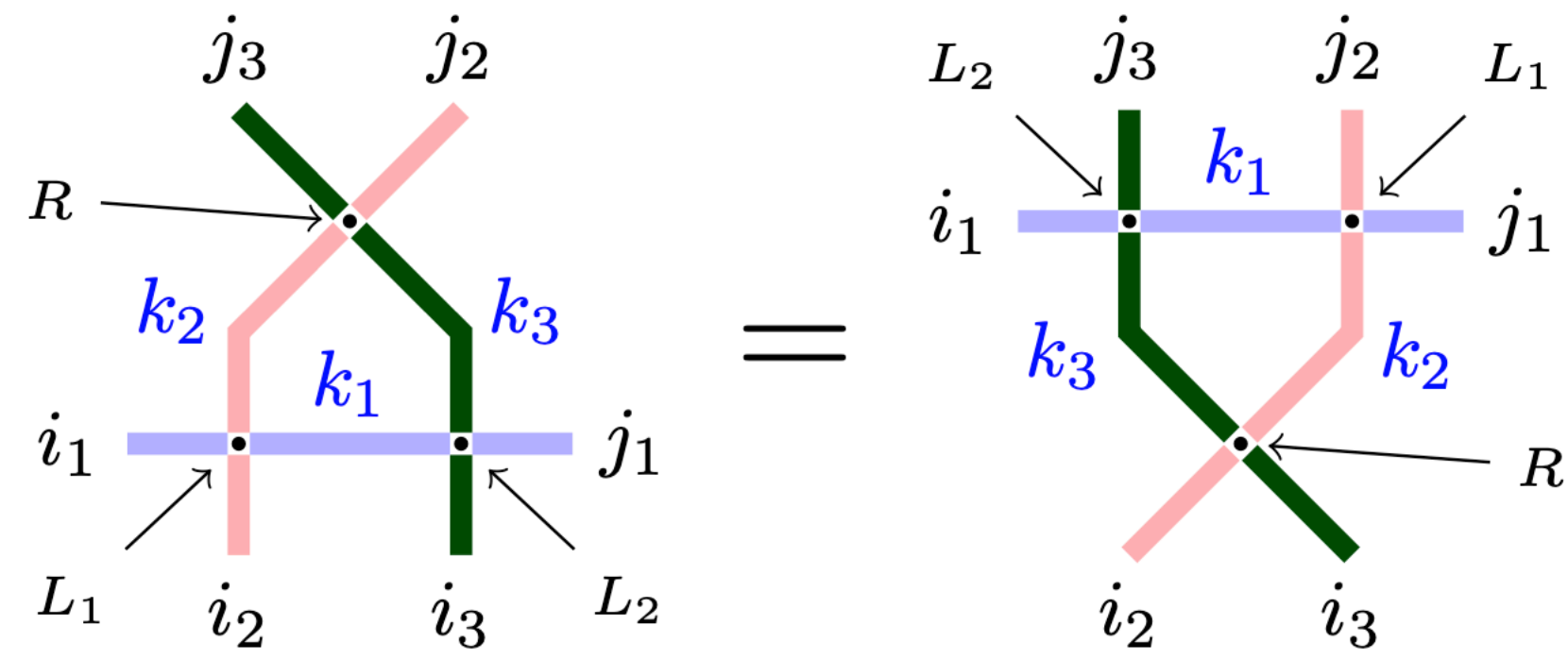
Intertwining relation



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Intertwining relation for general stochastic R matrices



$$L_{u,s}^{(1)}(g, 0; g, 0) = \frac{1 - q^g su}{1 - su},$$

$$L_{u,s}^{(1)}(g, 1; g, 1) = \frac{-su + q^g s^2}{1 - su},$$

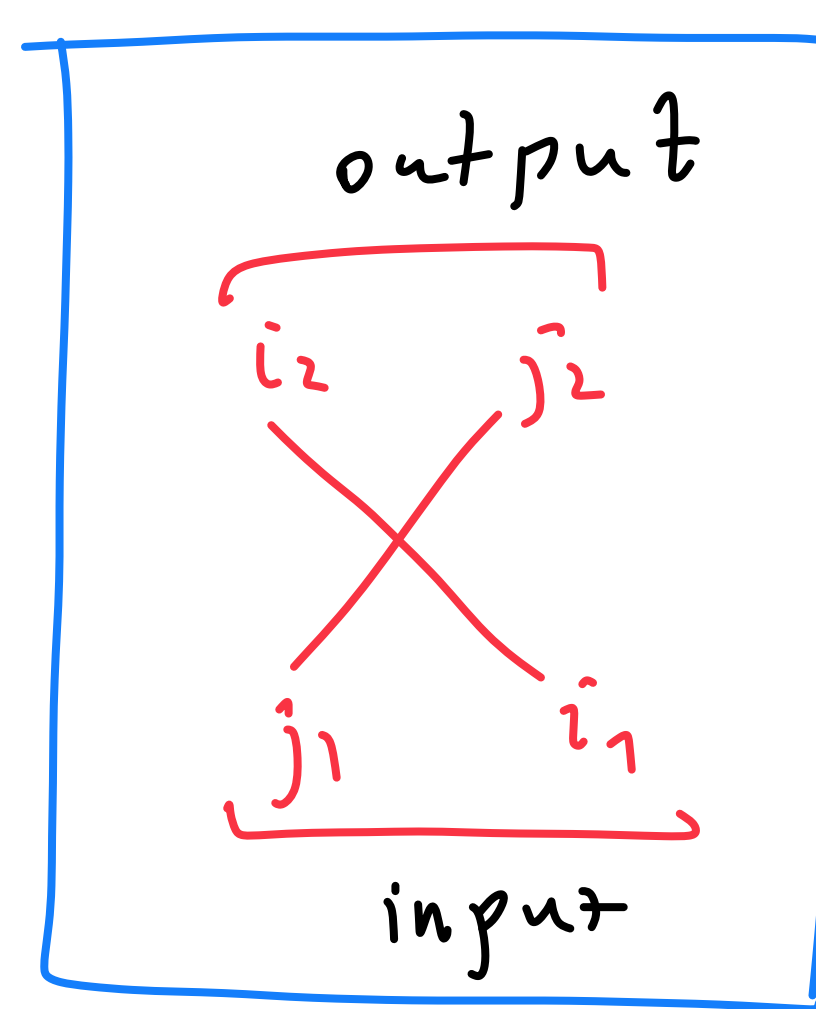
$$L_{u,s}^{(1)}(g, 0; g - 1, 1) = \frac{-su(1 - q^g)}{1 - su};$$

$$L_{u,s}^{(1)}(g, 1; g + 1, 0) = \frac{1 - q^g s^2}{1 - su}.$$

$$L_i = L_{u_i, s_i}^{(j)} \quad (\text{fused})$$

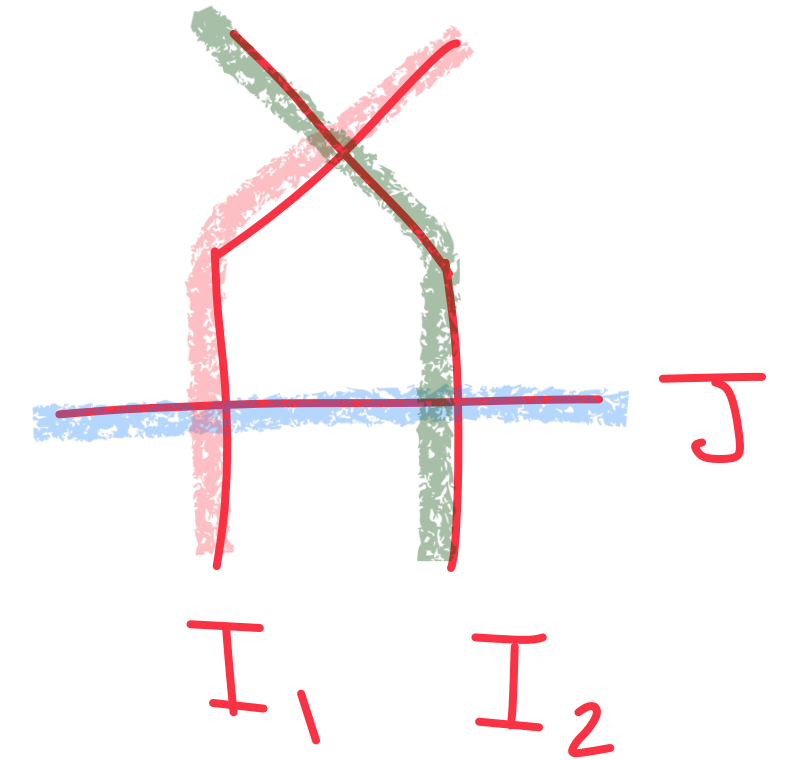
$$R = R_{u_2/u_1, s_1, s_2} = L_{\frac{s_1 u_2}{u_1}, s_2}^{(I_1)}$$

Stochastic:

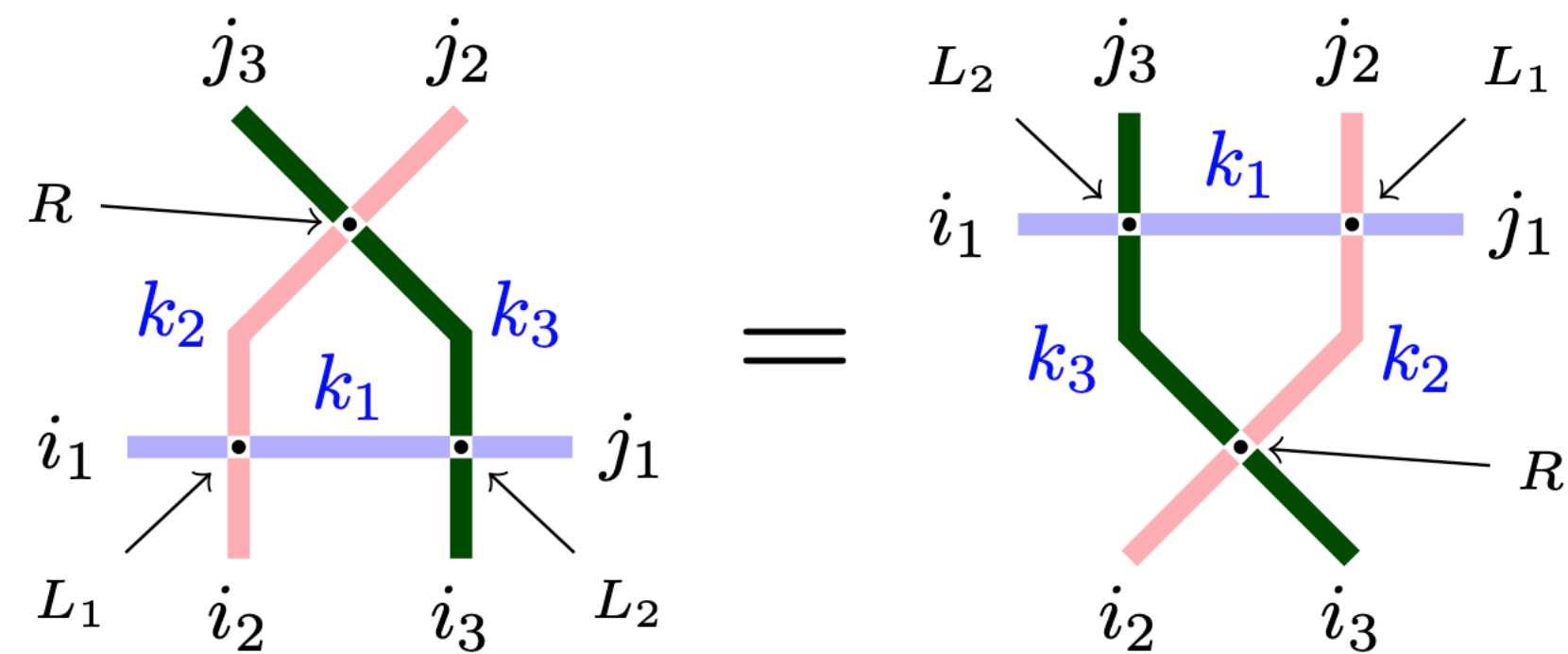


$$s_1 = q^{-I_1/2}$$

(fusion)



Intertwining relation for general stochastic R matrices



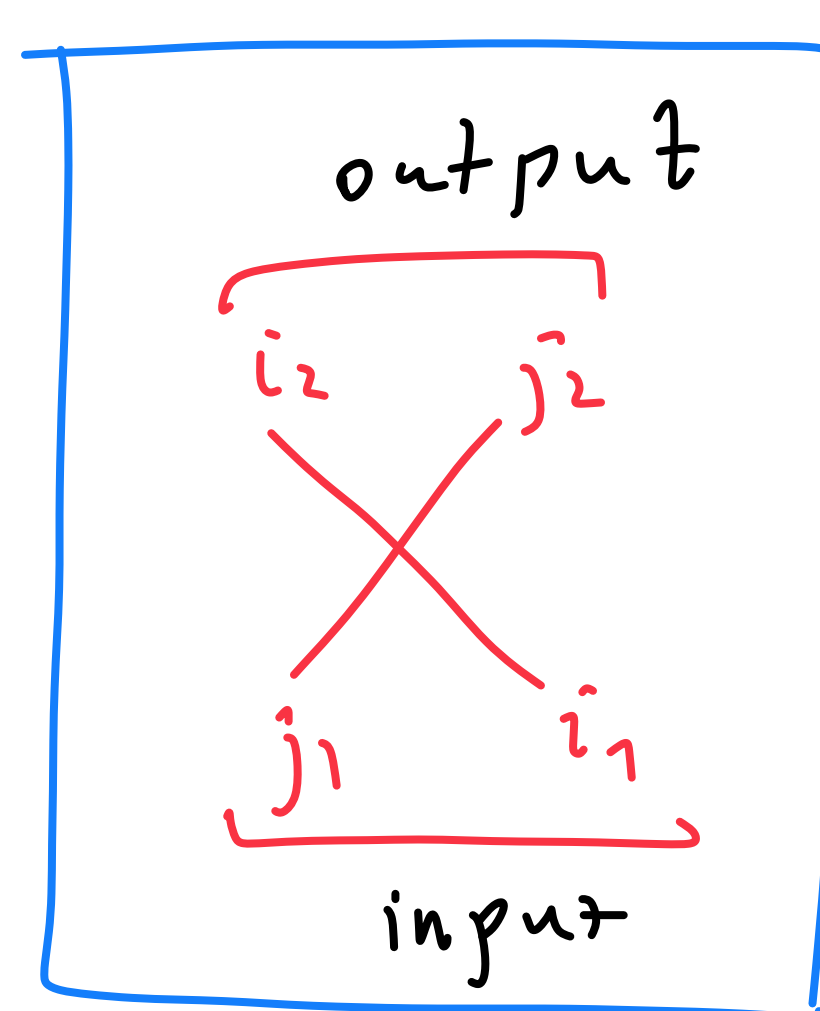
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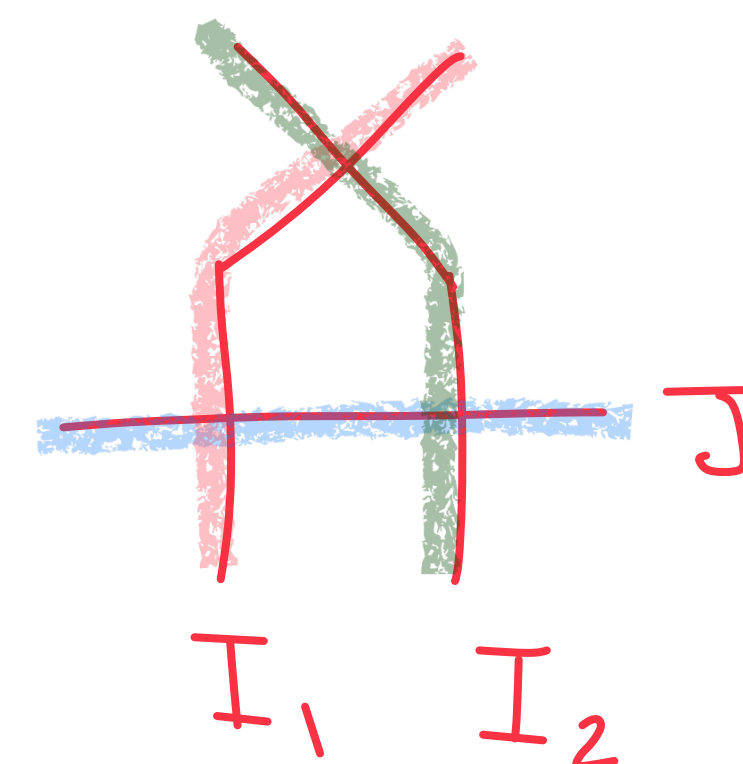
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(fusion)



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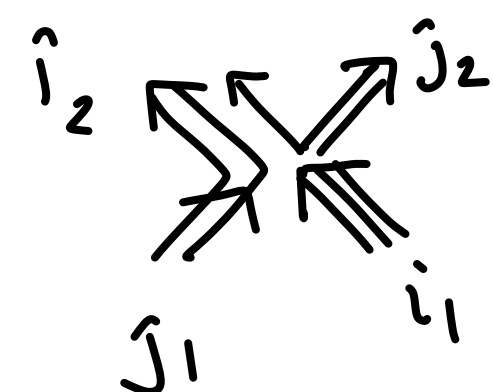
$$R = R_{u_2/u_1, s_1, s_2}^{(I_1)} = L_{\frac{s_1 u_2}{u_1}, s_2}^{(I_1)}$$

q-Mahn (monotone)

$$u_2/u_1 = s_2/s_1$$

⇒

specialization

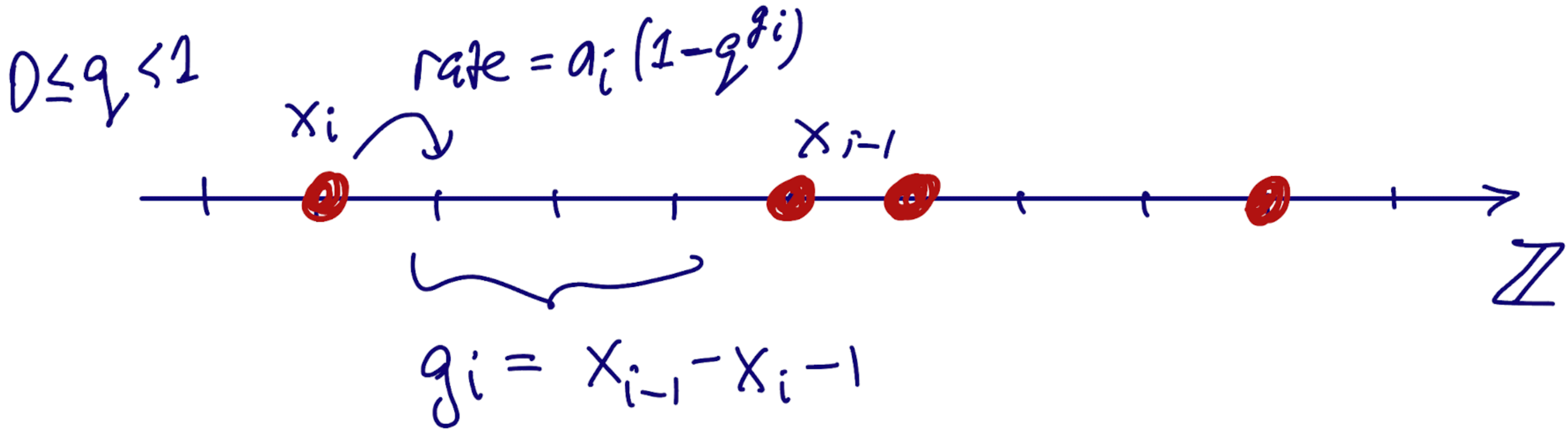


$$j_2 \leq i_1$$

For questions and remarks

General intertwining and Lax equations

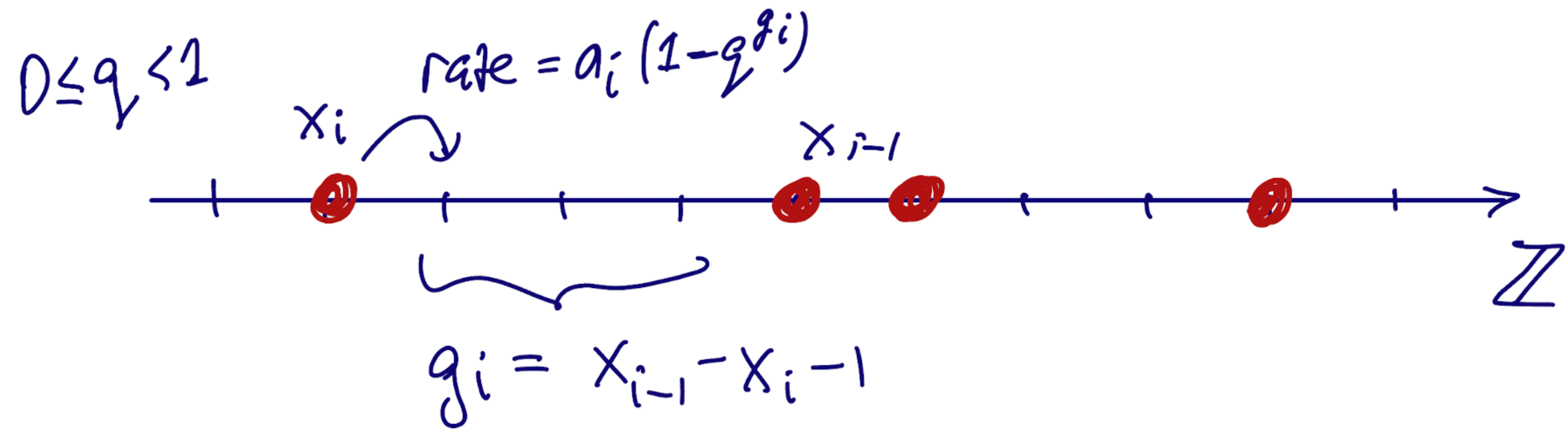
Intertwining for the q-TASEP in continuous time



$g_0 = +\infty$

In continuous time, each particle x_i jumps forward at rate $a_i(1 - q^{g_{ap_i}})$.
 Let $T_a(t)$ be the q-TASEP semigroup

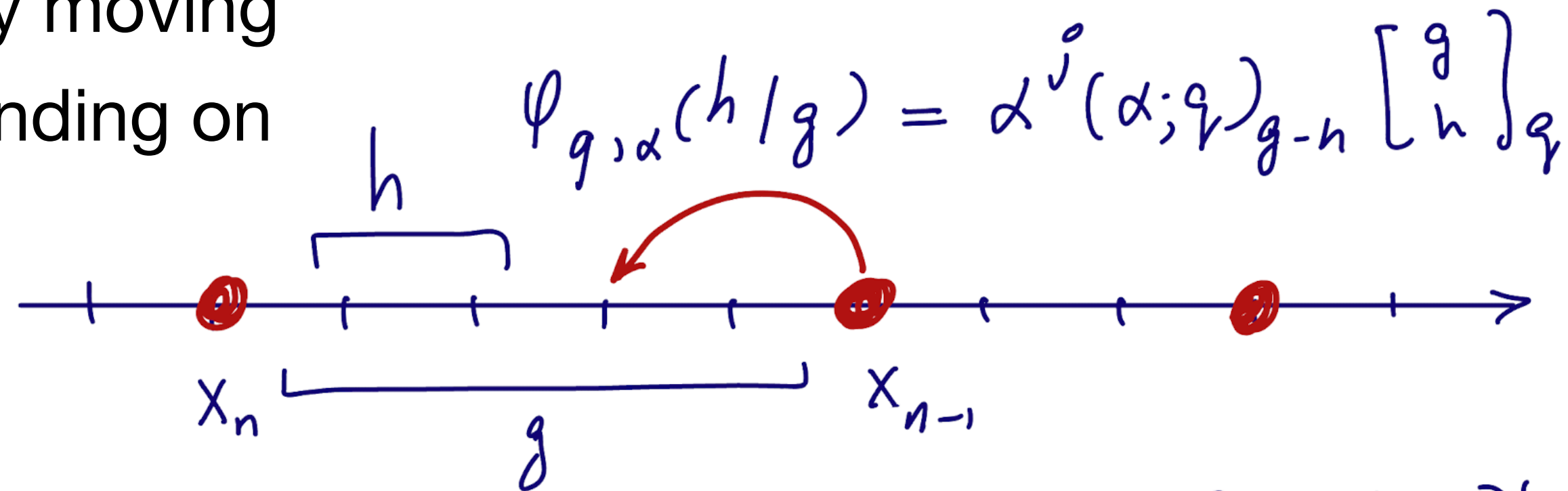
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Let B_{n-1} be the operator of randomly moving particle x_{n-1} back closer to x_n , depending on $\alpha = a_n/a_{n-1} < 1$.

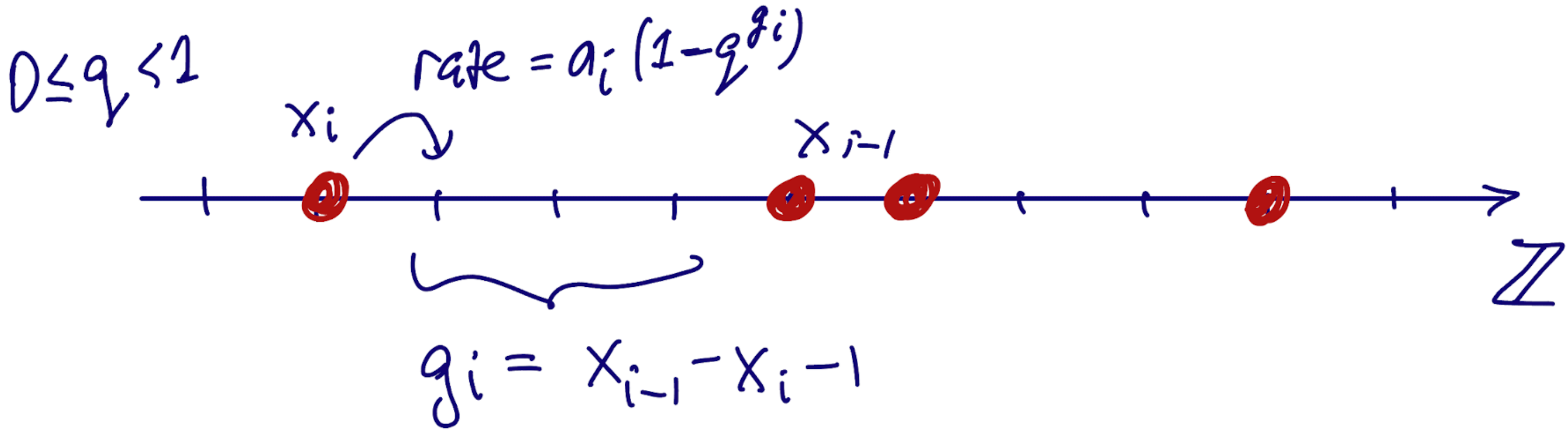


$$(a; q)_k = (1-a)(1-aq) \dots (1-aq^{k-1})$$

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$$[n]_q = \frac{(q; q)_n}{(q; q)_{n-k} (q; q)_k}$$

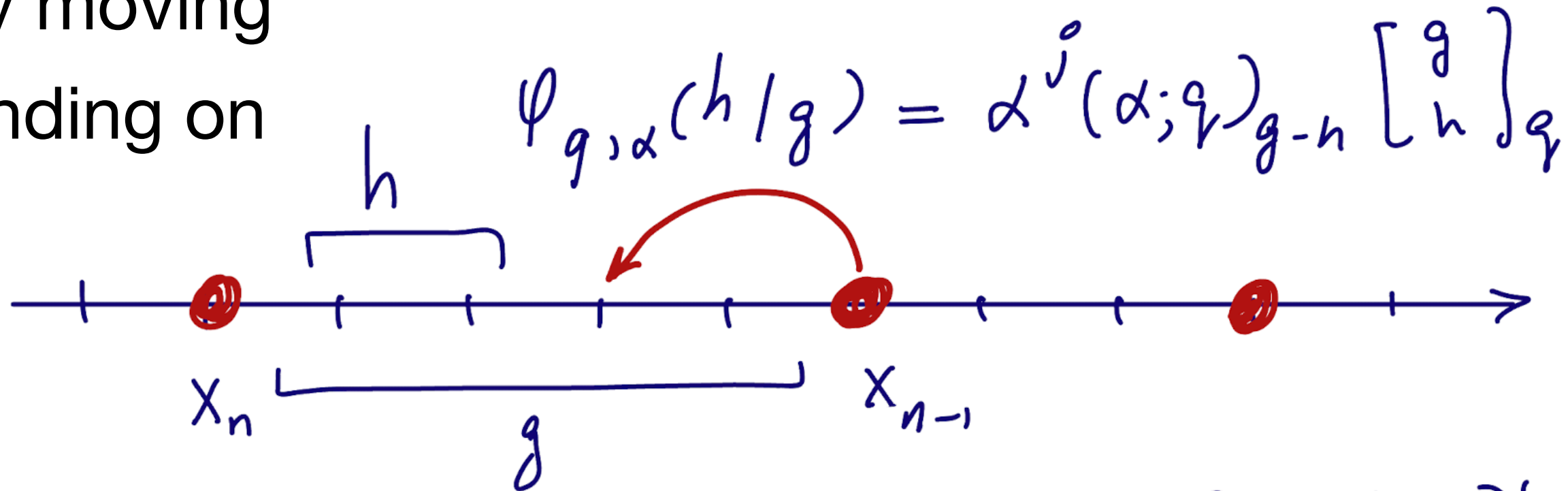
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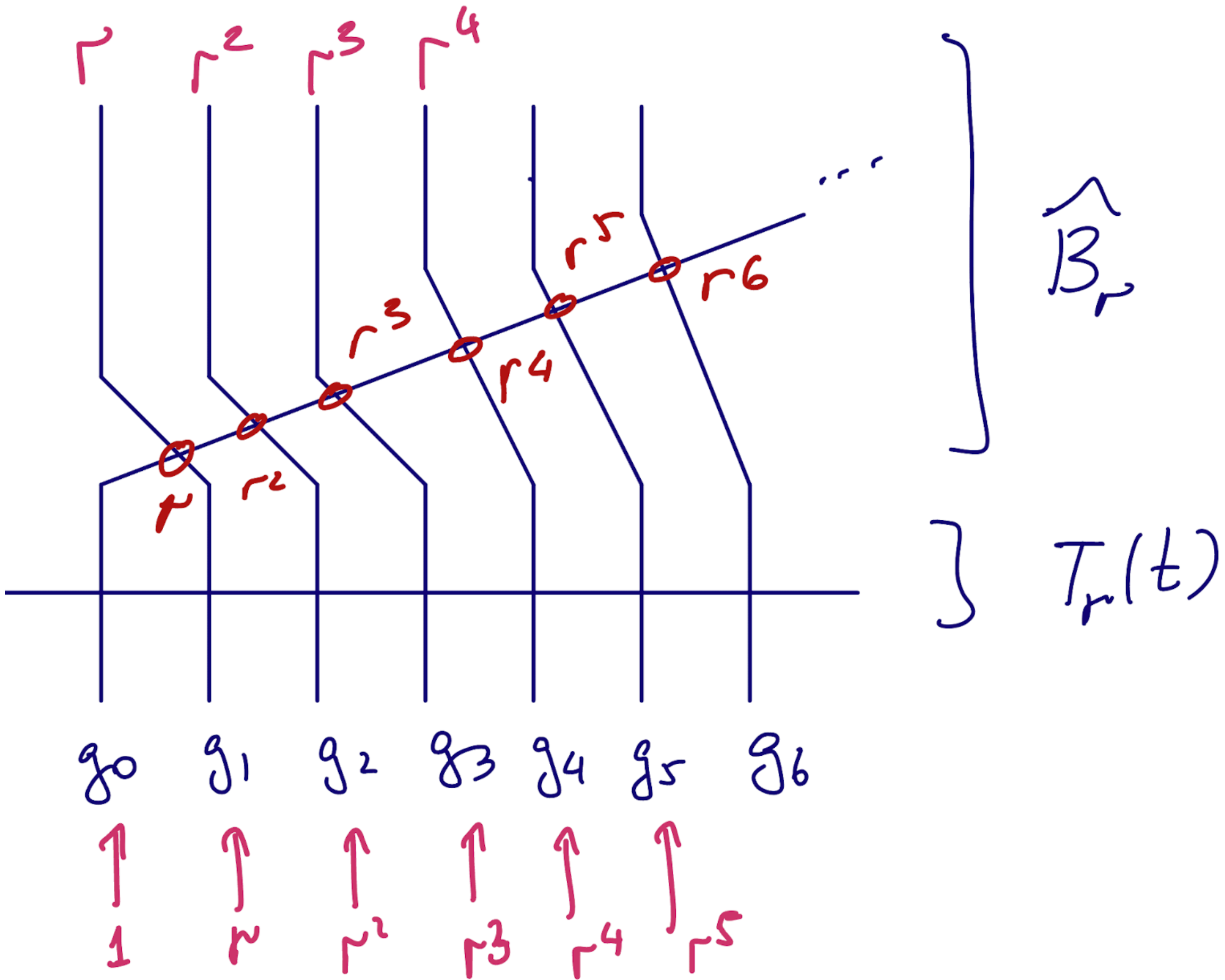
Theorem (P.-Saenz 2022). We have the intertwining $T_{\mathbf{a}}(t)B_{n-1} = B_{n-1}T_{\sigma_{n-1}\mathbf{a}}(t)$, where σ swaps $a_{n-1} \leftrightarrow a_n$.

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 $\alpha = a_n/a_{n-1} < 1$
 $[n]_q = \frac{(q; q)_n}{(q; q)_{n-k} (q; q)_k}$

Application to densely packed configurations: [P.-Saenz 2019], [P. 2019]

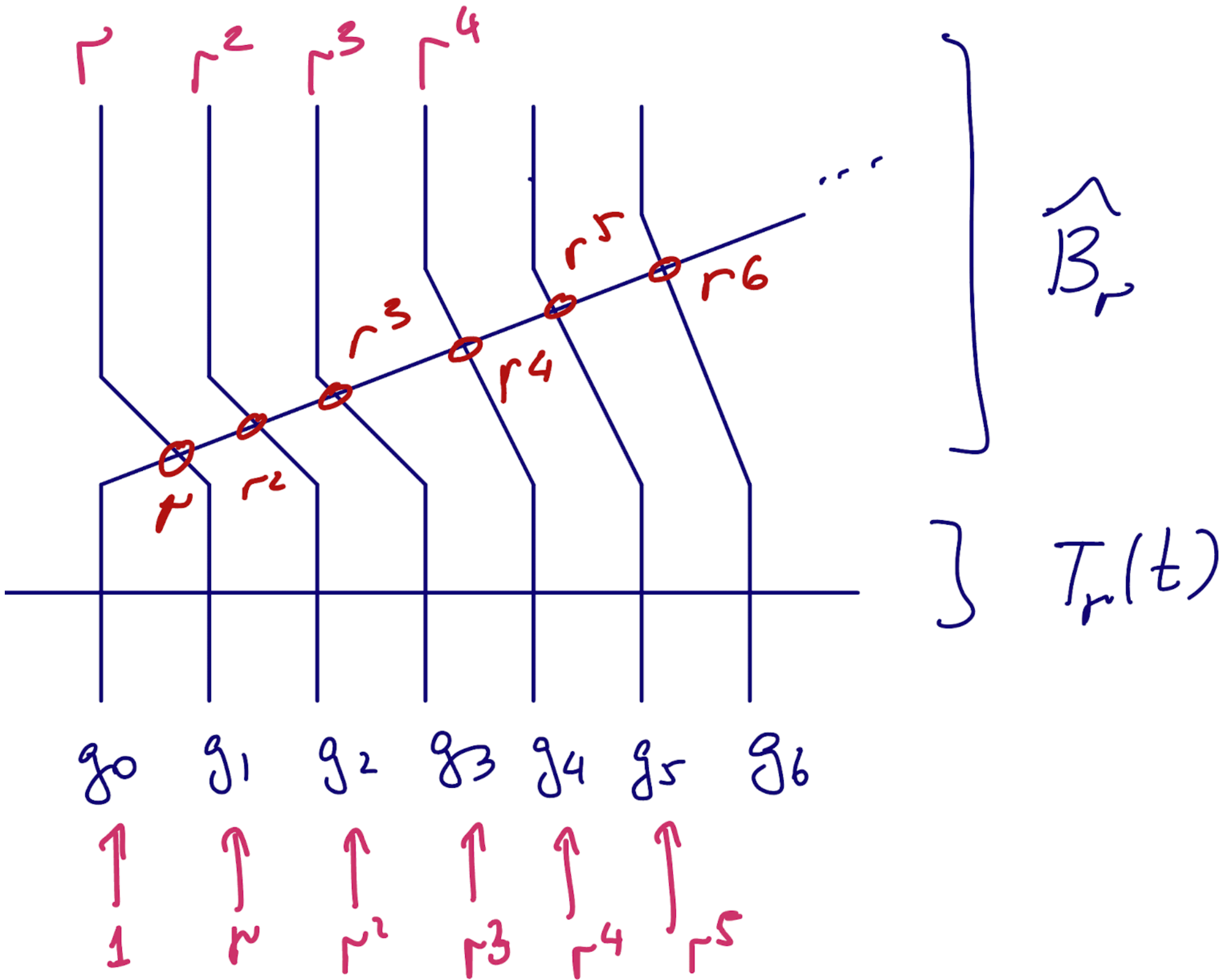
From intertwining to Lax equations for q-TASEP

Let $a_n = r^n$. Let us organize the tower of applications of B_1, B_2, B_3, \dots



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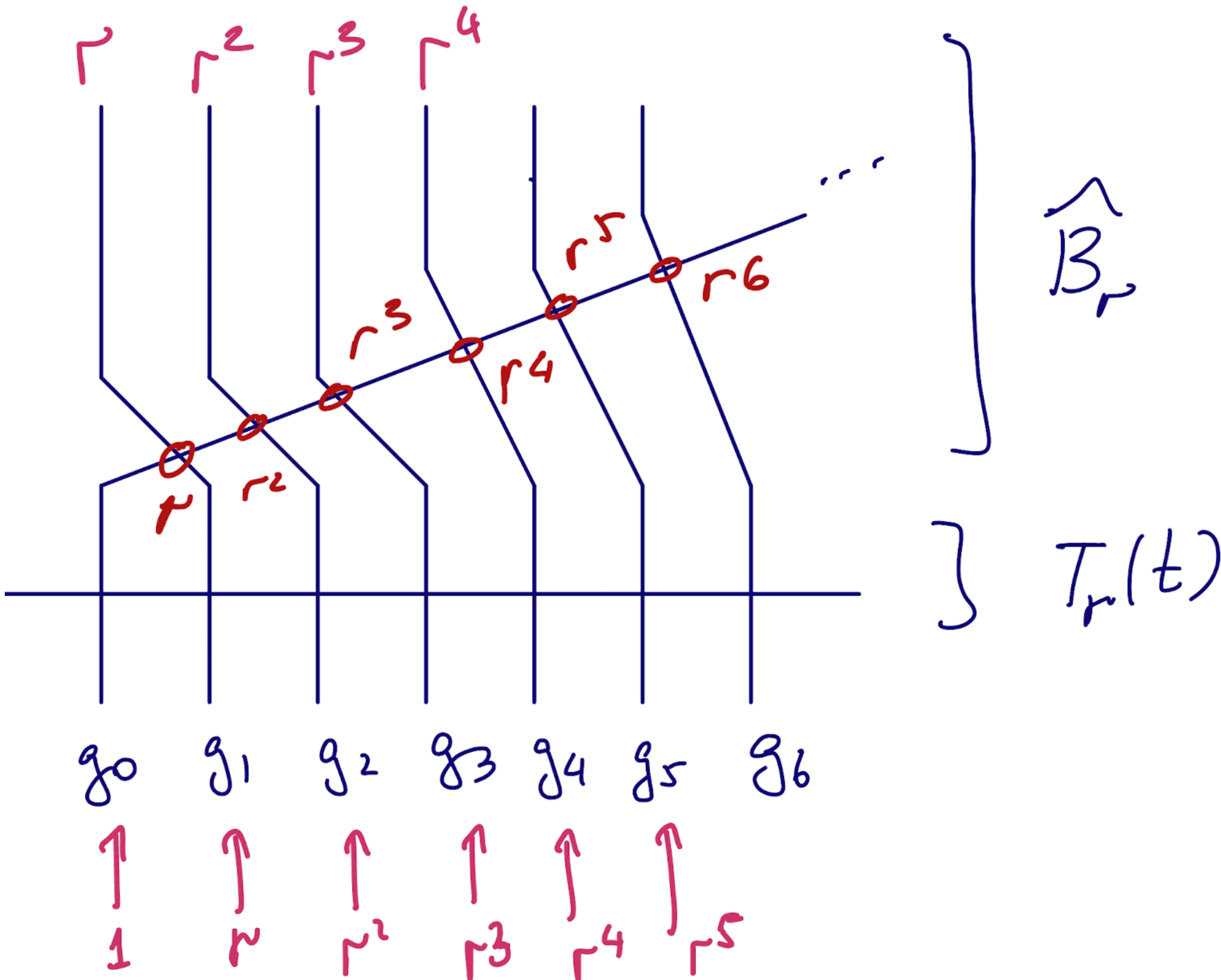
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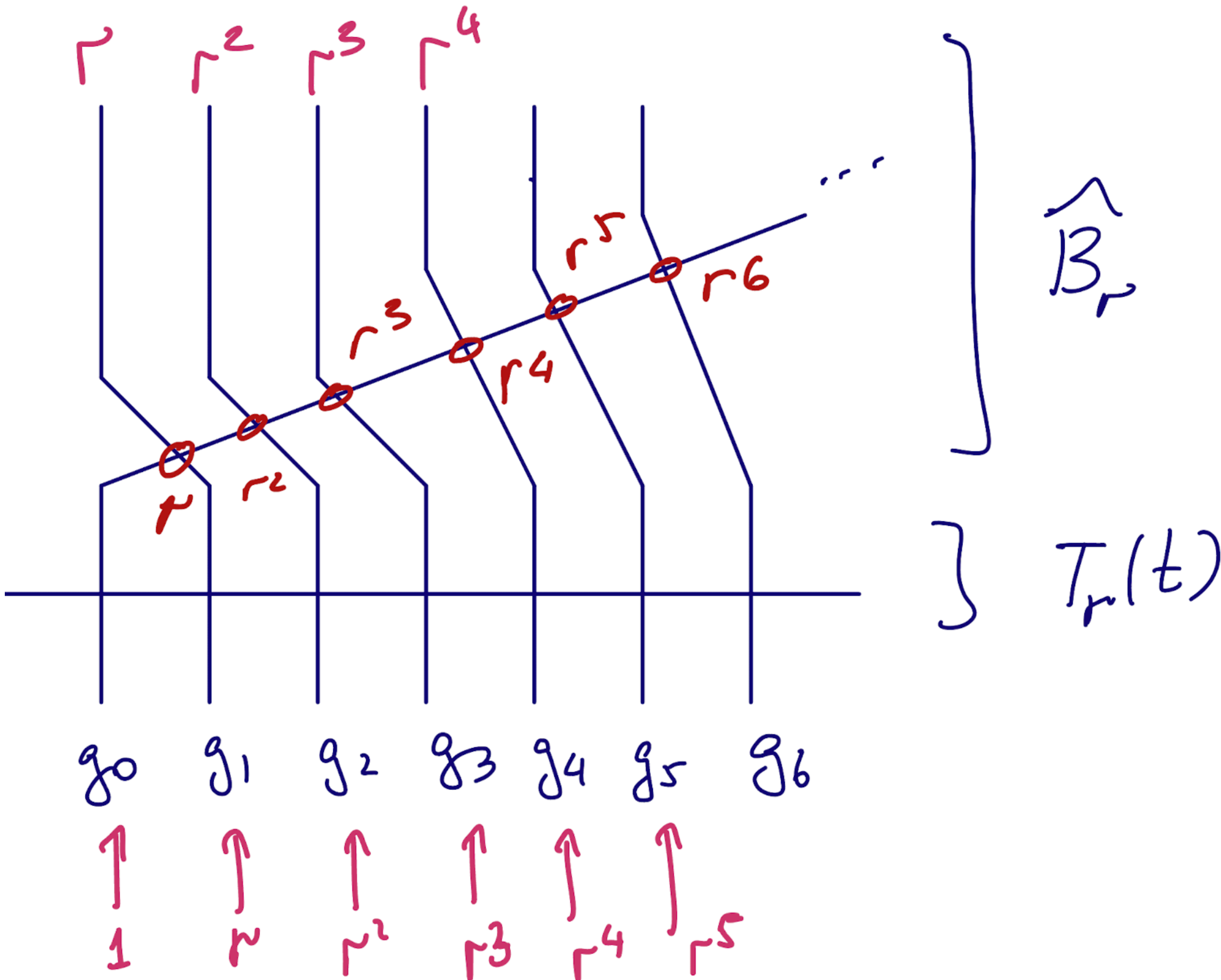
Take a continuous time Poisson limit of $(\hat{B}_r)^{\tau/(1-r)}$. We get a Markov semigroup $B(\tau)$, and intertwining

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(details on $B(\tau)$ later)

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Note: Outside the q -Hahn case $u_2/u_1 = s_2/s_1$, this cross-vertex system B_r does **not** preserve the empty configuration!

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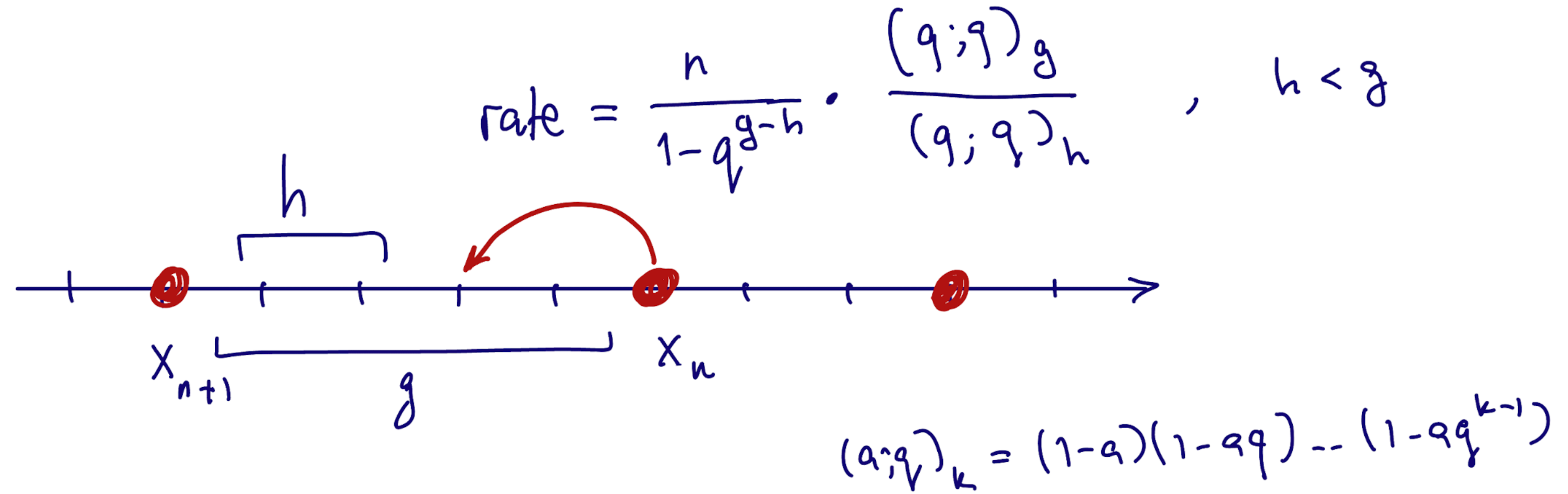
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- For expectations, this means $t \mathbb{E}_y \left[(\mathsf{T}F)(x(t)) \right] = \mathsf{B} \mathbb{E}_y \left[F(x(t)) \right] - \mathbb{E}_y \left[(\mathsf{B}F)(x(t)) \right]$ for any function of the configuration (note, first term in LHS vanishes if $y = \textit{step}$)

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- The Lax equation should give access to all multipoint observables for q-TASEP, but this information is not that easy to extract... [Quastel-Remenik 2019] show KP equations for KPZ fixed point

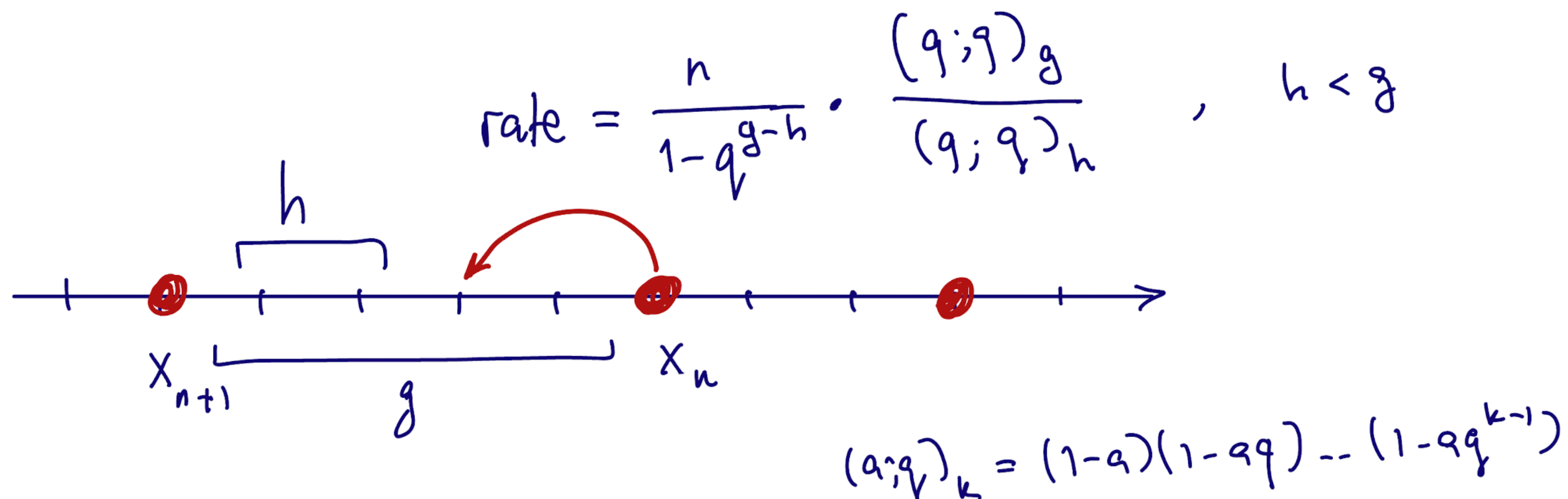
The backwards dynamics B for q-TASEP and TASEP

The backwards dynamics $B(\tau)$ is a continuous time Markov process on particle configurations which are densely packed to the left. Each particle x_n jumps back independently in continuous time:

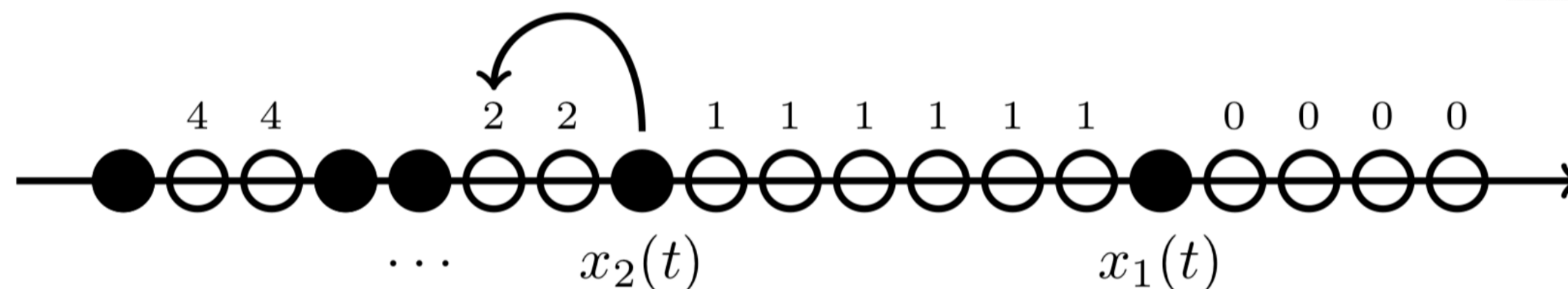


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Case $q = 0$

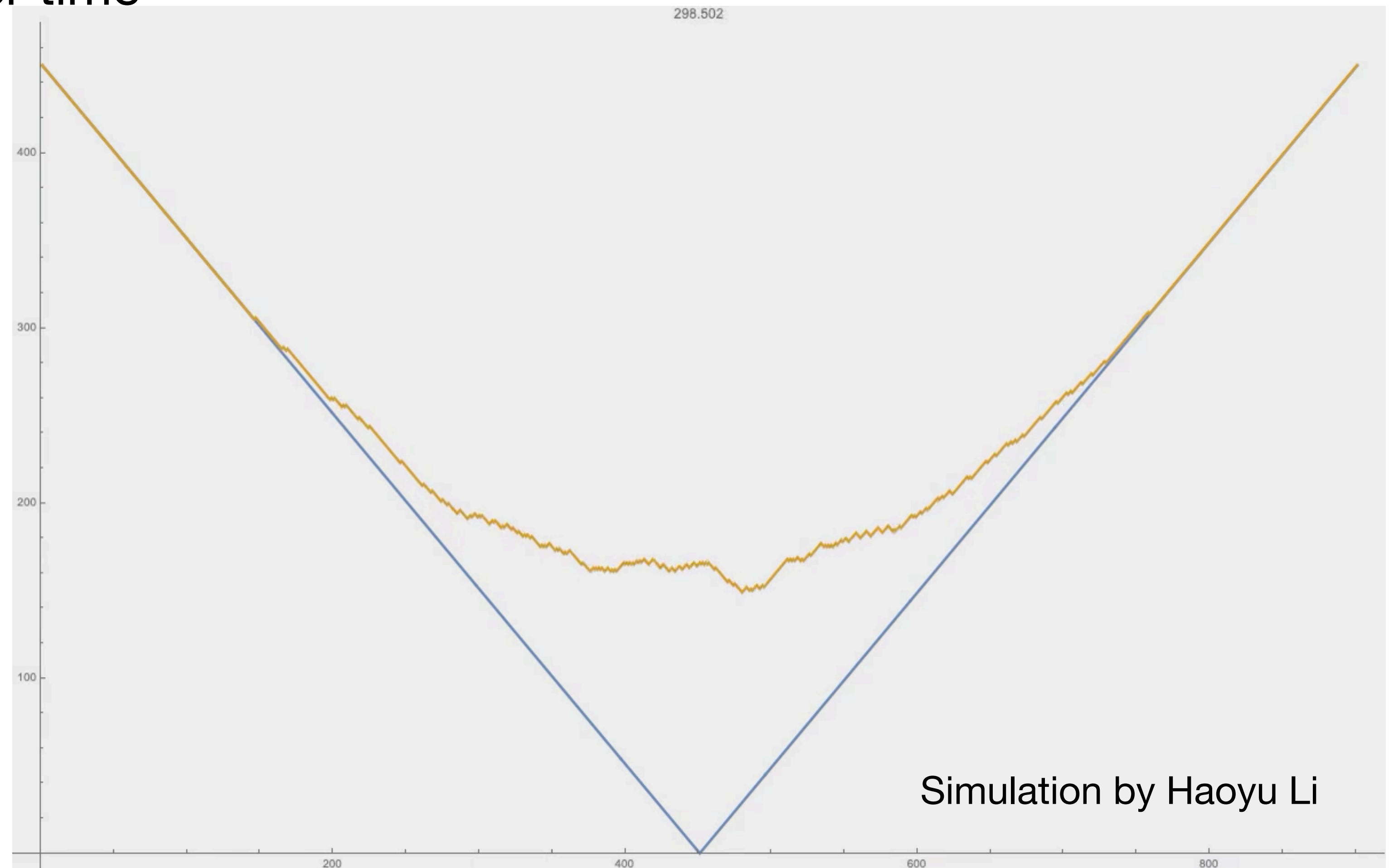


- Each hole has an independent exponential clock with rate equal to the number m of particles to its right, $\mathbb{P}(\text{wait} > s) = e^{-m \cdot s}$, $s > 0$.
- When the clock at a hole rings, the leftmost of the particles that are to the right of the hole instantaneously jumps into this hole
- Because total rate of jump is proportional to the size of the gap, this is a discrete space inhomogeneous version of the Hammersley process **[Hammersley '72], [Aldous-Diaconis '95]**

Running TASEP back in time

Theorem [P.-Saenz '19]. $\delta_{step}T(t)B(\tau) = \delta_{step}T(e^{-\tau}t)$, which means that if we run TASEP from the step (densely packed) initial configuration, and then run the backwards process, then the result is a TASEP distribution at an earlier time

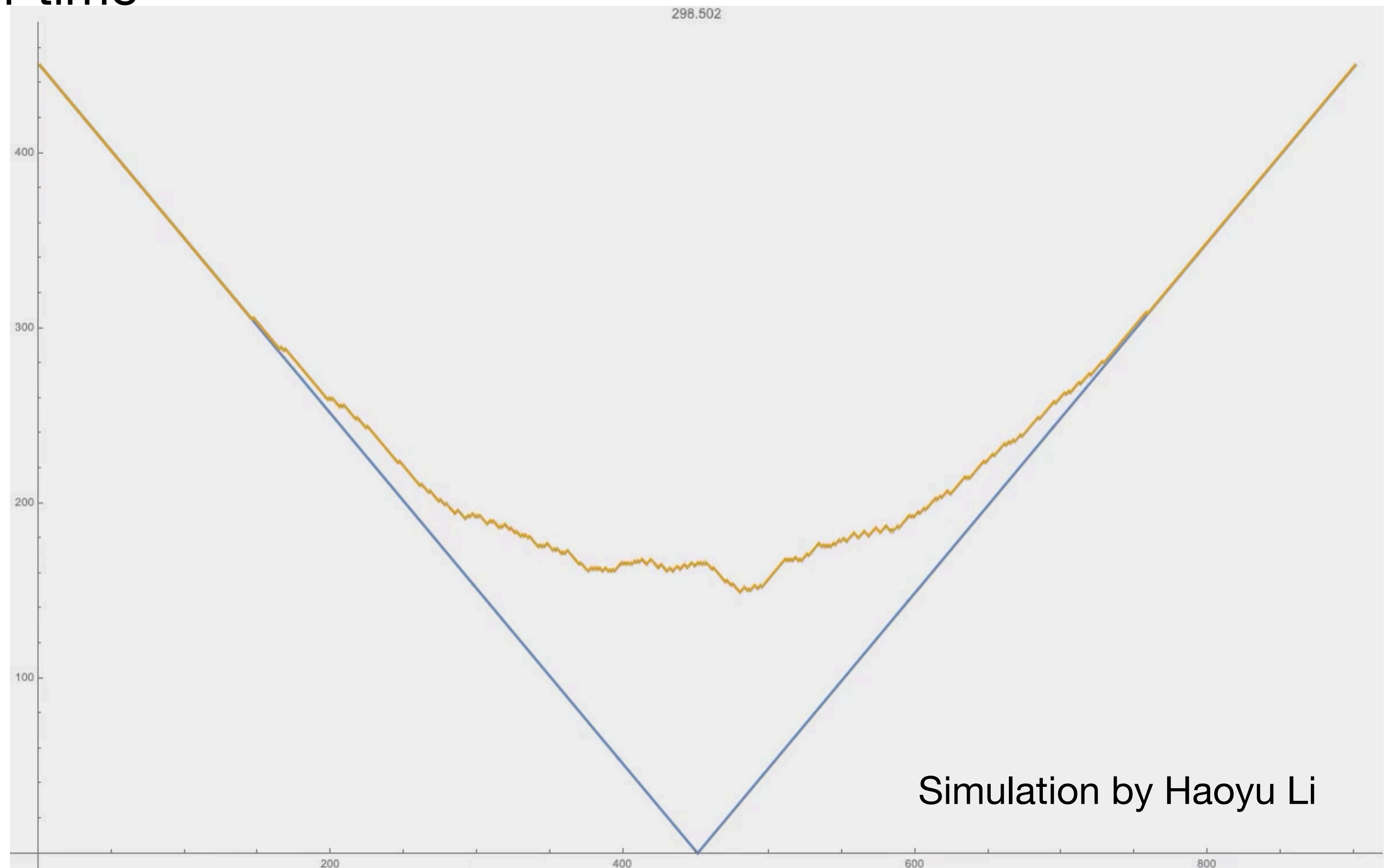
TASEP as a growth process
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For questions and remarks

Coupling and rewriting history

Bijection of the Yang-Baxter equation

Let A, B be finite sets and $\sum_{a \in A} w(a) = \sum_{b \in B} w(b)$ (with positive terms)

A **bijection (coupling)** of this identity is a family of transition probabilities

$p(a \rightarrow b)$ and $p'(b \rightarrow a)$, satisfying

$$w(a)p(a \rightarrow b) = w(b)p'(b \rightarrow a)$$

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1	1	0	(maximally dependent)
3	1/3	2/3	

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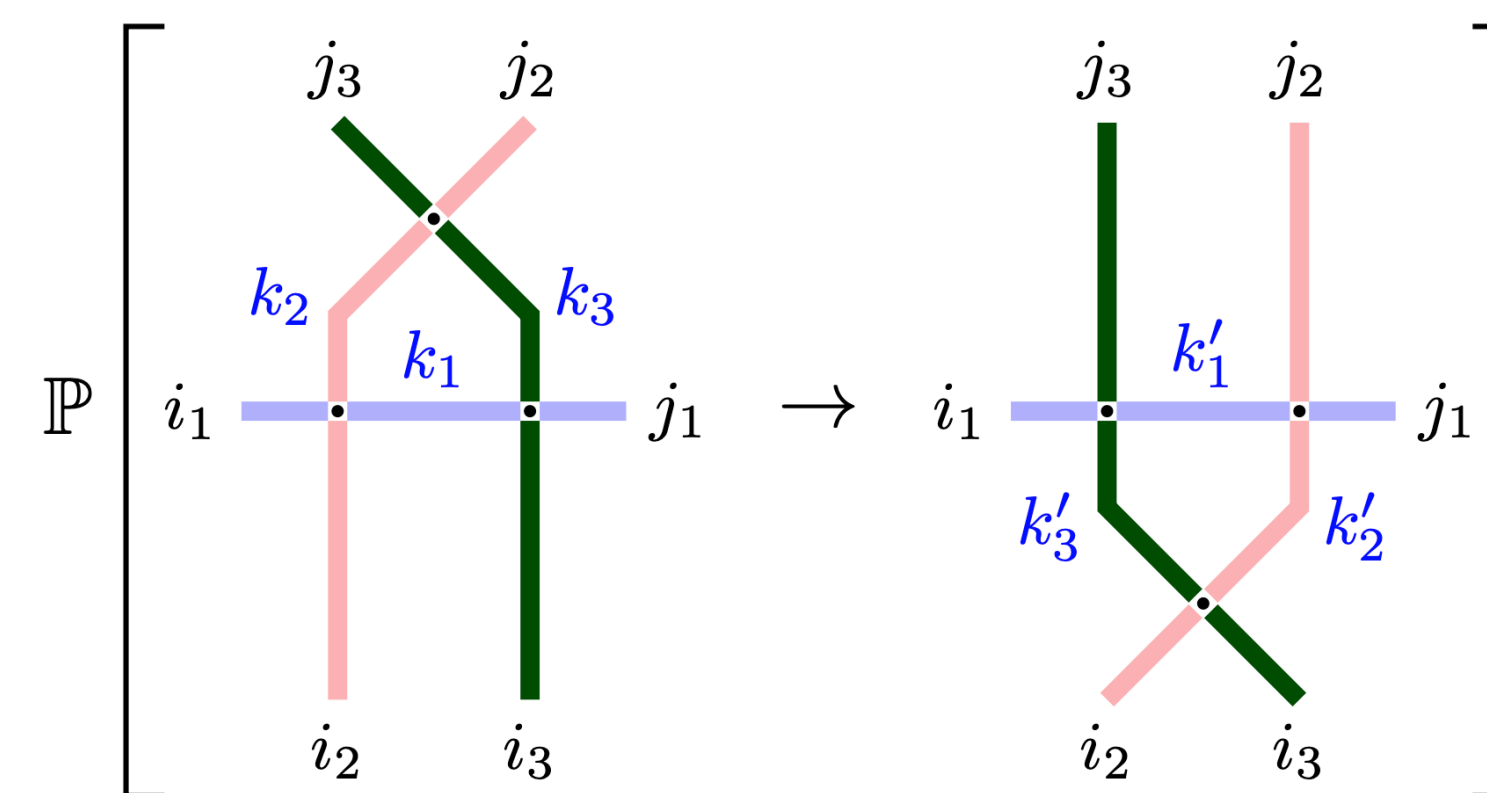
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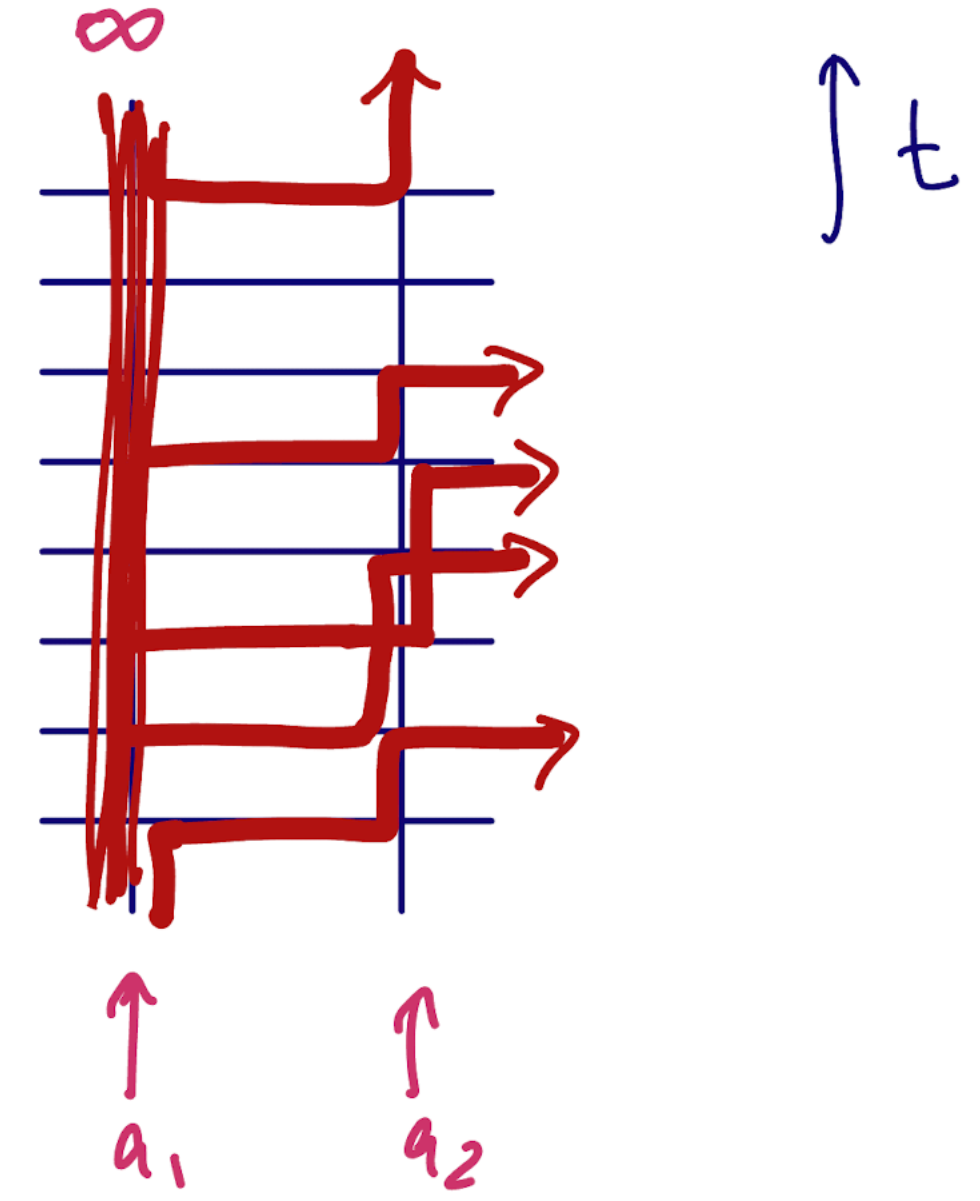
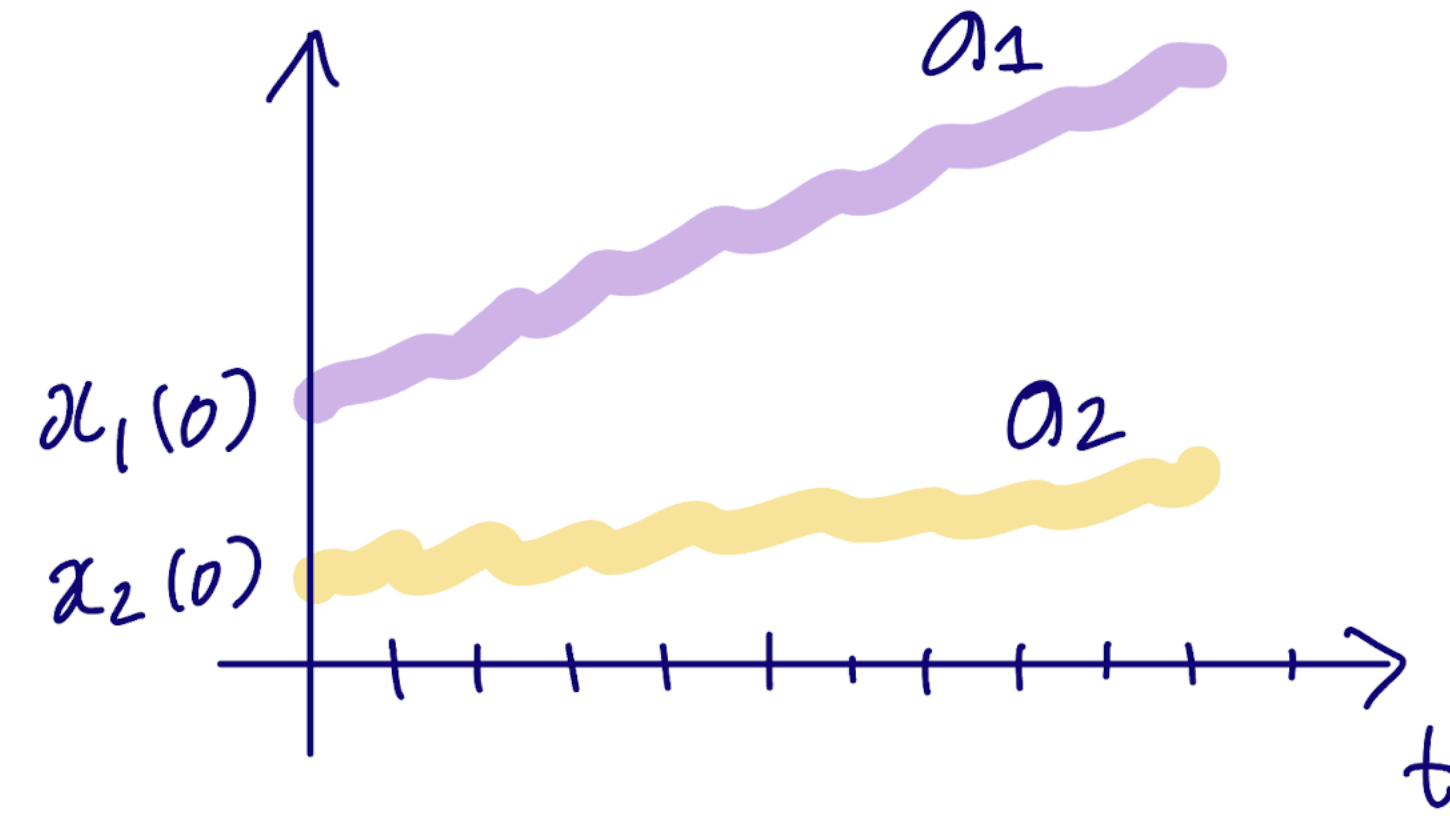
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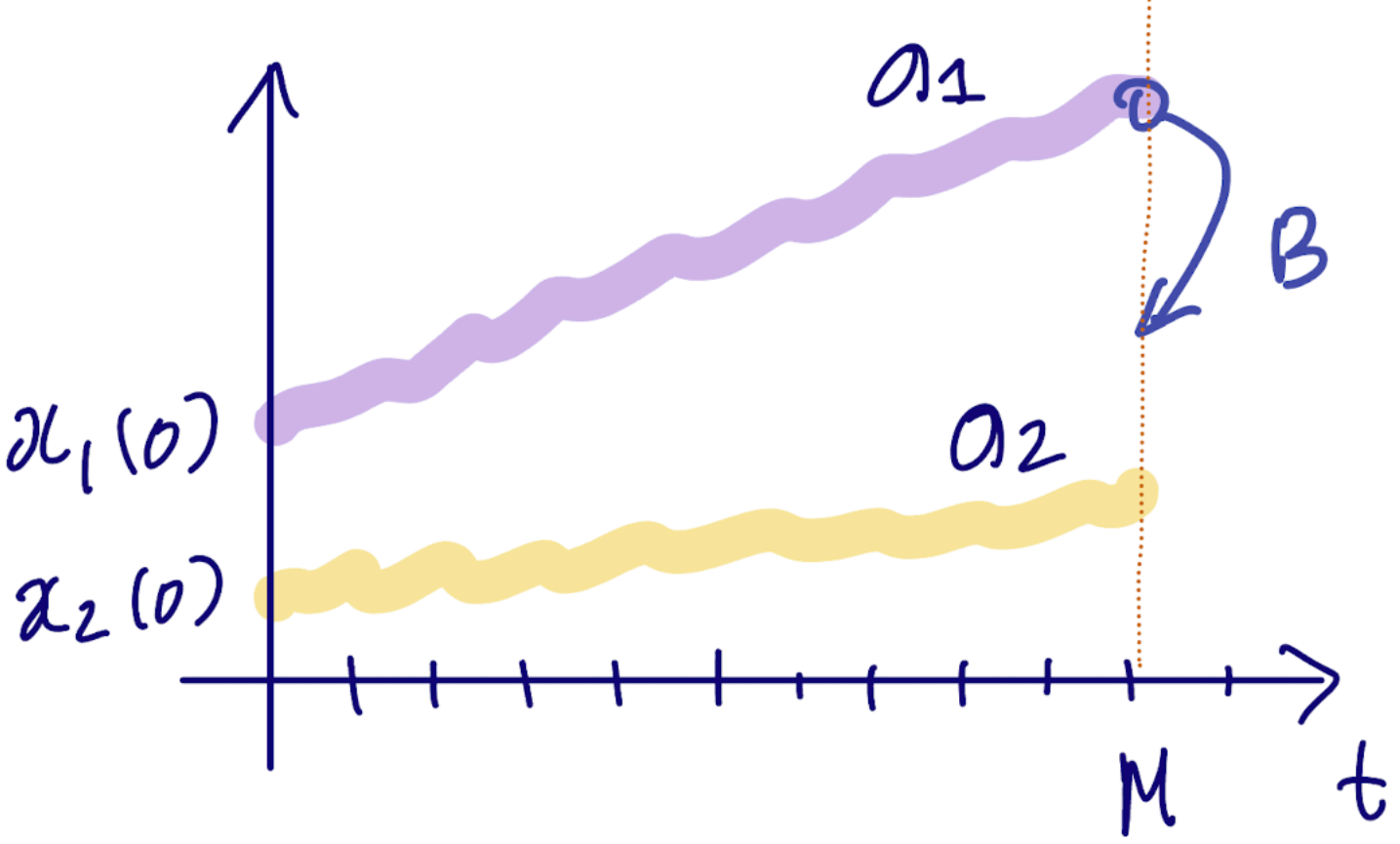


Rewriting history processes

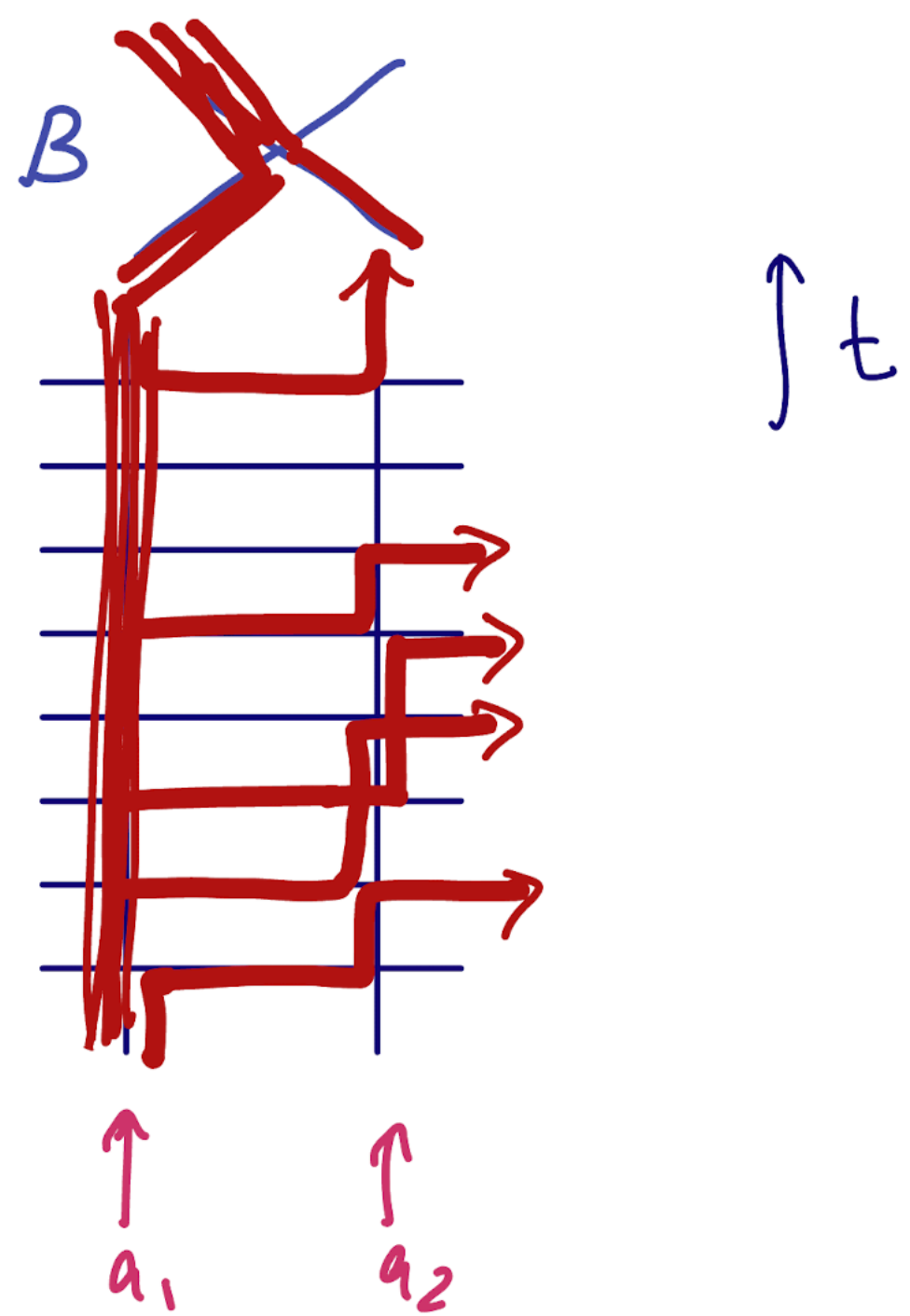
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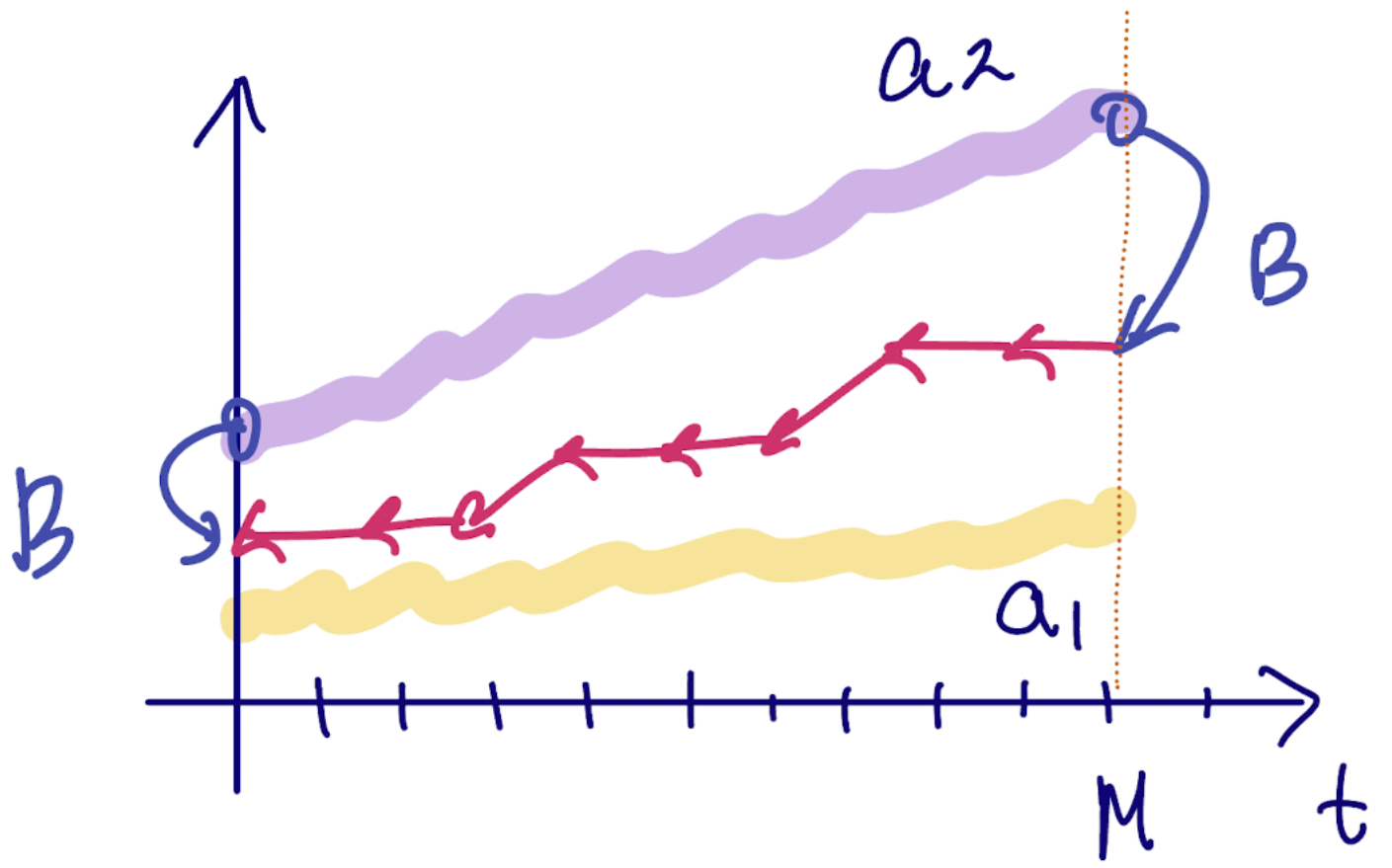
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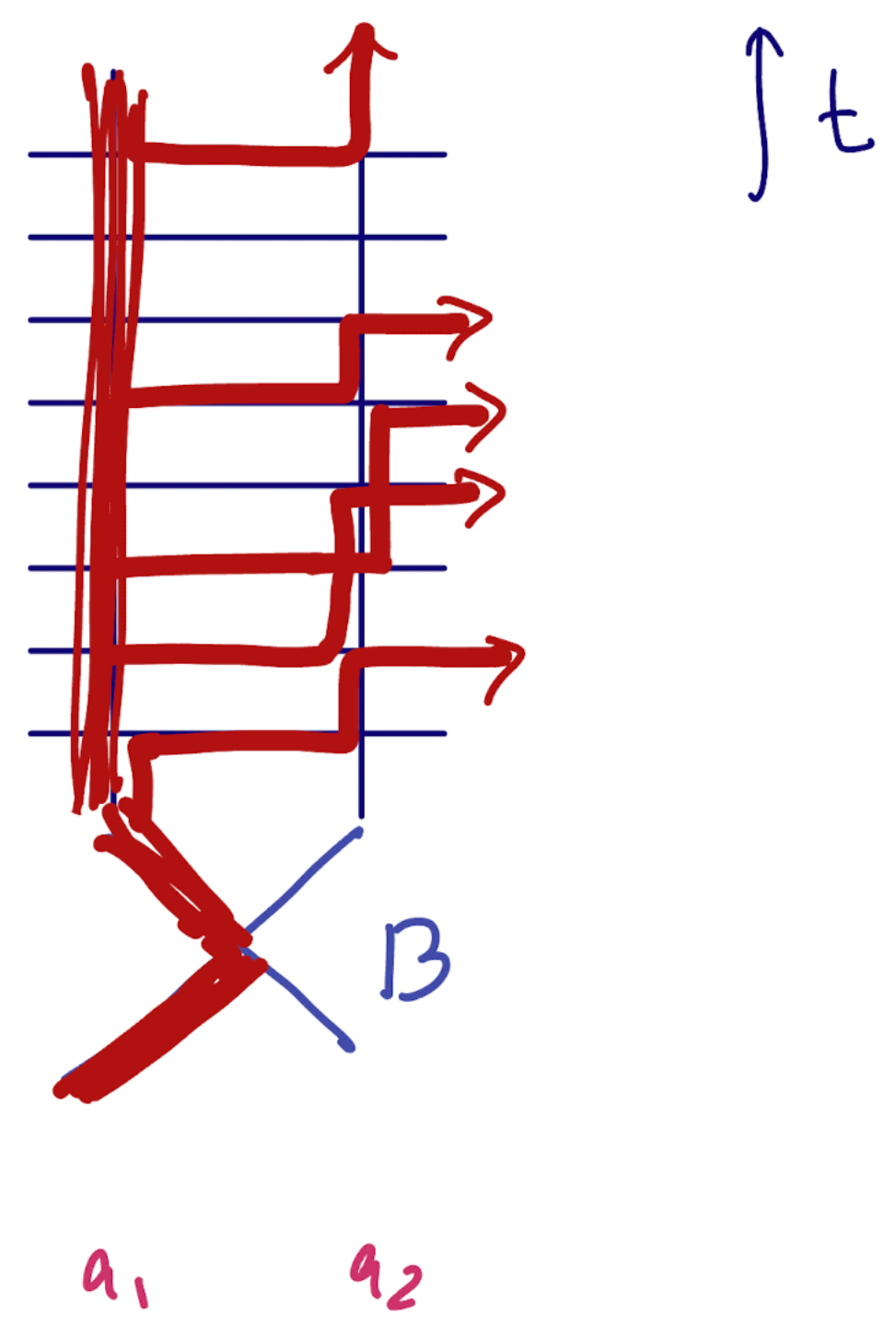
\Leftrightarrow



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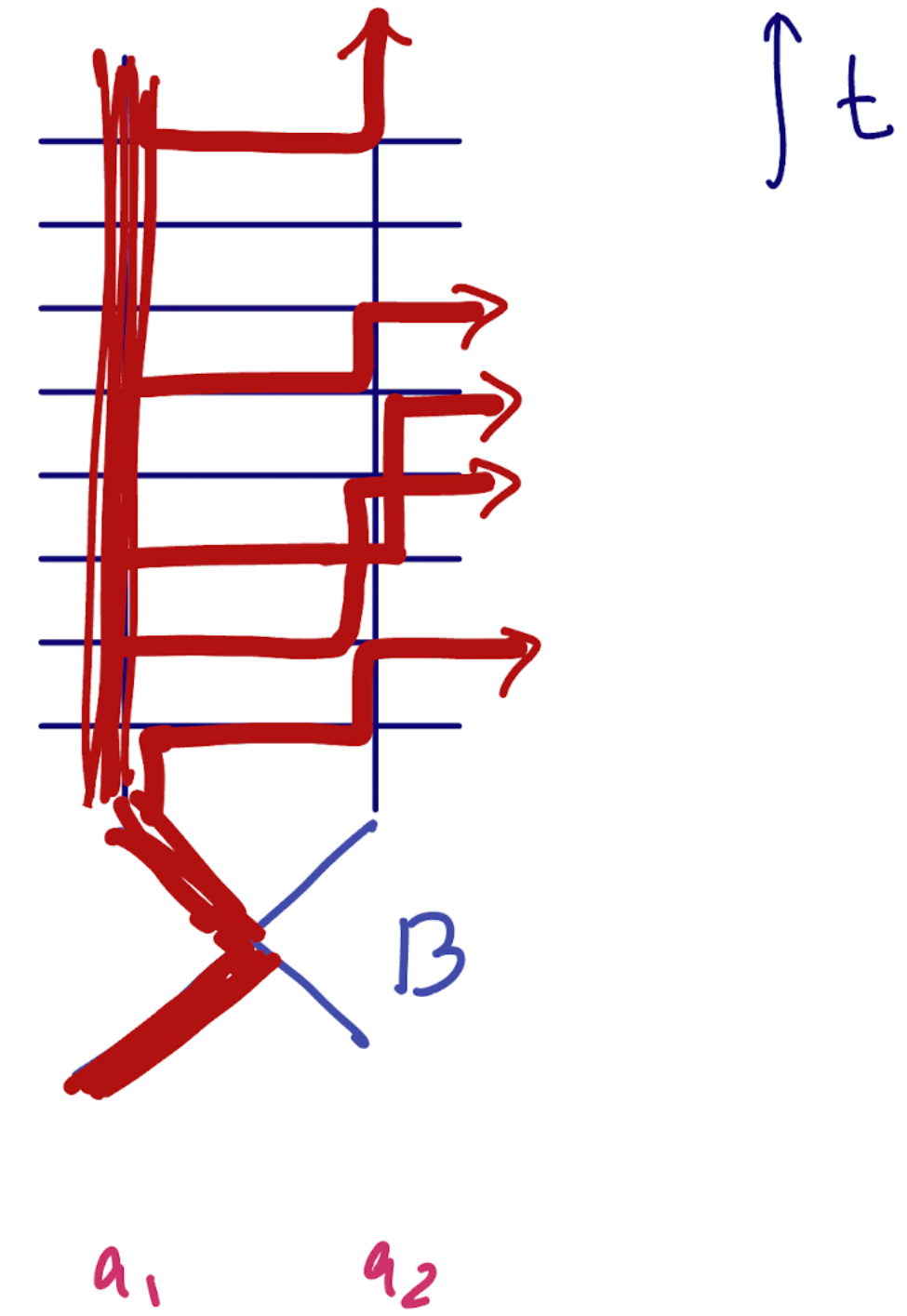
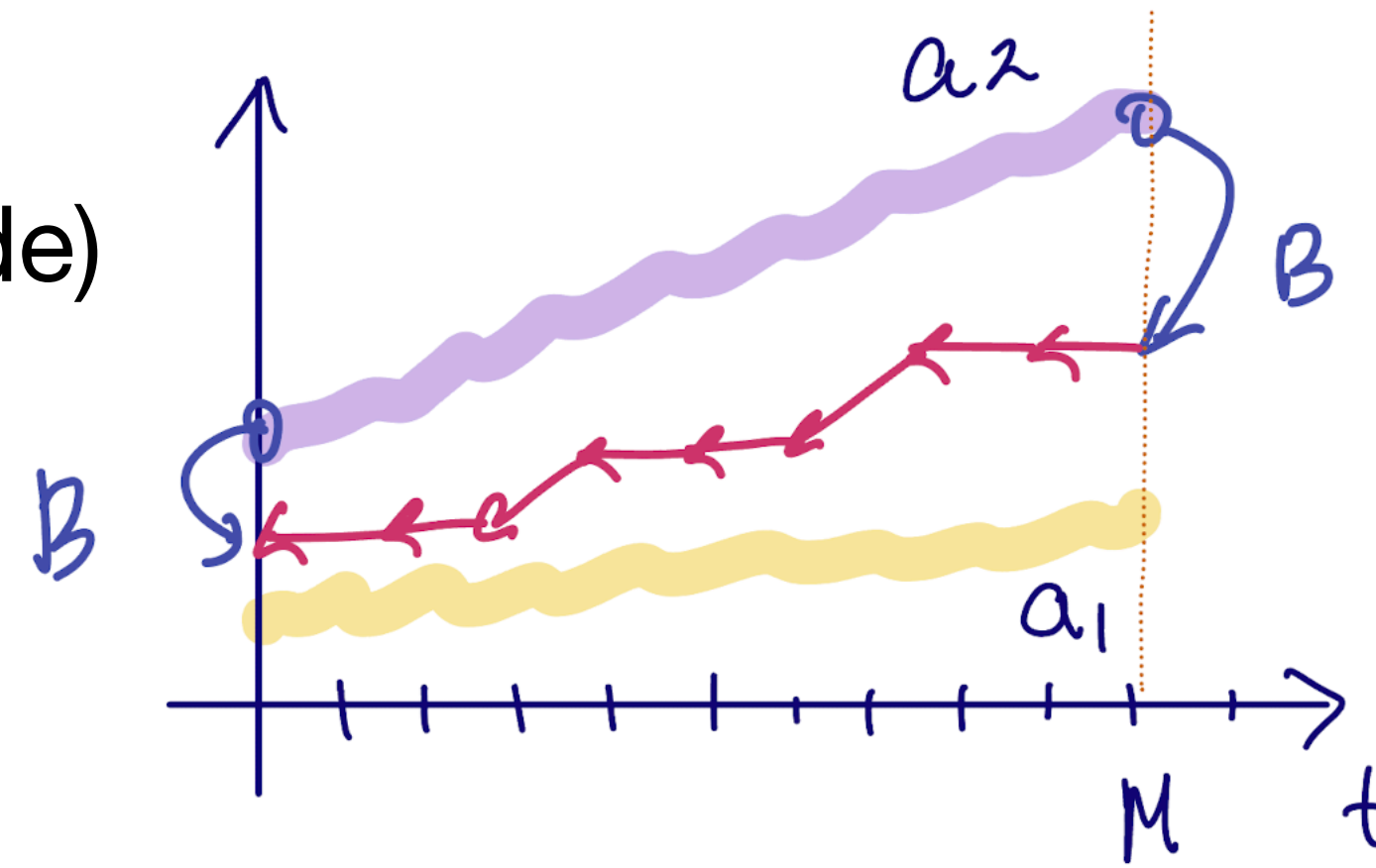
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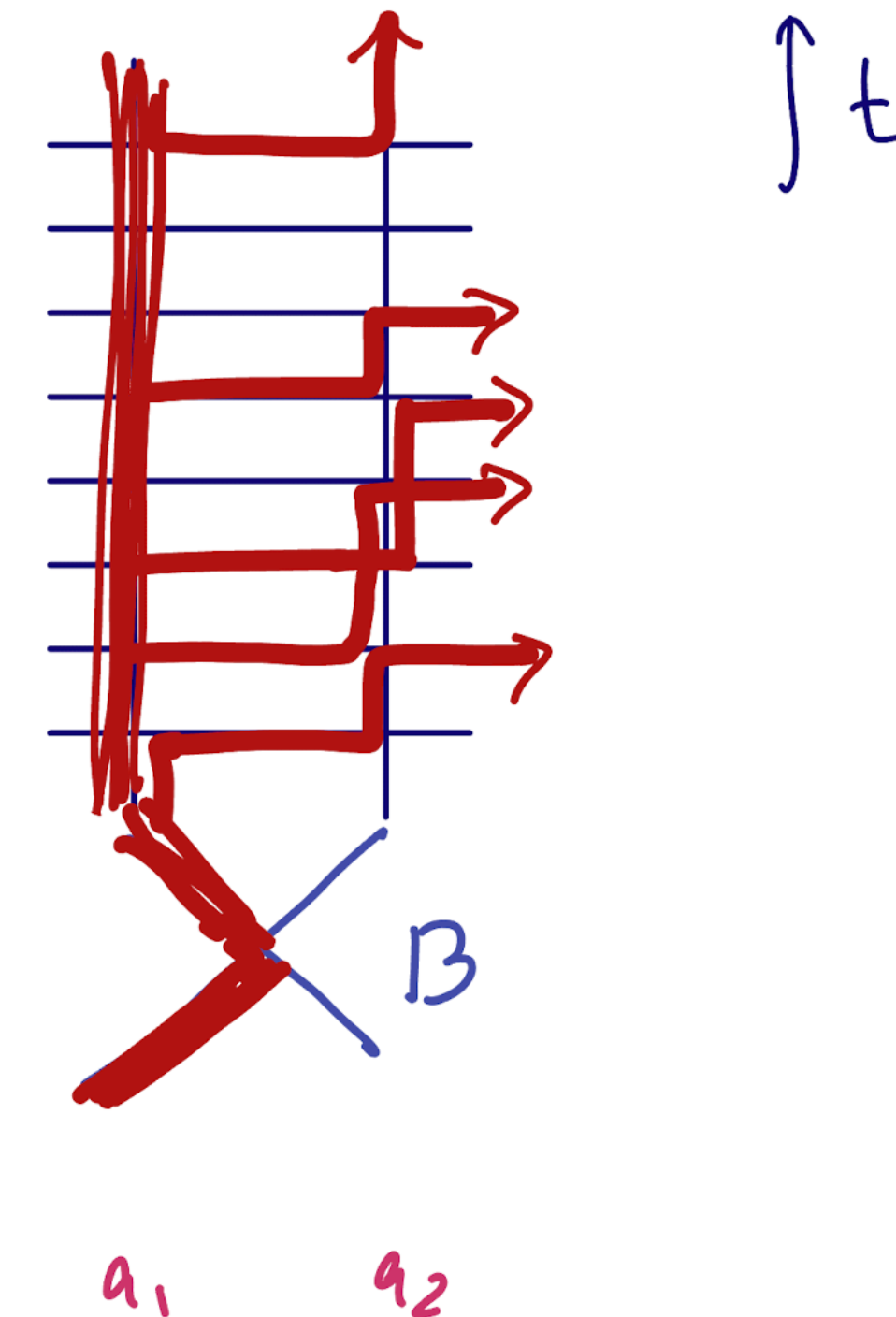
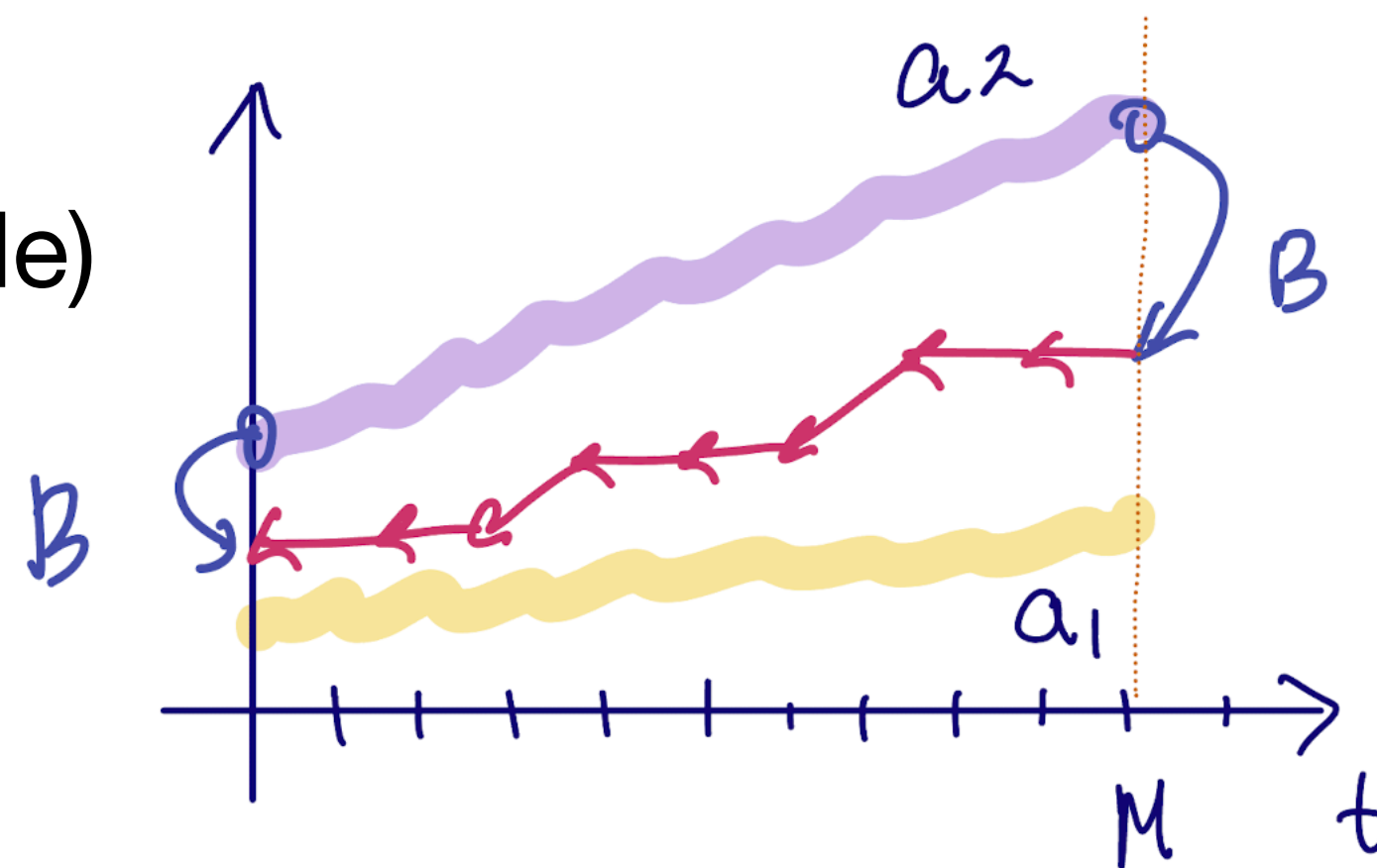
- from future to past (in the figure)
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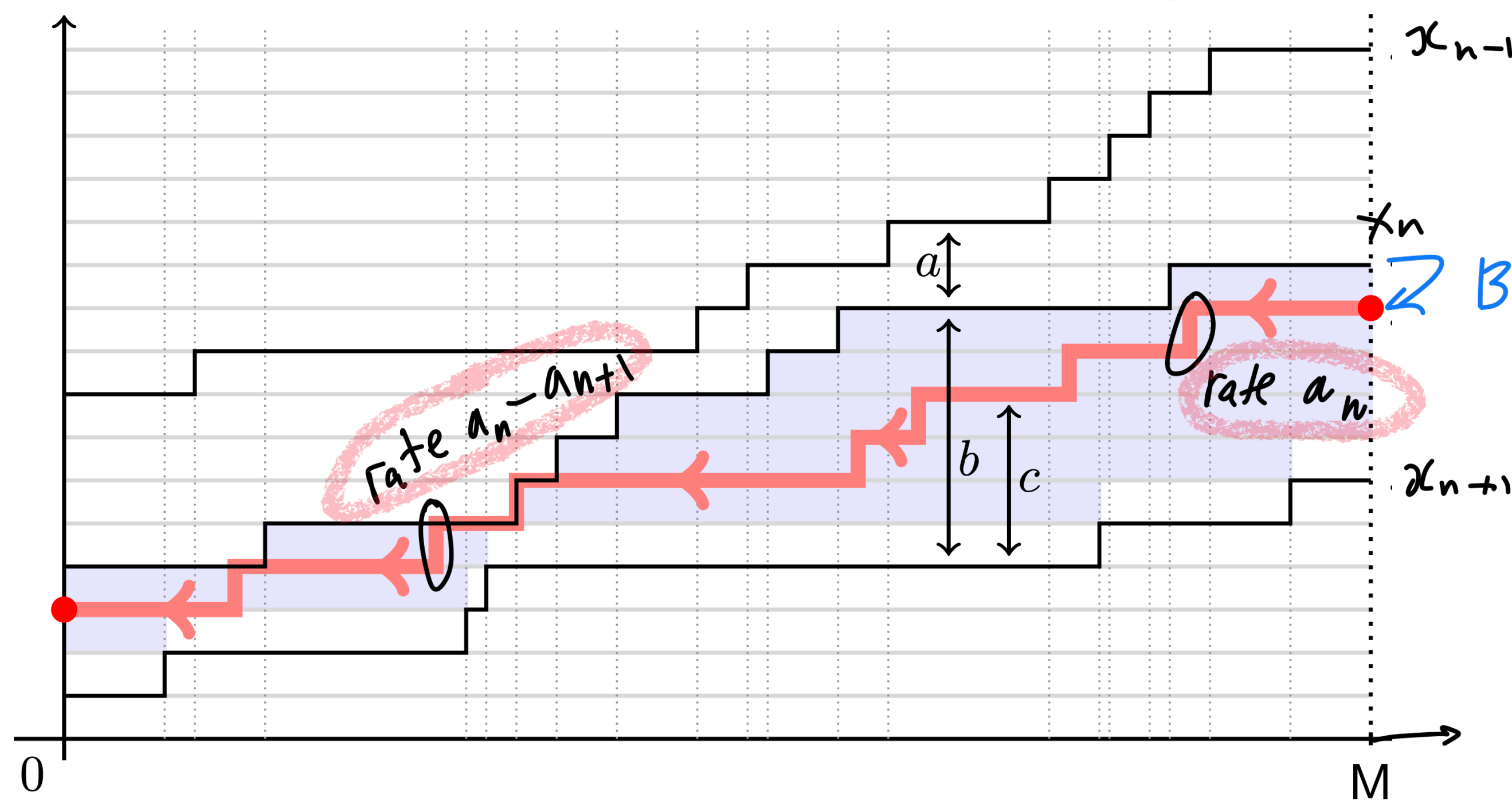
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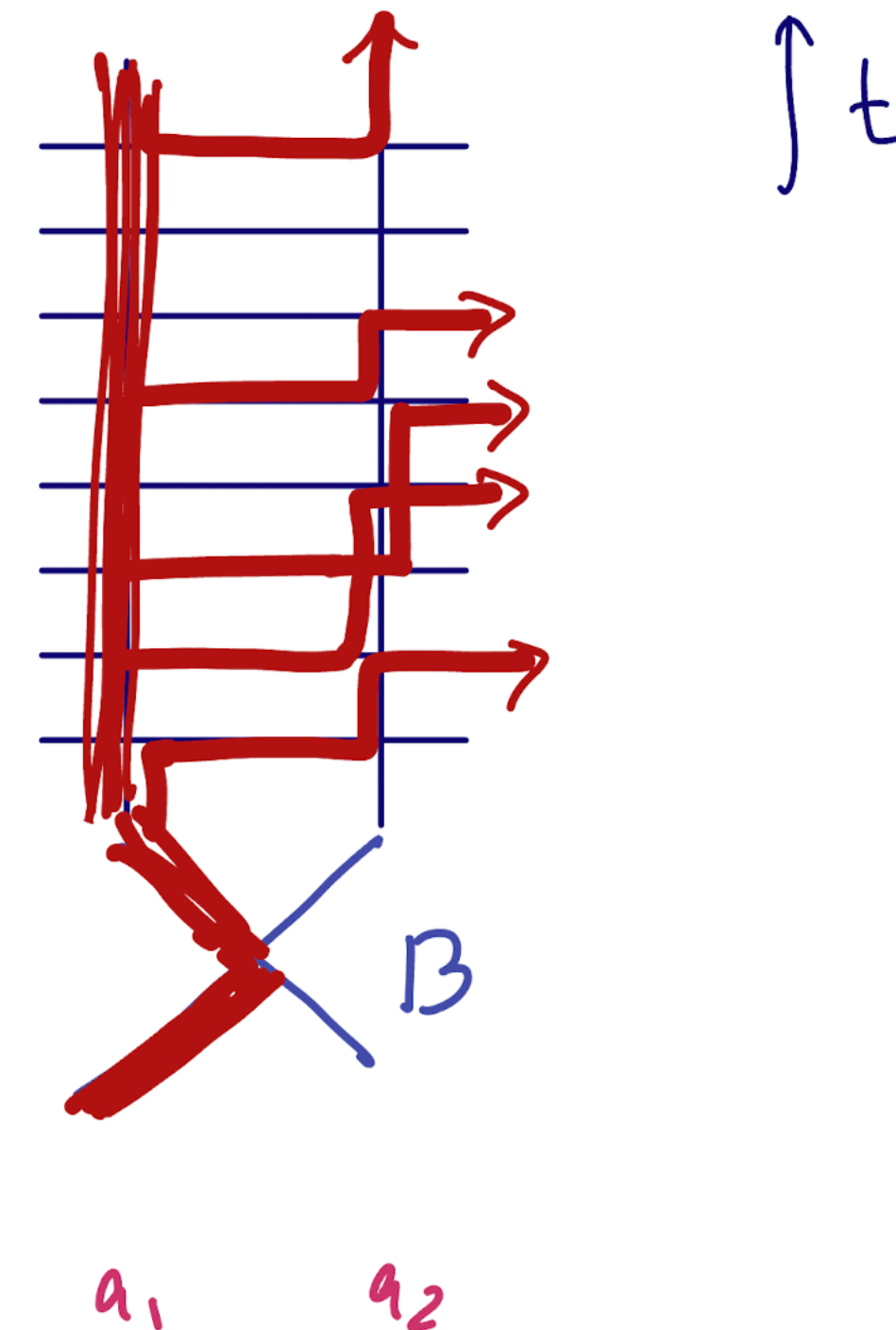
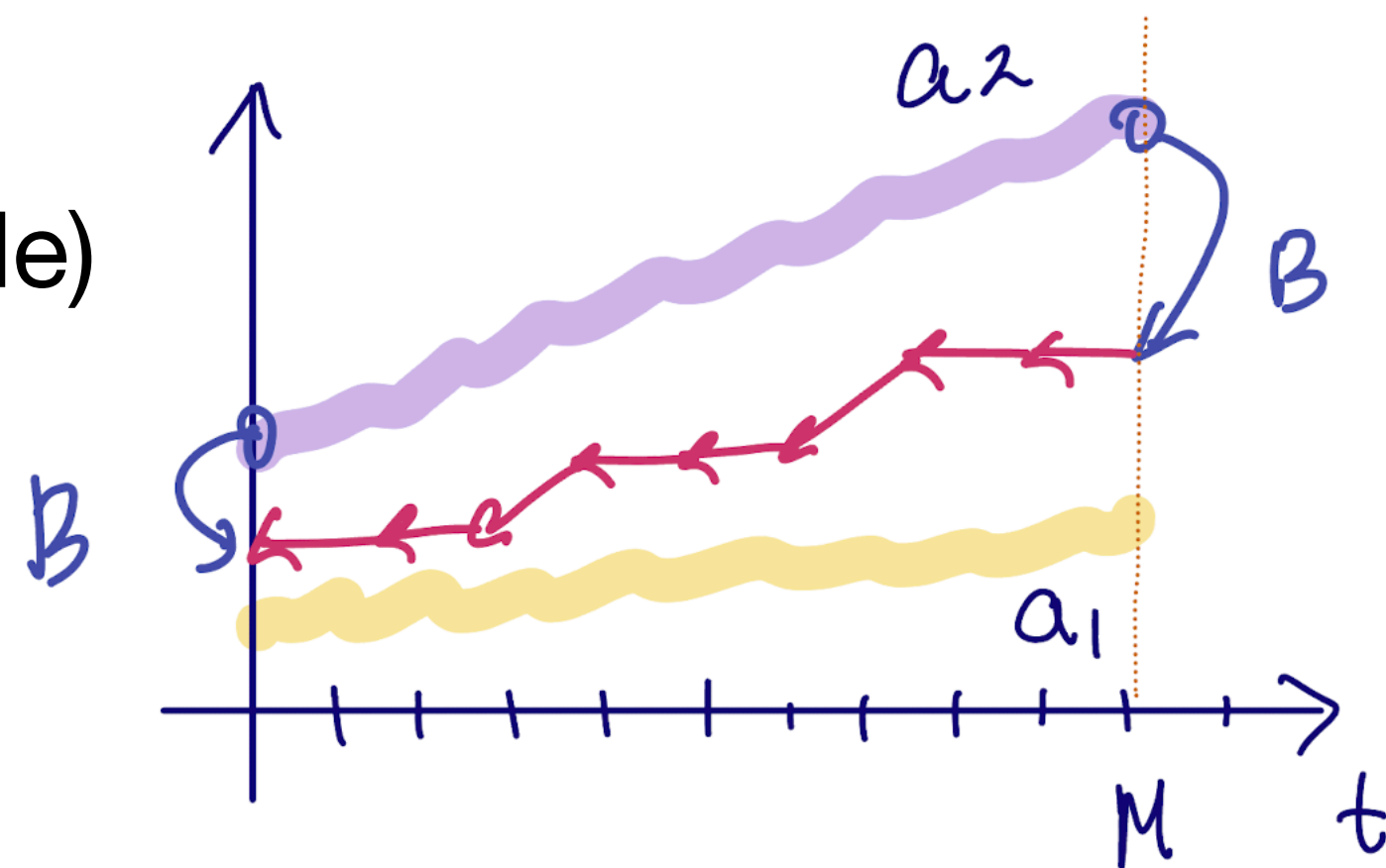
Cont. Time TASEP w. $a_n > a_{n+1}$



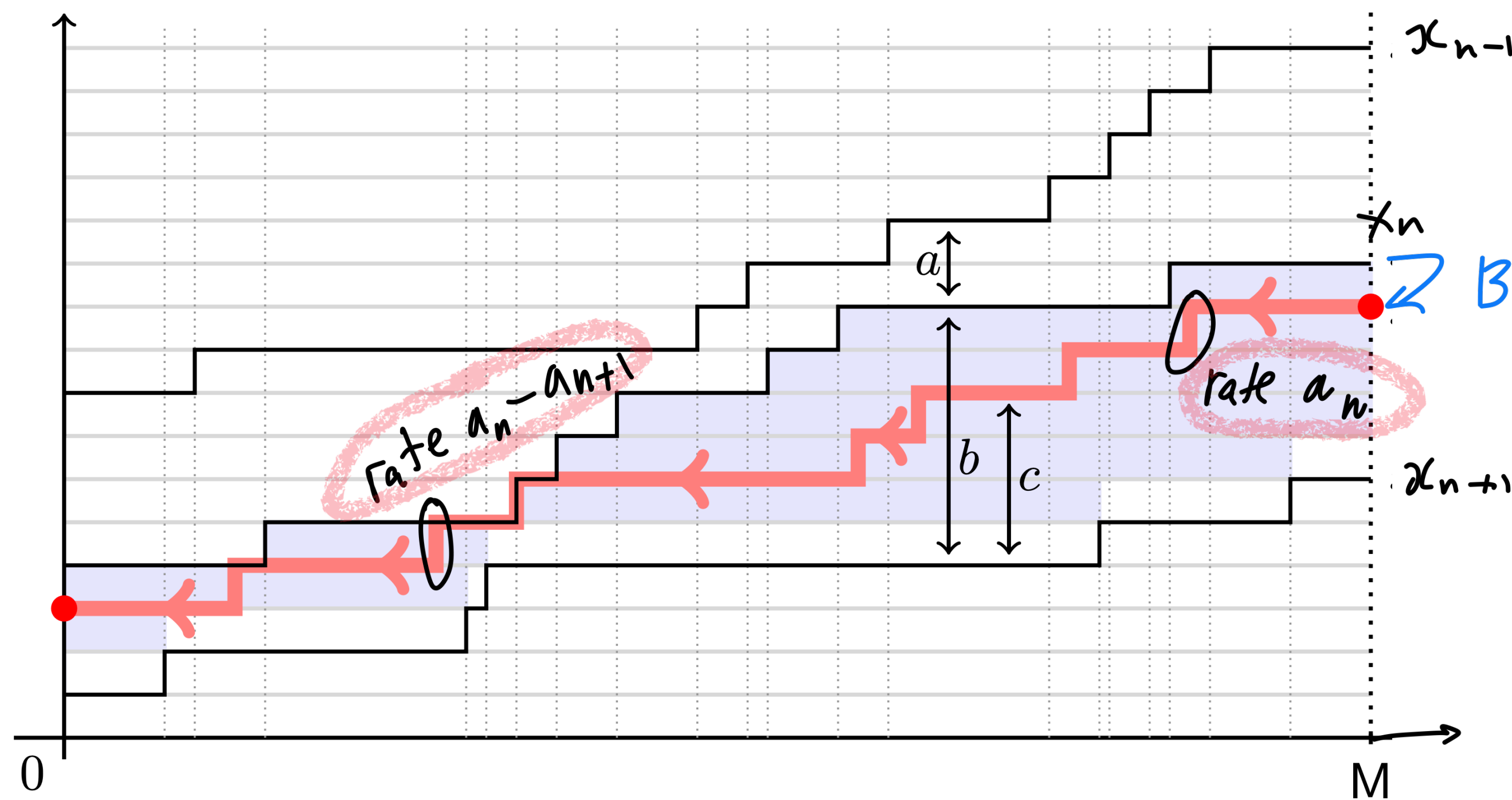
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Theorem [P.-Saenz 2022]. Move x_n back by geometric jump B. Then run a random walk x'_n in the chamber between x_n, x_{n+1} , in reverse time, with jump rates down $a_n - a_{n+1} \mathbf{1}_{b=c}$.

Then the new trajectories are distributed as a TASEP with speeds

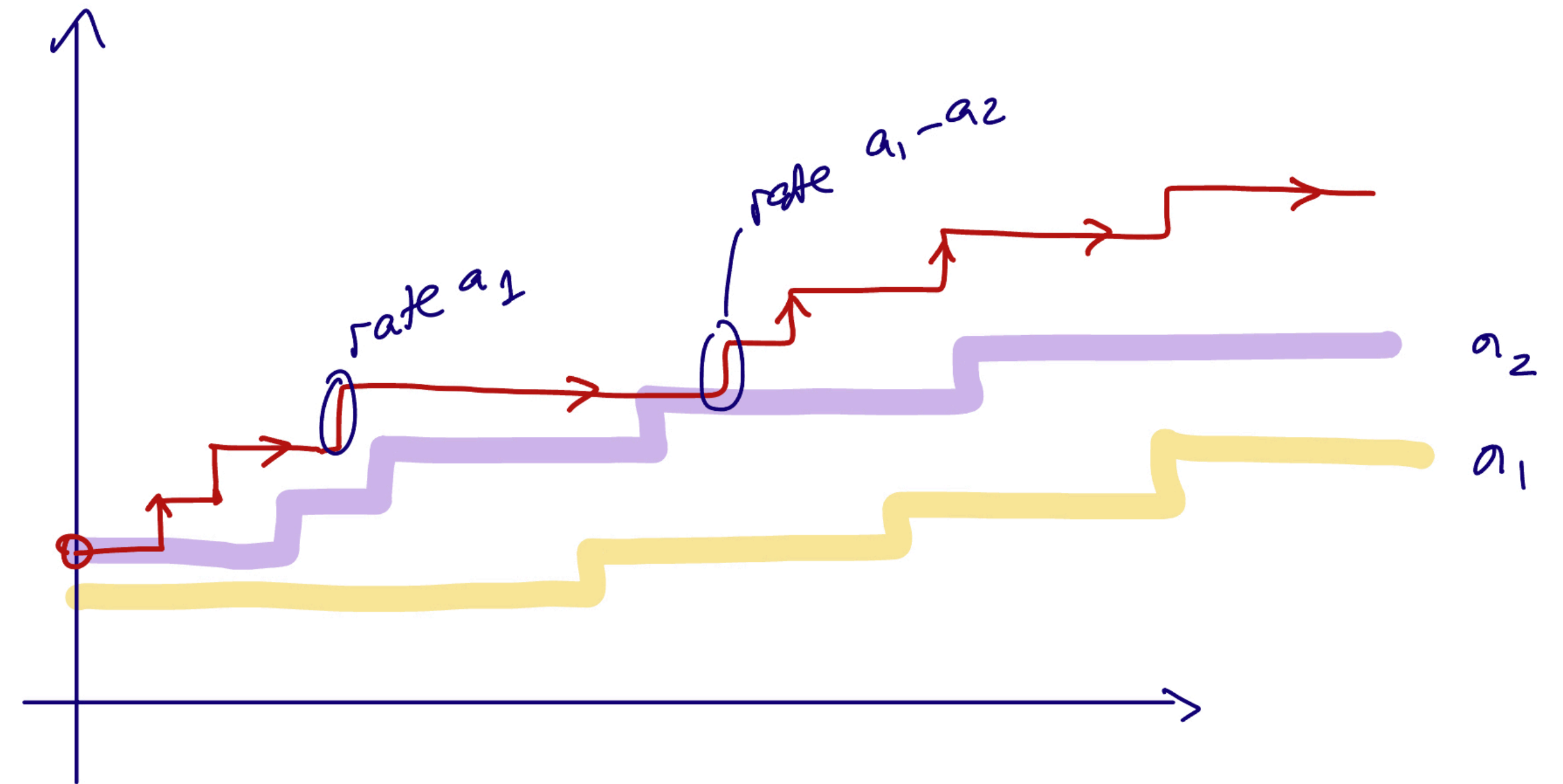
$(\dots, a_{n-1}, a_{n+1}, a_n, a_{n+2}, \dots)$

Last neat (new!) statement about the Poisson process

Rewriting history from past to future for the first particle:

Start from SF system, then the joint distribution of the red and yellow trajectories is **the same** as the FS system, i.e. TASEP with speeds $a_1 > a_2$.

Rewriting history is independent from the second particle (TASEP feature only)

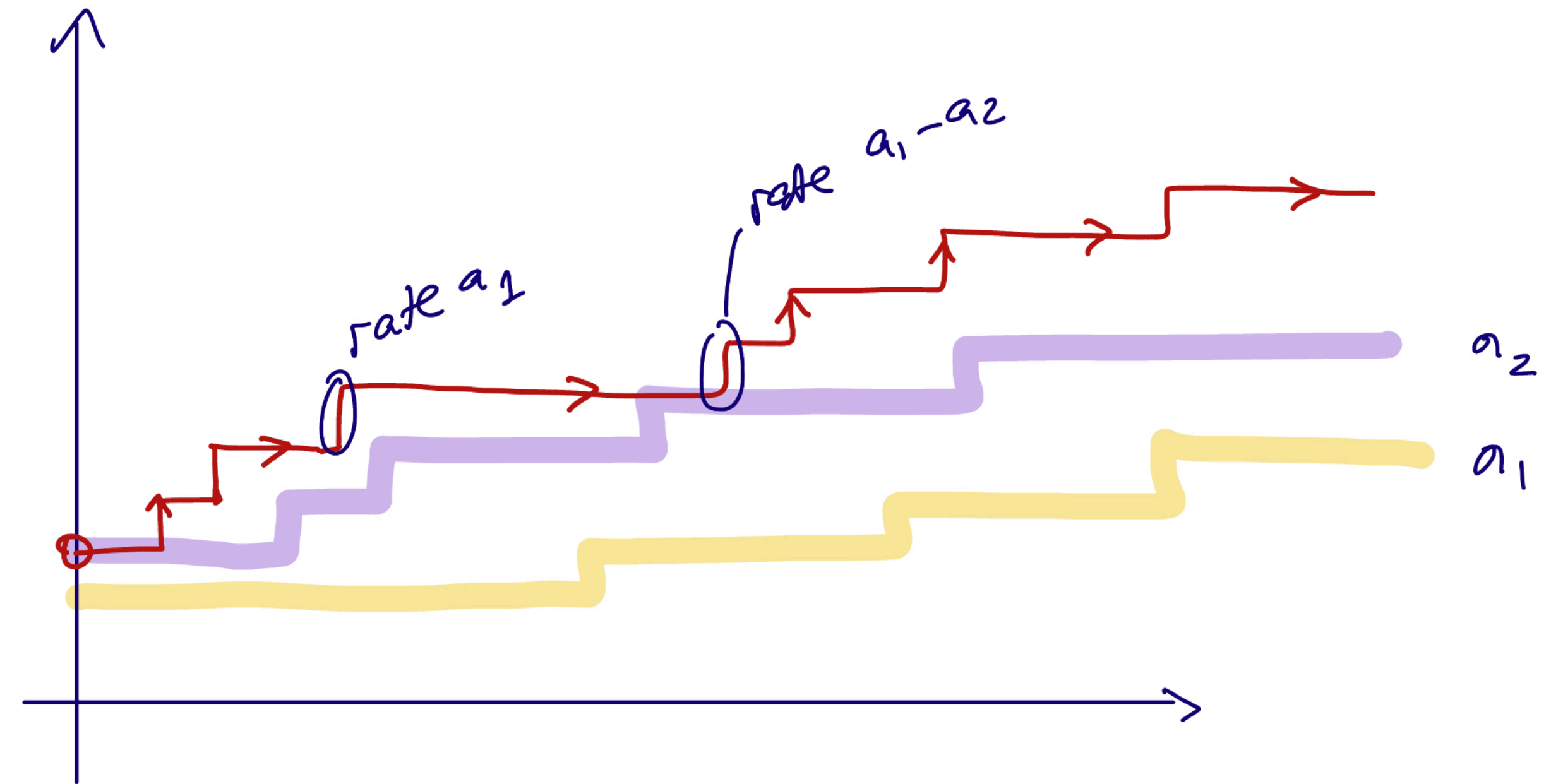


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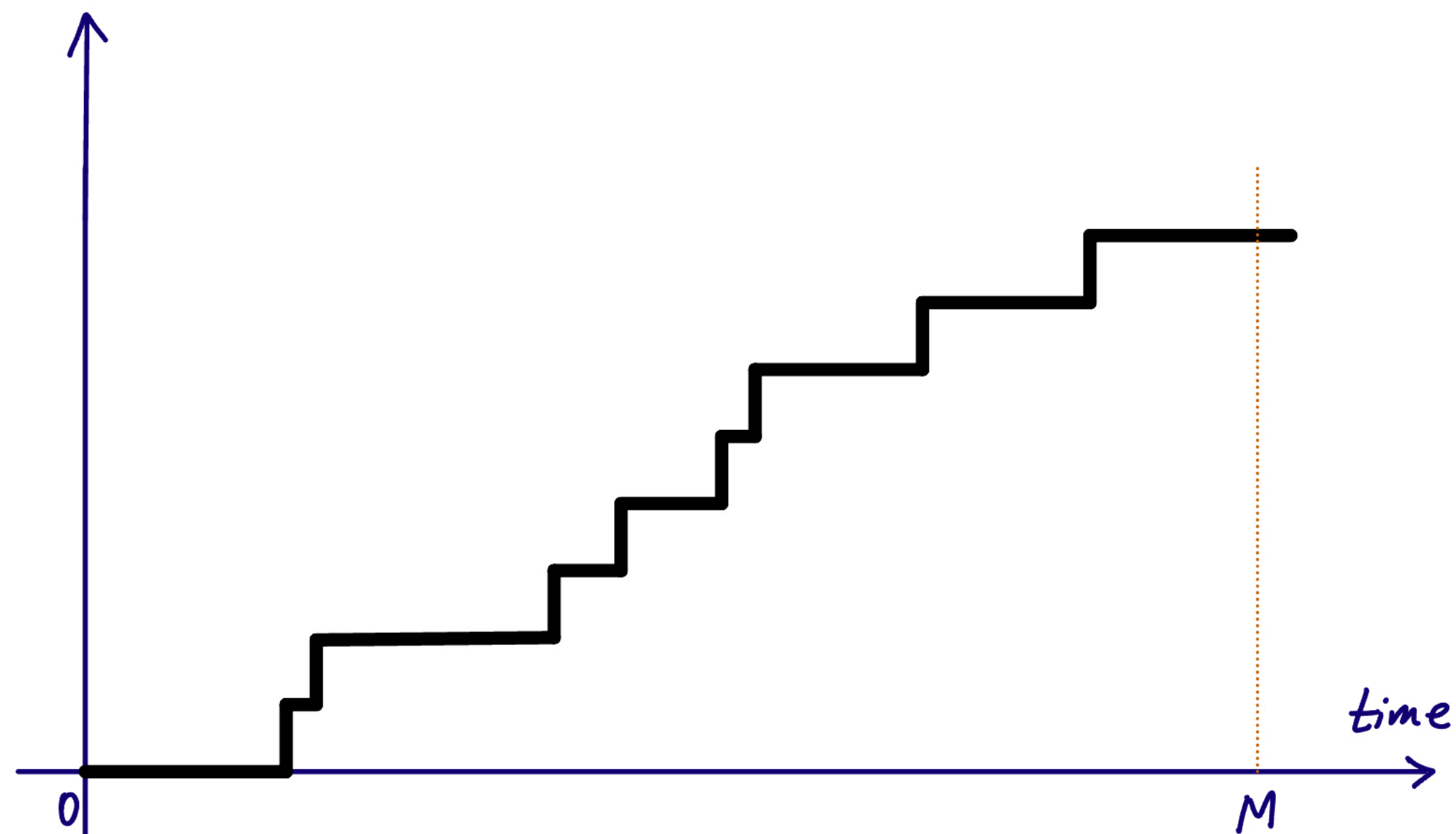
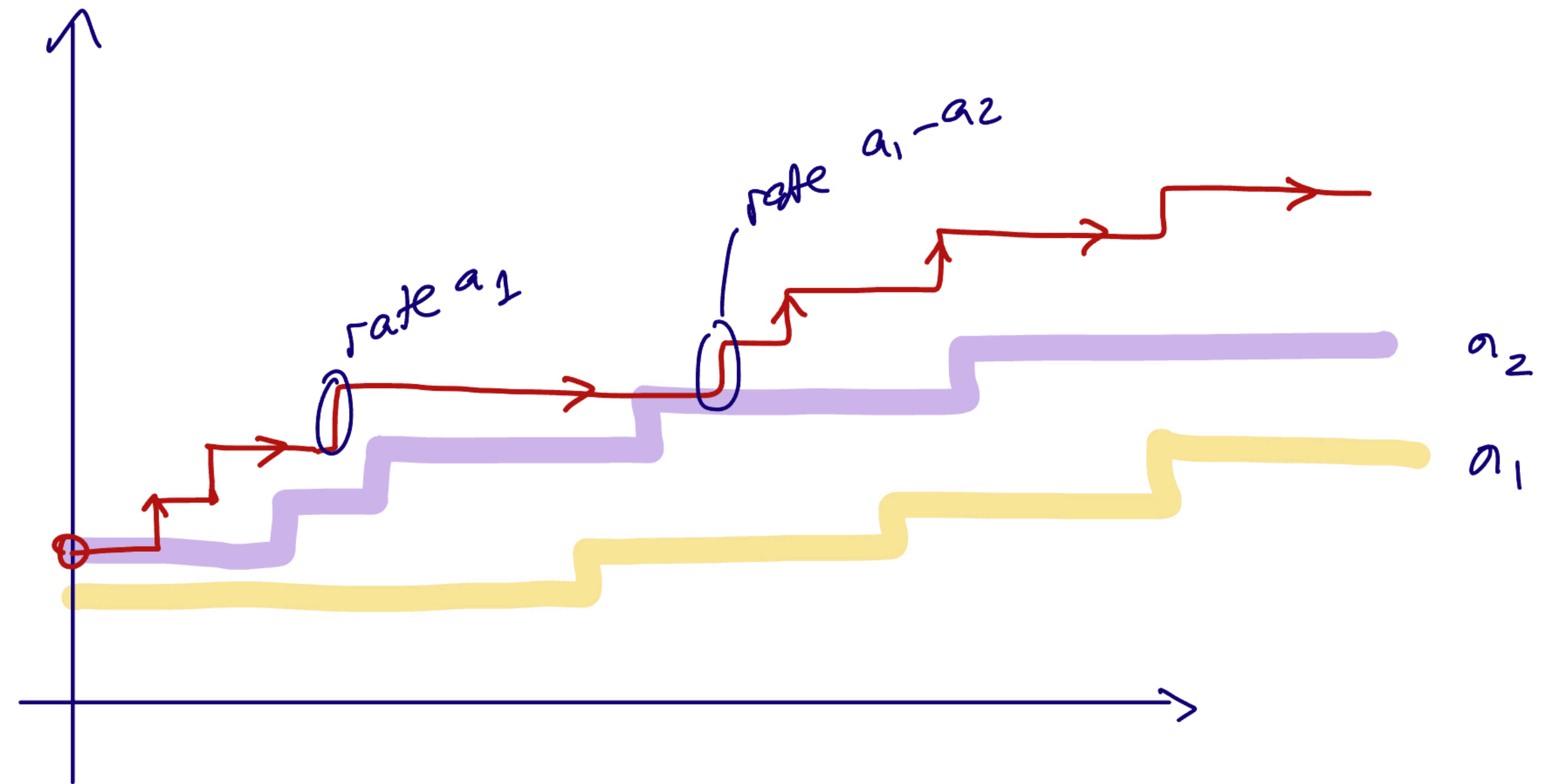
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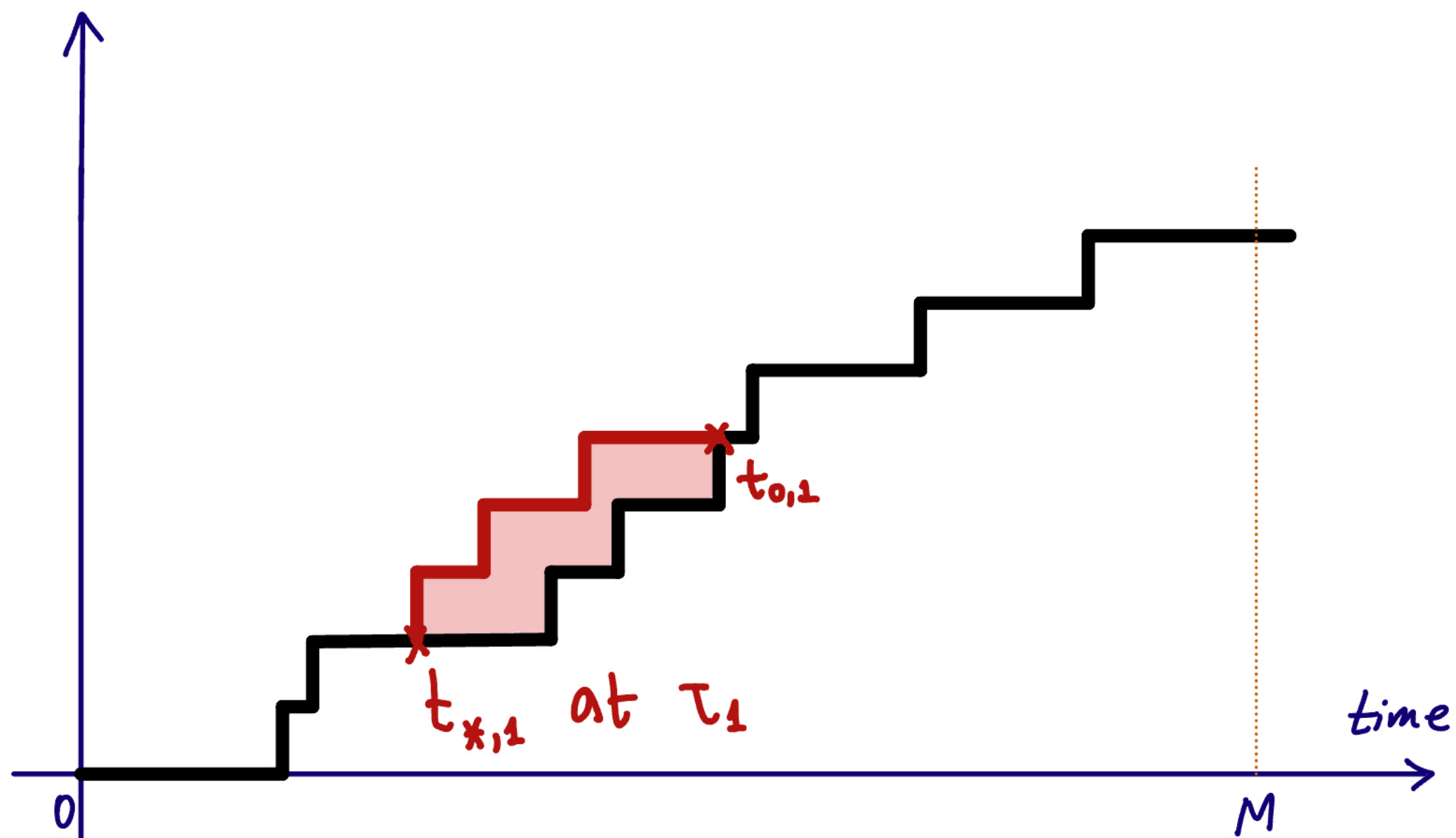
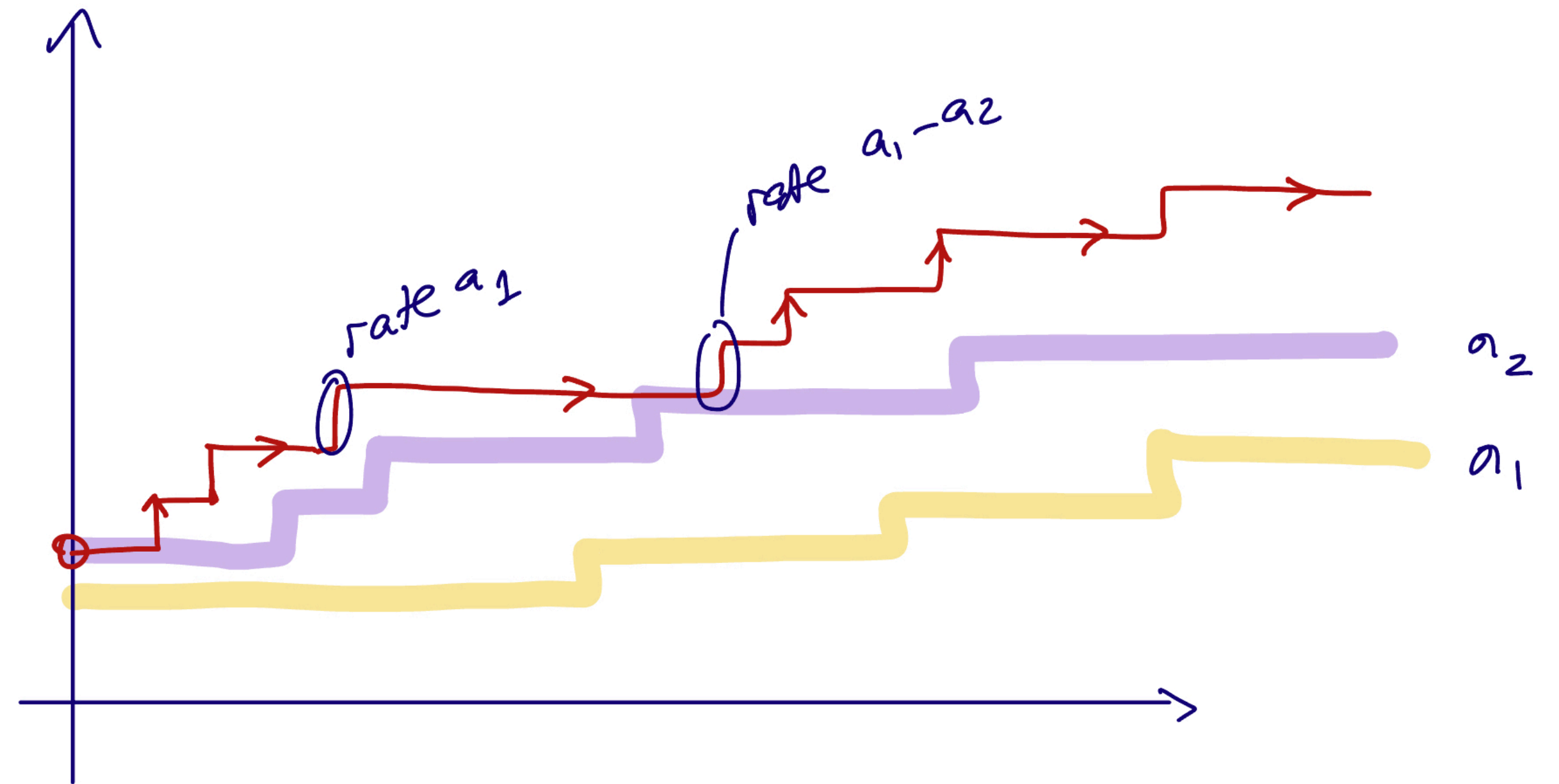
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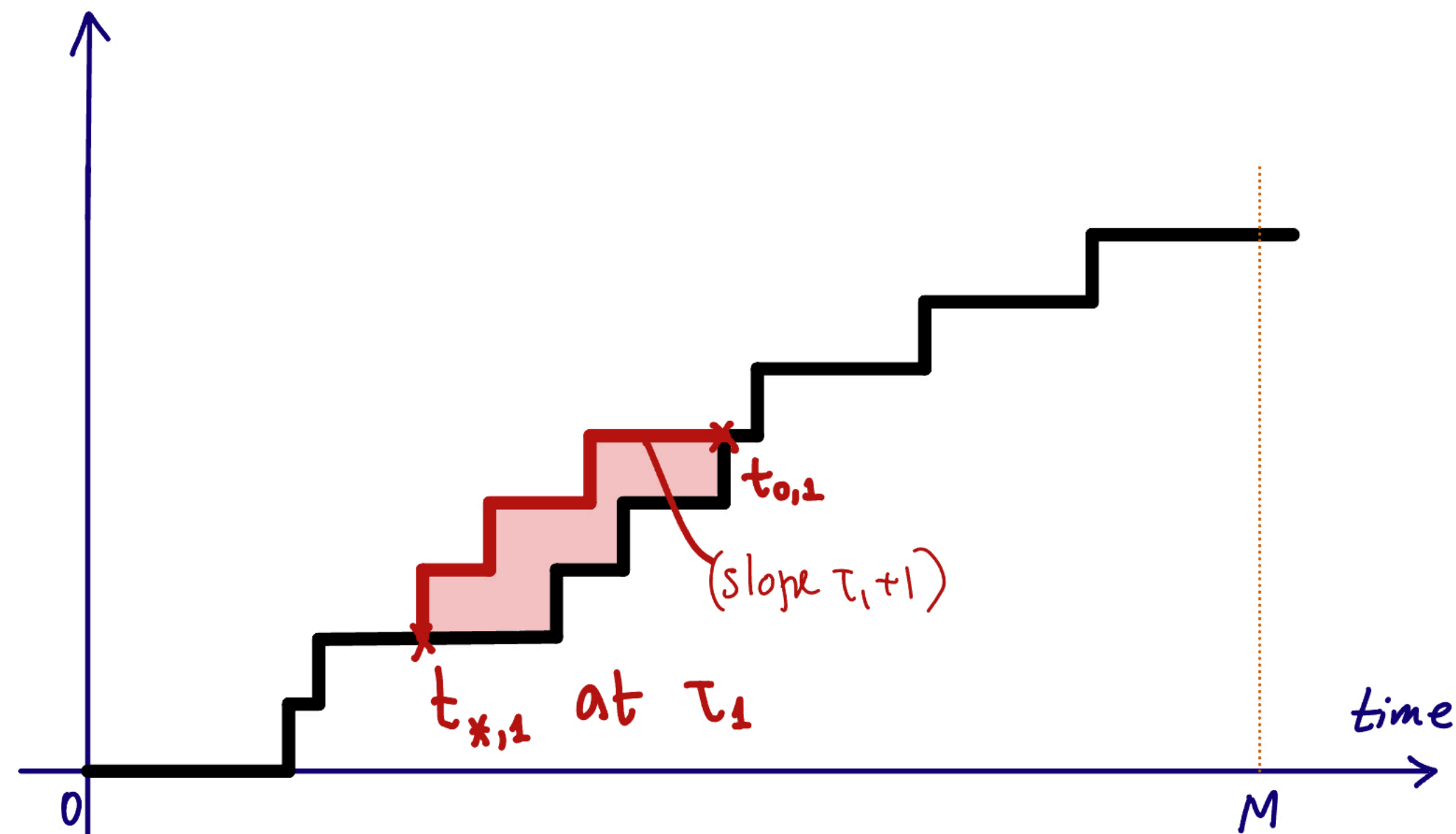
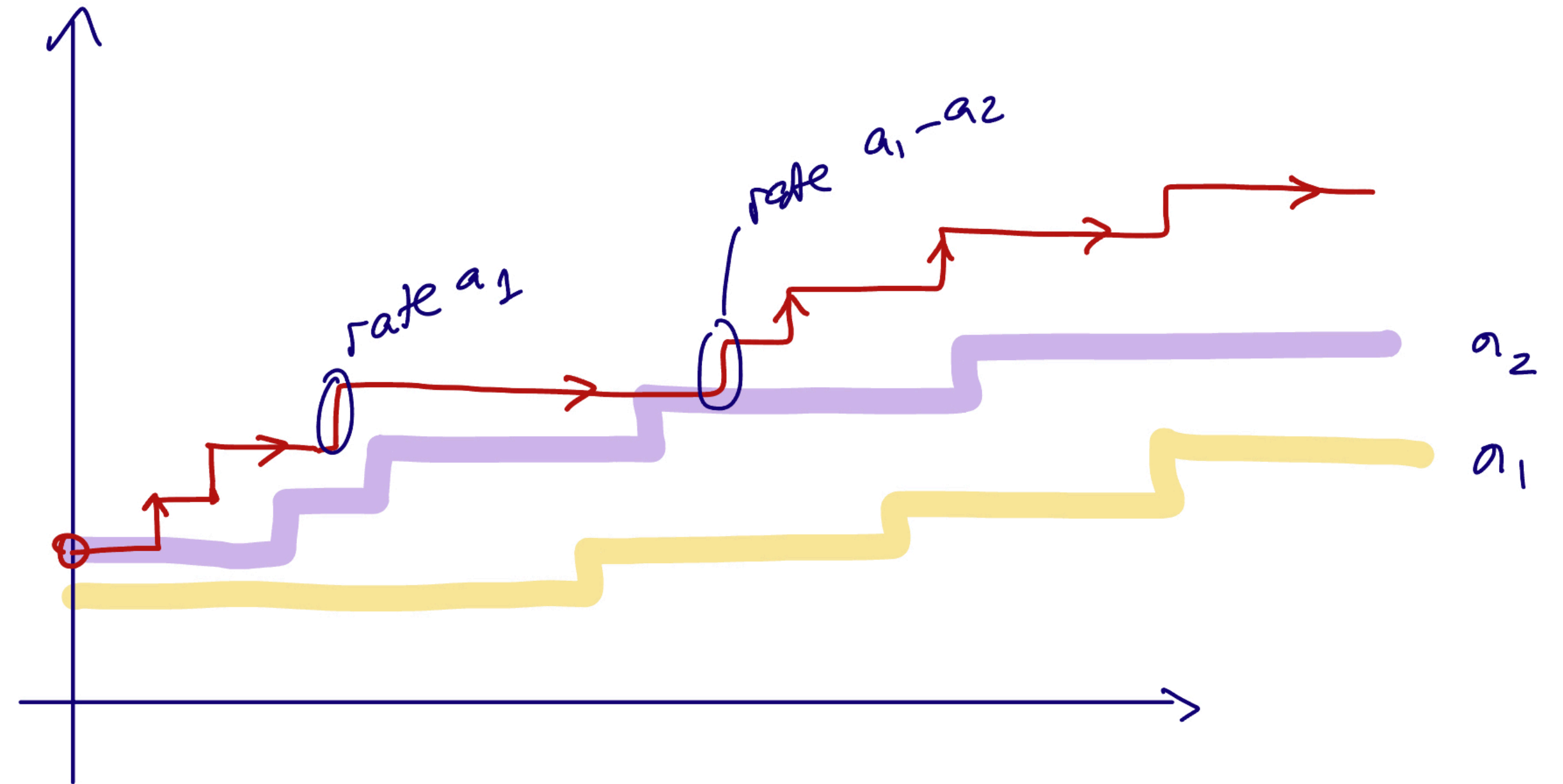
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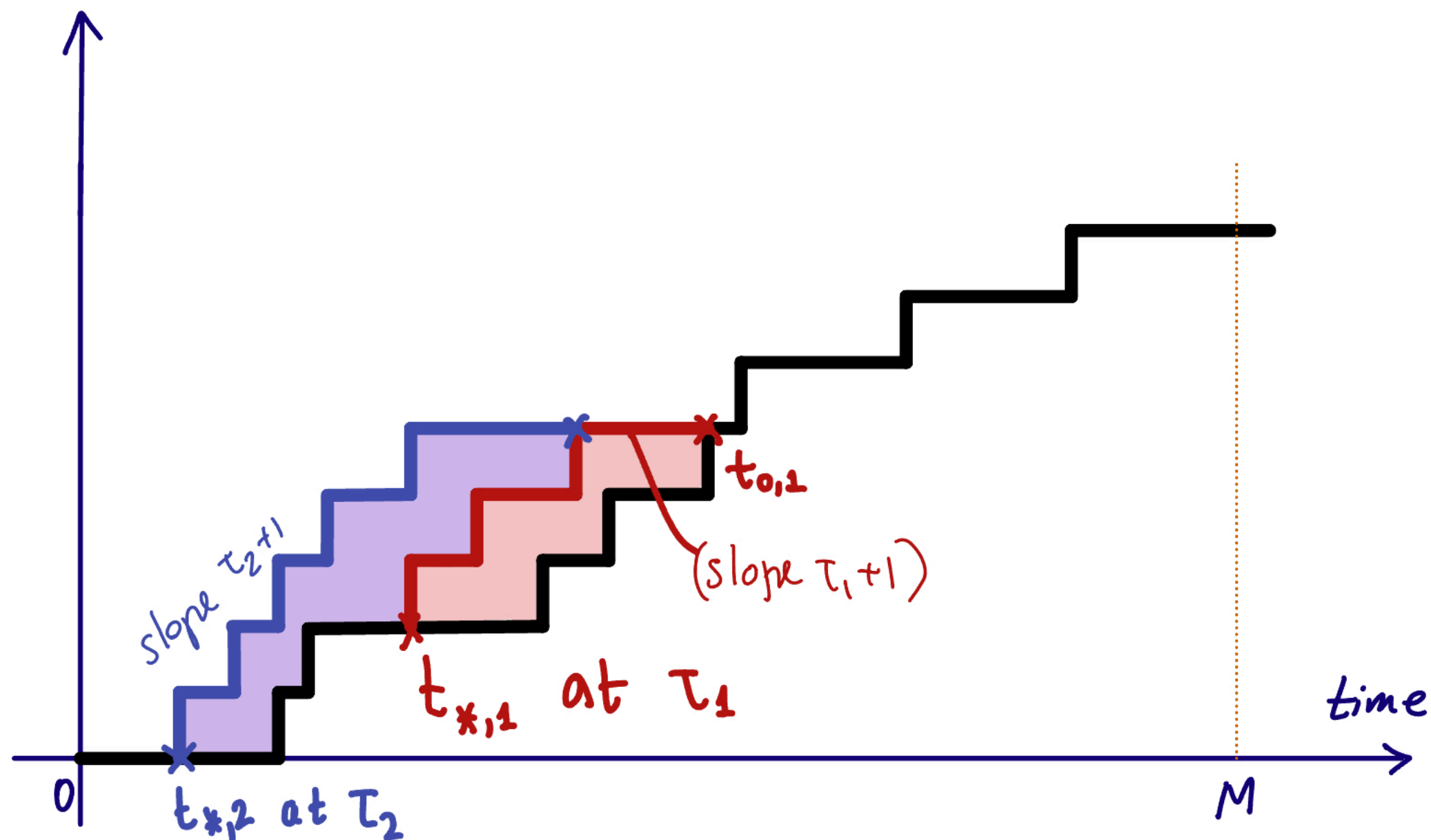
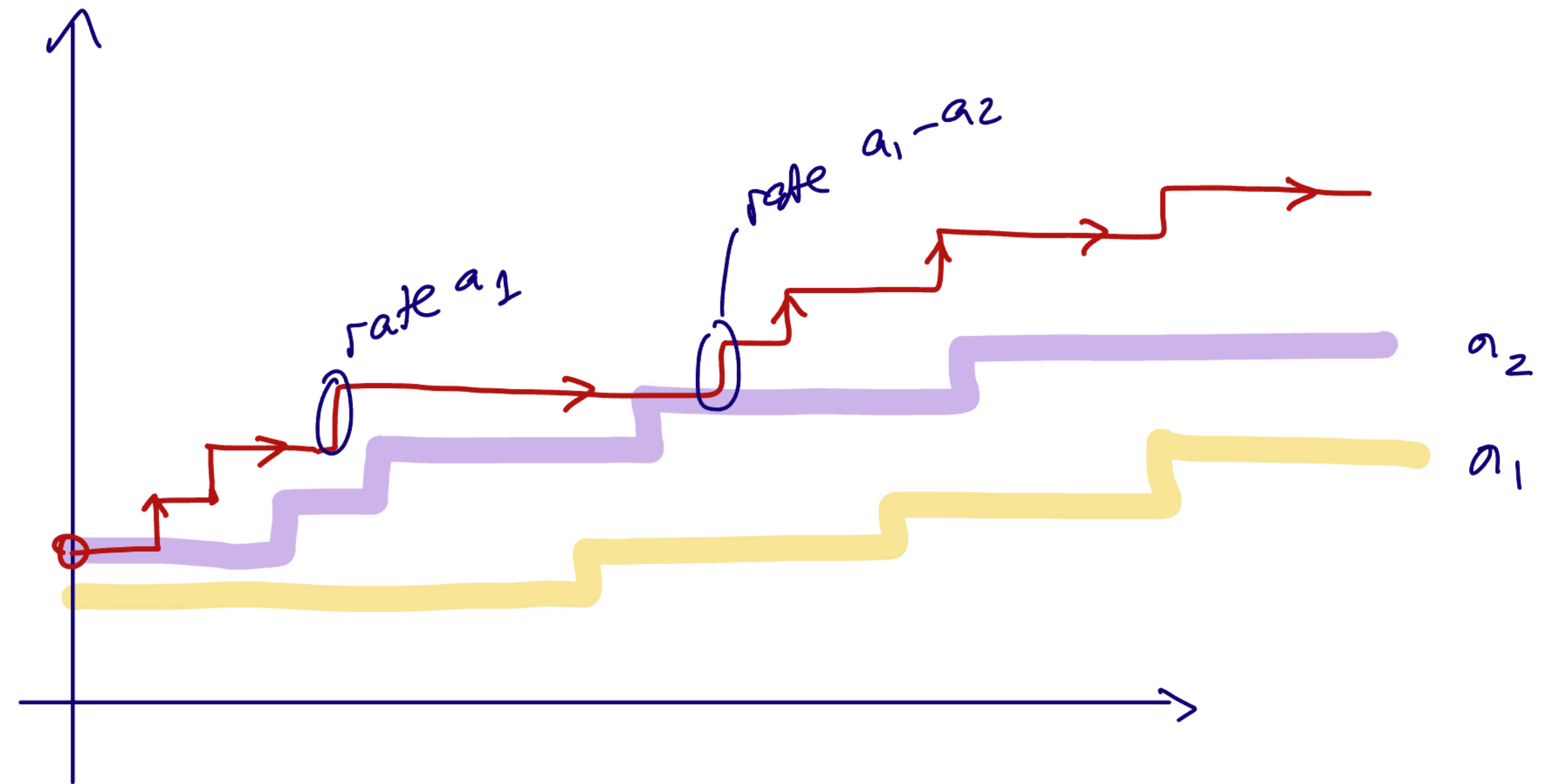
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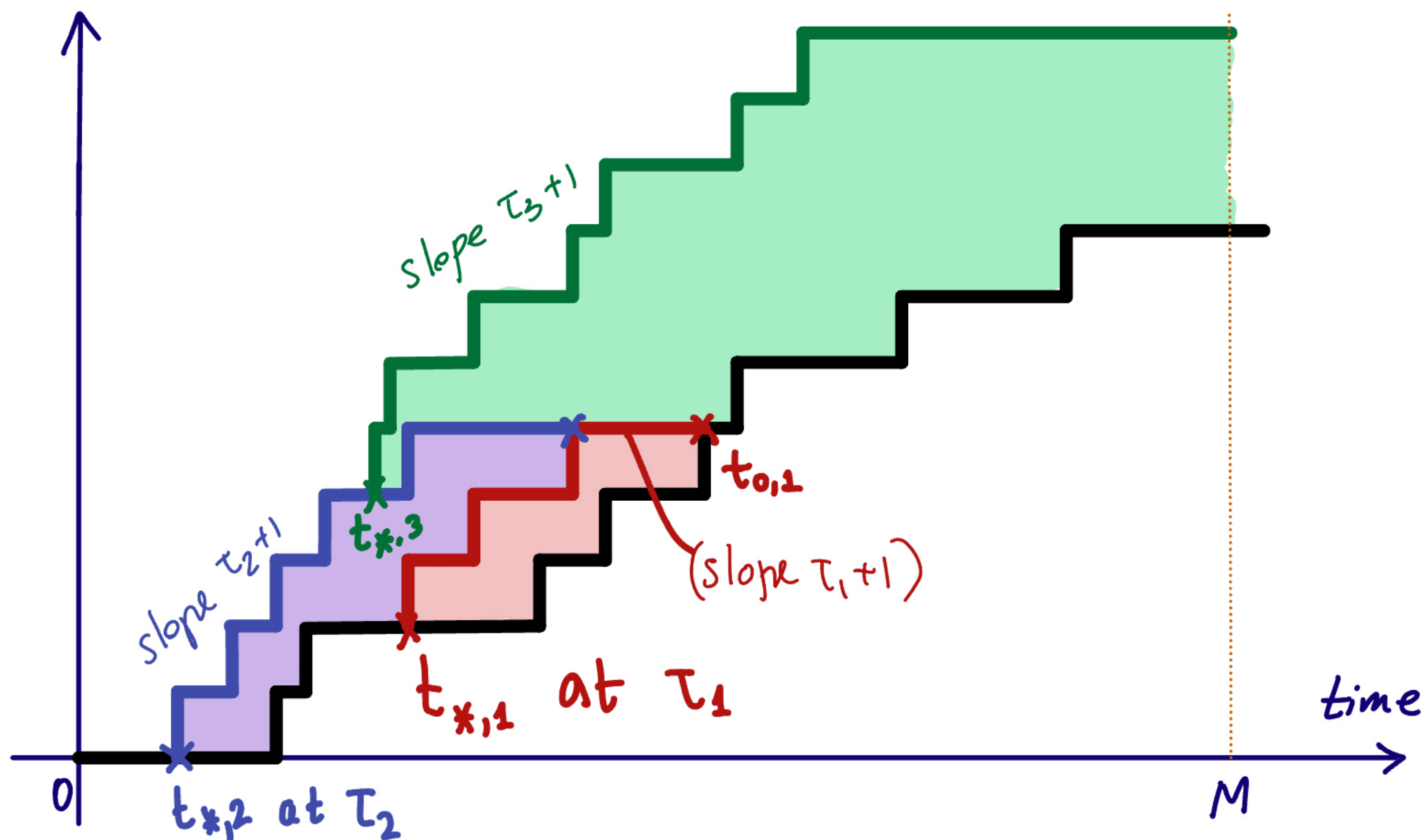
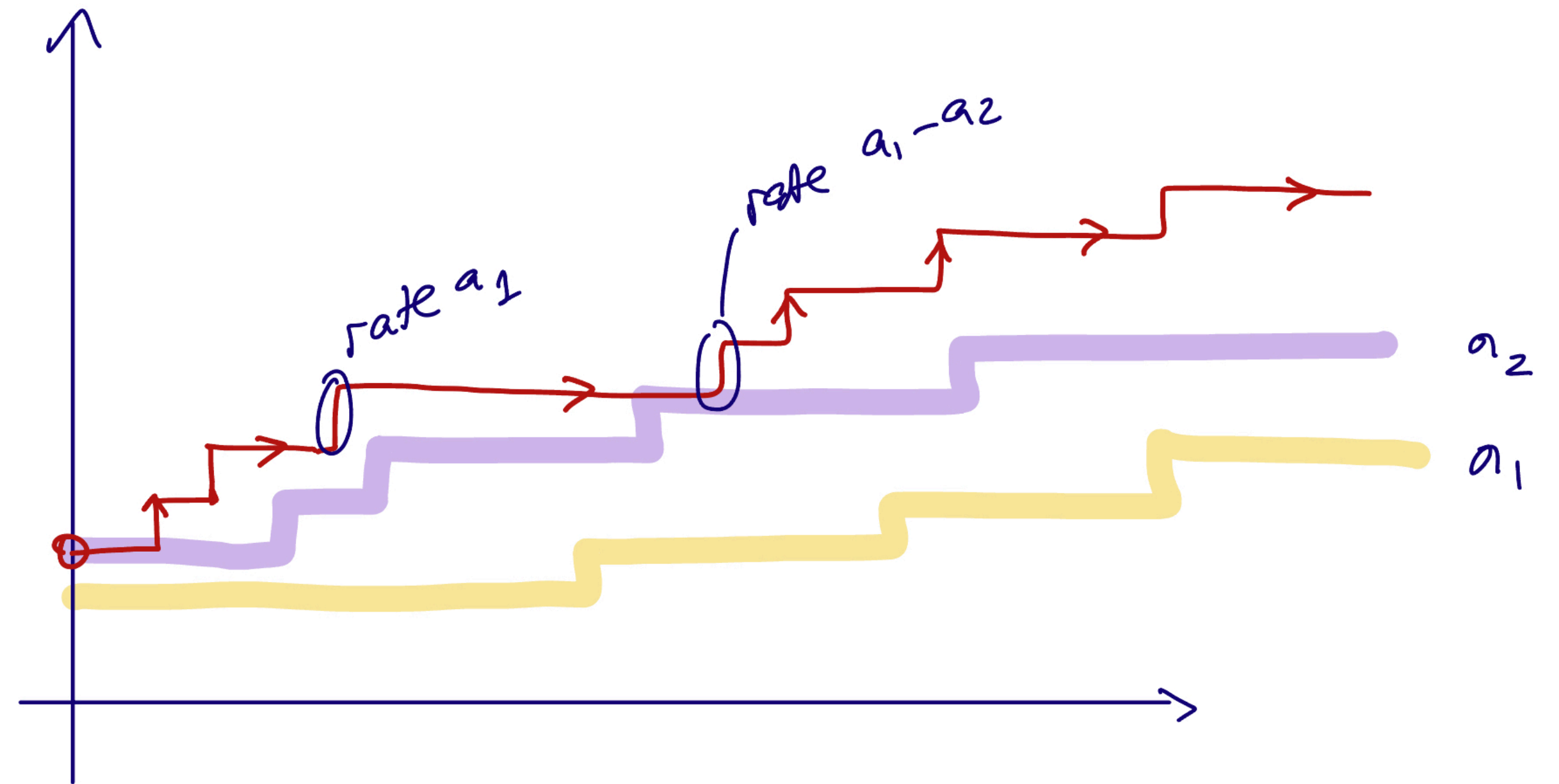
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- We discover Lax equations for q -TASEP and TASEP (their role should be better explored)
- We also construct neat couplings for the whole trajectories, and get a new result about the Poisson process

Thank you for your attention!

For questions and remarks